# Reasoning about QoS Contracts in the Probabilistic Duration Calculus 

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#### Abstract

The notion of contract was introduced to component-based software development in order to facilitate the semantically correct composition of components. We extend the form of this notion which is based on designs to capture probabilistic requirements on execution time. We show how reasoning about such requirements can be done in an infinite-interval-based system of probabilistic duration calculus.


## Introduction

Combining off-the-shelf and dedicated components has become an established approach to achieving reuse, modularity, productivity and reliability. Contracts facilitate the correct use of components. A contract is a collection of requirements which are written in terms of the component interface. Contract requirements should be satisfied by implementations of the component, provided that the items imported from other components also satisfy the requirements appearing in the contract for them. Four levels of contracts have been identified in [BJPW99]. These are the syntactical level, the behavioural level, the synchronization level and the quality of service level. Quality of Service ( QoS ) is a collective term for non-functional requirements such as worst-case and average execution time, and the consumption of resources such as memory, power, bandwidth, etc.

Component models are built around appropriate formalisations of the notions of interface, contract, component composability, composition, etc. A contract theory for components based on the notion of design from [HH98] has been proposed in [HLL06, HXZ06] and has become known as the rCOS model. Since designs capture input-output relations, this model is mostly about the functional requirements on components and leaves out the QoS level from [BJPW99]. In our previous work we extended the rCOS model to capture requirements on timing and resources [Dan05, HD07]. We have considered hard requirements, where, e.g., missing a deadline is regarded as fatal. We used the Duration Calculus $(D C)$ as our notation. QoS is mainly concerned with soft requirements, where, e.g., missing a deadline by little and not too often is tolerable. Handling requirements on the QoS involves reasoning about probability.

In this paper we extend designs to capture probabilistic requirements on execution time and develop a technique to reason about QoS of real-time embedded systems using an infinite-interval-based system of probabilistic $D C(P D C)$ which was proposed in [Gue07] as an extension of a corresponding system of Probabilistic Interval Temporal Logic with infinite intervals (PITL). PDC with infinite intervals subsumes the systems of $P D C$ from [LRSZ93, DZ99, Gue00b] and has a relatively complete proof system to support formal reasoning. The fitness of (non-probabilistic) $D C$ for reasoning about real-time systems has been asserted by numerous case studies [ZZ94, DW96, SX98, Dan98, LH99]. Since $D C$ is interval-based, reasoning about the behaviour of whole method executions, including their execution time, is relatively straightforward in $D C$. By using a probabilistic extension of $D C$ we are able to enjoy this advantage when reasoning about QoS requirements too.

[^0]
## 1 Preliminaries

We consider only the extended set of the real numbers $\overline{\mathbf{R}}=\mathbf{R} \cup\{\infty\}$ as the flow of time in PITL and $P D C$. In order to facilitate the description of repetitive behaviour, we include a least-fixed-point operator for non-probabilistic formulas, which was introduced in [Pan95] and studied in [Gue00a]. ITL with infinite intervals [ZDL95, PWX98, SX98, WX04] is the underlying non-probabilistic logic of PITL and PDC. It extends the syntax of predicate logic by a binary modality (.;.), known as chop. ${ }^{1}$ Non-logical symbols are divided into rigid and flexible depending on whether their meaning is required to be the same at all reference intervals or not. Individual variables are rigid.

An interpretation of a vocabulary $\mathbf{L}$ is a function $I$ on $\mathbf{L}$ which maps the symbols from $\mathbf{L}$ to members of $\overline{\mathbf{R}}$, functions and predicates on $\overline{\mathbf{R}}$, according to the type and arity of symbols. $I(s)$ takes an interval from $\tilde{\mathbf{I}}$ as an additional argument in case $s$ is flexible. We use the sets of intervals

$$
\mathbf{I}^{f i n}=\left\{\left[\tau_{1}, \tau_{2}\right]: \tau_{1}, \tau_{2} \in \mathbf{R}, \tau_{1} \leq \tau_{2}\right\}, \mathbf{I}^{i n f}=\{[\tau, \infty]: \tau \in \mathbf{R}\} \text { and } \tilde{\mathbf{I}}=\mathbf{I}^{f i n} \cup \mathbf{I}^{i n f}
$$

Given $\sigma_{1} \in \mathbf{I}^{f i n}$ and $\sigma_{2} \in \tilde{\mathbf{I}}$ such that $\max \sigma_{1}=\min \sigma_{2}, \sigma_{1} ; \sigma_{2}$ stands for $\sigma_{1} \cup \sigma_{2}$. Given an interpretation $I$, the values $I_{\sigma}(t)$ of terms $t$ at intervals $\sigma \in \tilde{\mathbf{I}}$ are defined in the usual way, with the reference interval being an additional argument for flexible symbols. Satisfaction $\models$ is defined with respect to an interpretation and a reference interval. Flexible relation symbols are interpreted predicates which take the reference interval as an argument too. The clauses for $\perp, \Rightarrow$ and $\exists$ are the usual ones. The clause for (.;.) is

$$
I, \sigma \models(\varphi ; \psi) \text { iff } I, \sigma_{1} \models \varphi \text { and } I, \sigma_{2} \models \psi \text { for some } \sigma_{1} \in \mathbf{I}^{f i n} \text { and } \sigma_{2} \in \tilde{\mathbf{I}} \text { such that } \sigma_{1} ; \sigma_{2}=\sigma \text {. }
$$

$0, \infty,+$ and $=$ are mandatory in $I T L$ vocabularies and always have the usual interpretation. A mandatory flexible constant $\ell$ always evaluates to the length of the reference interval. Infix notation for + and $=$ and $\top, \wedge, \Rightarrow, \Leftrightarrow$ and $\forall$ are used in the usual way. ITL-specific abbreviations include

$$
\left(\varphi_{1} ; \ldots ; \varphi_{n-1} ; \varphi_{n}\right) \rightleftharpoons\left(\varphi_{1} ; \ldots\left(\varphi_{n-1} ; \varphi_{n}\right) \ldots\right), \diamond \varphi \rightleftharpoons(\top ; \varphi ; \top) \vee(\top ; \varphi), \square \varphi \rightleftharpoons \neg \diamond \neg \varphi .
$$

$\diamond$ and $\square$ bind more tightly and (.;.) binds less tightly than the boolean connectives.
A complete proof system for $I T L$ with infinite intervals with respect to an appropriate abstract domain of durations was presented in [WX04].

Vocabularies for $D C$ with infinite intervals additionally include state variables $P, Q, \ldots ;$ state expressions $S$ are boolean combinations of state variables with the logical constants written as $\mathbf{0}$ and $\mathbf{1}$ and in turn appear as the argument of duration terms $\int S$, which are the $D C$-specific construct in the syntax of $D C$ terms. Formulas in $D C$ are as in $I T L$. State variables evaluate to piece-wise constant functions of type $\overline{\mathbf{R}} \rightarrow\{0,1\}$. The value $I_{\tau}(S)$ of state expression $S$ at time $\tau$ is defined using $I(P)(\tau)$ for the involved state variables $P$ in the usual way. Values of duration terms are defined by the equality

$$
I_{\sigma}\left(\int S\right)=\int_{\min \sigma}^{\max \sigma} I_{\tau}(S) d \tau
$$

$I_{\sigma}\left(\int S\right)$ can be $\infty$ for $\sigma \in \mathbf{I}^{\text {inf }}$. The expression $\lceil S\rceil$ abbreviates $\ell \neq 0 \wedge \int \neg S=0$ and $\ell$ can be viewed as an abbreviation for $\int \mathbf{1}$ in $D C$.

Axioms and rules for $D C$ (with infinite intervals) which are complete relative to validity in real-time ITL (with infinite intervals), have been presented in [HZ92] (resp. [Gue07].)

The least-fixed-point operator If $\varphi_{1}, \ldots, \varphi_{n}$ have no negative occurrences of the propositional variables $X_{1}, \ldots, X_{n}$ and $i \in\{1, \ldots, n\}$, then $\mu_{i} X_{1} \ldots X_{n} \cdot \varphi_{1}, \ldots, \varphi_{n}$ is well-formed and $I, \sigma \vDash \mu_{i} X_{1} \ldots X_{n} \cdot \varphi_{1}, \ldots, \varphi_{n}$ iff $\sigma \in A_{i}$, where $A_{1}, \ldots, A_{n}$ are the smallest subsets of $\tilde{I}$ which satisfy the equalities

$$
A_{i}=\left\{\sigma \in \tilde{\mathbf{I}}: I_{X_{1},}^{\lambda \sigma . \sigma \in A_{1}, \ldots, \lambda, \ldots . \sigma \in A_{n}}, \sigma \models \varphi_{i}\right\}, i=1, \ldots, n .
$$

Iteration, also known as Kleene star, can be defined using $\mu$ by the equivalence $\varphi^{*} \rightleftharpoons \mu_{1} X . \ell=0 \vee(\varphi ; X)$. $I, \sigma \models \varphi^{*}$ can be defined independently by the condition:

$$
\min \sigma=\max \sigma \text { or } \sigma=\sigma_{1} ; \ldots ; \sigma_{n} \text { and } I, \sigma_{i} \models \varphi, i=1, \ldots, n, \text { for some } n<\omega, \sigma_{1}, \ldots, \sigma_{n} \in \tilde{\mathbf{I}} .
$$

[^1]Axioms and rules for $\mu$ and * in $D C$ were proposed in [Pan95, Gue00a, GD05].
Higher-order quantifiers We use $\exists$ on flexible constants and state variables with the usual meaning, in order to describe the semantics of local variables. The deductive power of some axioms and rules for this usage has been studied in [ZGZ00, Gue00a, GD05].

Probabilistic ITL and DC with infinite intervals (PITL) extends the syntax of ITL terms by probability terms of the form $p(\varphi)$ where $\varphi$ is a formula. Formula syntax is as in $I T L$, with $\mu$ and higher-order quantifiers included. A PITL model is based on a collection of interpretations of a given vocabulary $\mathbf{L}$. Each interpretation is meant to describe a possible behaviour of the modelled system. Consider a non-empty set $\mathbf{W}$, a function $I$ on $\mathbf{W}$ into the set of the $I T L$ interpretations of $\mathbf{L}$ and a function $P$ of type $\mathbf{W} \times \overline{\mathbf{R}} \times 2^{\mathbf{W}} \rightarrow[0,1]$. Let $I^{w}$ and $P^{w}$ abbreviate $I(w)$ and $\lambda \tau, X . P(w, \tau, X)$, respectively, for all $w \in \mathbf{W} . I^{w}$ and $P^{w}, w \in \mathbf{W}$, are intended to represent the set of behaviours and the associated probability distributions for every $\tau \in \overline{\mathbf{R}}$ in the PITL models for $\mathbf{L}$.

Definition 1 Let $\tau \in \overline{\mathbf{R}}$. Then $w \equiv_{\tau} v$ iff
$I^{w}(s)=I^{v}(s)$ for all rigid symbols $s \in \mathbf{L}$, except possibly the individual variables;
$I^{w}(s)\left(\sigma, d_{1}, \ldots, d_{\# s}\right)=I^{v}(s)\left(\sigma, d_{1}, \ldots, d_{\# s}\right)$ for all flexible $s \in \mathbf{L}$, all $d_{1}, \ldots, d_{\# s} \in \overline{\mathbf{R}}$ and all $\sigma \in \tilde{\mathbf{I}}$ such that $\max \sigma \leq \tau$;
$P^{w}\left(\tau^{\prime}, X\right)=P^{v}\left(\tau^{\prime}, X\right)$ for all $X \subseteq \mathbf{W}$ and all $\tau^{\prime} \leq \tau$.
Clearly $\equiv_{\tau}$ is an equivalence relation on $W$ for all $\tau \in \overline{\mathbf{R}}$. Members of $\mathbf{W}$ which are $\tau$-equivalent model the same behaviour up to time $\tau$. If $\tau_{1}>\tau_{2}$, then $\equiv_{\tau_{1}} \subset \equiv_{\tau_{2}}$ and $w \equiv_{\infty} v$ holds iff $P^{w}=P^{v}$ and $I^{w}$ and $I^{v}$ agree on all symbols, except possibly some individual variables. $[w]_{\equiv_{\tau}}$ is the set of those $v \in \mathbf{W}$ which represent the probabilistic branching of $w$ from time $\tau$ onwards.

Definition 2 A general PITL model for $\mathbf{L}$ is a tuple of the form $\langle\mathbf{W}, I, P\rangle$ where $F, \mathbf{W}, I$ and $P$ are as above and satisfy the following requirements for every $w \in \mathbf{W}$ :

- W is closed under variants of interpretations. If $w \in \mathbf{W}, x$ is an individual variable from $\mathbf{L}$ and $a \in \overline{\mathbf{R}}$, then there is a $v \in \mathbf{W}$ such that $P^{v}=P^{w}$ and $I^{v}=\left(I^{w}\right)_{x}^{a}$, where $\left(I^{w}\right)_{x}^{a}$ maps $x$ to $a$ and is the same as $I^{w}$ on other symbols.
- The functions $P^{w}$ are probability measures. For every $w \in W$ and $\tau \in \overline{\mathbf{R}}$ the function $\lambda X . P^{w}(\tau, X)$ is a probability measure on the boolean algebra $\left\langle 2^{\mathbf{W}}, \cap, \cup, \emptyset, \mathbf{W}\right\rangle$. Furthermore $\lambda X . P^{w}(\tau, X)$ is required to be concentrated on $[w]_{\equiv_{\tau}}: P^{w}(\tau, X)=P^{w}\left(\tau, X \cap[w]_{\equiv_{\tau}}\right)$ for all $X \subseteq \mathbf{W}$.

Informally, the probability for a behaviour in $X \subseteq[w]_{\equiv_{\tau}}$ to be chosen is $P_{\tilde{\mathbf{I}}}{ }^{w}(\tau, X)$. Satisfaction $\models$ is defined in PITL with respect to a model $M=\langle\mathbf{W}, I, P\rangle$, a $w \in \mathbf{W}$, and a $\sigma \in \tilde{\mathbf{I}}$. If $\psi$ is a sentence, then

$$
\llbracket \psi \rrbracket_{M, w, \sigma}=\left\{v \in[w]_{\equiv_{\max \sigma}}: M, v,[\min \sigma, \infty] \models \psi\right\}
$$

This means that $\llbracket \psi \rrbracket_{M, w, \sigma}$ consists of the interpretations $v$ which are max $\sigma$-equivalent to $w$ and satisfy $\psi$ at the infinite interval starting at $\min \sigma$. In case $\psi$ has free variables $x_{1}, \ldots, x_{n}, M, v,[\min \sigma, \infty] \models \psi$ should be evaluated with $I^{w}\left(x_{1}\right), \ldots, I^{w}\left(x_{n}\right)$ as the values of $x_{1}, \ldots, x_{n}$, in order to preserve the intended meaning:

$$
\llbracket \psi \rrbracket_{M, w, \sigma}=\left\{v \in[w]_{\equiv_{\max \sigma}}:\left(\forall v^{\prime} \in W\right)\left(P^{v^{\prime}}=P^{v} \wedge I^{v^{\prime}}=\left(I^{v}\right)_{x_{1}, \ldots, x_{n}\left(x_{1}\right), \ldots, I_{n}^{w}\left(x_{n}\right)}^{I_{n}} \Rightarrow M, v^{\prime},[\min \sigma, \infty] \models \psi\right)\right\}
$$

Using this notation, term values $w_{\sigma}(t)$ of probability terms $t$ can be defined by putting

$$
w_{\sigma}(p(\psi))=P^{w}\left(\max \sigma, \llbracket \psi \rrbracket_{M, w, \sigma}\right)
$$

Values of terms of other forms are defined as in (non-probabilistic) ITL.
The probability functions $\lambda X \cdot P^{w}(\tau, X)$ for $w \in \mathbf{W}$ and $\tau \in T$ in general PITL models $M=\langle\mathbf{W}, I, P\rangle$ are needed just as much as they provide values for probability terms. That is why we accept structures of the form $\langle\mathbf{W}, P, I\rangle$ with their probability functions $\lambda X . P^{w}(\tau, X)$ be defined just on the (generally smaller) algebras $\left\langle\left\{\llbracket \psi \rrbracket_{M, w, \sigma}: \psi \in \mathbf{L}, \sigma \in \tilde{\mathbf{I}}, \max \sigma=\tau\right\}, \cap, \cup, \emptyset,[w]_{\equiv_{\tau}}\right\rangle$ as general PITL models too.

PITL is a conservative extension of ITL. Axioms and a proof rule which extend the proof system for $I T L$ with infinite intervals to a system for PITL were shown in [Gue07] to be complete with respect to a generalisation of the $\mathbf{R}$-based semantics, where $\overline{\mathbf{R}}$ is replaced by an abstract domain and the probability measures are required to be only finitely aditive.

The probability functions $\lambda X . P^{w}(\tau, X)$ need not be related to each other in general models for PITL, whereas applications typically lead to models with an origin of time $\tau_{0}=\min T$ and a distinguished $w_{0} \in \mathbf{W}$ such that $\left[w_{0}\right]_{\equiv_{\tau_{0}}}=\mathbf{W}$ and $\lambda X \cdot P^{w_{0}}\left(\tau_{0}, X\right)$ can be regarded as the global probability function. Then, given an arbitrary $w \in \mathbf{W}$ and $\tau \in \mathbf{R}$, the probability function $\lambda X . P^{w}(\tau, X)$ should represent conditional probability, the condition being $\tau$-equivalence with $w$. Hence we should have

$$
\begin{equation*}
P^{w_{0}}(\tau, A)=\int_{w \in\left[w_{0}\right]_{\equiv \tau}} P^{w}\left(\tau^{\prime}, A\right) d\left(\lambda X \cdot P^{w_{0}}(\tau, X)\right) . \tag{1}
\end{equation*}
$$

The following rules enable approximating (1) with arbitrary precision in PITL proofs:

$$
\begin{equation*}
\frac{\varphi \Rightarrow \neg(\varphi ; \ell \neq 0)}{\ell=0 \wedge p(\varphi \wedge p(\psi)<x ; \top)=0 \Rightarrow p((\varphi ; \top) \wedge \psi) \geq x \cdot p(\varphi ; \top)} \tag{P}
\end{equation*}
$$

$$
\begin{equation*}
\frac{\varphi \Rightarrow \neg(\varphi ; \ell \neq 0)}{\ell=0 \wedge p(\varphi \wedge p(\psi)>x ; \top)=0 \Rightarrow p((\varphi ; \top) \wedge \psi) \leq x \cdot p(\varphi ; \top)} \tag{P}
\end{equation*}
$$

The proof system for PITL from [Gue07] is minimal. Using the abbreviations

$$
\varphi_{l}^{h} \rightleftharpoons \varphi \wedge \ell \geq l \wedge \ell \leq h \text { and }\left[E T_{\varphi} \in[l, h]\right]_{x} \rightleftharpoons \ell=0 \wedge p(\varphi ; \top)=1 \Rightarrow p\left(\varphi_{l}^{h} ; \top\right)=x
$$

we can write the derived rule
$(S e q) \quad \frac{\alpha \Rightarrow \neg(\alpha ; \ell \neq 0), \beta \Rightarrow \neg(\beta ; \ell \neq 0),\left[E T_{\alpha} \in\left[l_{1}, h_{1}\right]\right]_{x_{1}},\left[E T_{\beta} \in\left[l_{2}, h_{2}\right]\right]_{x_{2}}}{\ell=0 \wedge p(\alpha ; \beta ; \top)=1 \Rightarrow p\left(\alpha_{l_{1}}^{h_{1}} ; \beta_{l_{2}}^{h_{2}} ; \top\right)=x_{1} x_{2}}$,
which is particularly important to our examples.
The system of probabilistic $D C$ ( $P D C$ ) with infinite intervals which we use in this paper is obtained by adding state variables and duration terms to PITL in the way used to obtain (non-probabilistic) $D C$ from $I T L$. The axioms and rules for $D C$ with infinite intervals are complete for $P D C$ relative to validity in PITL models based on $\overline{\mathbf{R}}$.

## 2 A toy concurrent programming language and its semantics in $D C$ with infinite intervals

We propose a toy language to illustrate our approach. It is shaped after that from [GD02] and has restricted form of method call, in order to set the stage for the use of components and contracts.

Programs consist of components, which import and/or export methods. Their syntax is:

```
component ::= component name method ::= name(parameter list)[ code];
    {import method}*
    {export method}*
end name
```

The part code is required only for exported methods. It has the syntax

```
code \(::=\) stop \(\mid\)
        return \([e] \mid\)
        X
        ( \(x:=e\); code) \(\mid\)
        (delay \(r\); code) |
        (call \([x:=]\) name(parameter list); code) \(\mid\)
        if \(b\) then code else code
        letrec code where \(X\) : code \(; \ldots ; X\) : code |
        var \(x\); code
        code \(\|\) code
```

(thread) termination statement return control and possibly a value continuation assignment delay by the specified amount of time call method and possibly obtain a value conditional statement mutual recursion statement local variable declaration parallel composition

We do not allow var to occur in the scope of other control statements．Assignments are atomic．Parameters are passed by value．A mutual recursion statement can trigger an infinite computation．Components are passive．The active part of a program is just a piece of code，typically a collection of concurrently running interleaved threads．The syntax of control statements deliberately makes tail－recursion the only expressible form of repetitive behaviour．We give no details on the type system and tacitly assume an appropriately many－sorted system of $D C$ ．

The execution of code can be described in terms of the values of its signals，variables and parameters as functions of time．The semantic function 【．】defined below maps every piece of code to a $D C$ formula which defines the set of its observable behaviours．We model each program variable $v$ by a corresponding pair of flexible constants $v$ and $v^{\prime}$ ，which denote the value of $v$ at the beginning and at the end of the reference interval and therefore satisfy the axiom $\forall x \neg\left(v^{\prime}=x ; v \neq x\right)$ where $x$ is a rigid individual variable．We model methods $m$ which return a value by a corresponding flexible function symbol．A formula of the form $v^{\prime}=m\left(e_{1}, \ldots, e_{n}\right)$ means that the reference interval describes a complete invocation of $m$ with $e_{1}, \ldots, e_{n}$ as the input parameters and $v^{\prime}$ as the value．We use a flexible predicate symbol for methods which return no value．We use dedicated state variables $R$ and $W$ to indicate that the thread is currently running，or has terminated，respectively．Building on the work from［PD98，GD02］，we use a state variable $N$ to mark computation time，which，unlike the time consumed by the execution of delay statements，waiting for the reaction of the environment，etc．，is regarded as Negligible，in order to simplify calculations．$R, W$ and $N$ satisfy the axioms

$$
\mathrm{T}(R, W) \rightleftharpoons\lceil R \Rightarrow N\rceil \wedge\lceil R \Rightarrow \neg W\rceil \wedge \square \neg(\lceil W\rceil ;\lceil\neg W\rceil),
$$

which express that computation time is negligible，a process can never be both running and terminated，and， once terminated，is never re－activated．A dedicated pair of state variables $R$ and $W$ describes the status of each thread．$N$ marks negligible time for all threads．The formulas

$$
\mathrm{K}(V) \rightleftharpoons \bigwedge_{x \in V} x^{\prime}=x \text { and } \mathrm{K}^{R}(V) \rightleftharpoons \mathrm{K}(V) \wedge\lceil R\rceil
$$

mean that the variables from $V$ preserve their values． $\mathrm{K}^{R}(V)$ additionally means that the thread is active throughout the reference interval．The clauses below define $\llbracket \cdot \|_{V}$ ，where $V$ is the set of program variables which are in the scope in the given code．

$$
\begin{array}{lll}
\llbracket \text { stop } \rrbracket_{V} & & \rightleftharpoons W\rceil \\
\llbracket \text { return } e \rrbracket_{V} & & \rightleftharpoons \\
\llbracket \text { return } \rrbracket_{V} & & \left.\rightleftharpoons \neg R\rceil ; \mathrm{K}^{R}(V) \wedge \mathbf{r}^{\prime}=e\right) \\
\llbracket X \rrbracket_{V} & \rightleftharpoons \neg R\rceil \\
\llbracket\left(C_{1} ; C_{2}\right) \rrbracket_{V} & \rightleftharpoons X \\
\llbracket x:=e \rrbracket_{V} & \rightleftharpoons\left(\llbracket C_{1} \rrbracket_{V} ; \llbracket C_{2} \rrbracket_{V}\right) \\
\llbracket \text { delay } r \rrbracket_{V} & \rightleftharpoons\left(\lceil\neg R\rceil ; \mathrm{K}^{R}(V \backslash\{x\}) \wedge x^{\prime}=e\right) \\
\llbracket \text { if } b \text { then } C_{1} \text { else } C_{2} \rrbracket_{V} & \rightleftharpoons\lceil\neg\rceil \wedge r=\int \neg N \\
\llbracket \text { call } v:=m\left(e_{1}, \ldots, e_{n}\right) \rrbracket_{V} & \rightleftharpoons\left(\lceil\neg\rceil ;\left(b \wedge \mathrm{~K}^{R}(V) ; \llbracket C_{1} \rrbracket_{V}\right) \vee\left(\neg b \wedge \mathrm{~K}^{R}(V) ; \llbracket C_{2} \rrbracket_{V}\right)\right) \\
\llbracket \text { call } m\left(e_{1}, \ldots, e_{n}\right) \rrbracket_{V} & \rightleftharpoons\left(\lceil\neg R\rceil ; \mathrm{K}(V \backslash\{v\}) \wedge v^{\prime}=m\left(e_{1}, \ldots, e_{n}\right)\right) \\
\llbracket \text { letrec } C \text { where } X_{1}: C_{1} ; \ldots X_{n}: C_{n} \rrbracket \rrbracket_{V} \rightleftharpoons \mu_{n+1} X_{1} \ldots X_{n} Y . \llbracket C_{1} \rrbracket_{V}, \ldots, \llbracket C_{n} \rrbracket_{V}, \llbracket C \rrbracket_{V} \\
\llbracket \text { var } v ; C \rrbracket_{V} \rightleftharpoons \exists v \exists v^{\prime}\left(\square\left(\left(\lceil\neg R\rceil \Rightarrow v^{\prime}=v\right) \wedge \forall x \neg\left(v^{\prime}=x ; v \neq x\right)\right) \wedge \wedge \llbracket C \rrbracket_{V \cup\{v\}}\right. \\
& & \\
& & \\
\llbracket\left(C_{1} \| C_{2}\right)_{V} \rrbracket \rightleftharpoons \exists R_{1} \exists R_{2} \exists W_{1} \exists W_{2}\left(\begin{array}{l}
\left\lceil W \Leftrightarrow W_{1} \wedge W_{2}\right\rceil \wedge\left\lceil R \Leftrightarrow R_{1} \vee R_{2}\right\rceil \wedge\left\lceil\neg R_{1} \wedge R_{2}\right\rceil \wedge \\
\mathrm{T}\left(R_{1}, W_{1}\right) \wedge\left[R_{1} / R, W_{1} / W\right] \llbracket C_{1} \rrbracket_{V} \wedge \\
\mathrm{~T}\left(R_{2}, W_{2}\right) \wedge\left[R_{2} / R, W_{2} / W\right] \llbracket C_{2} \rrbracket_{V}
\end{array}\right.
\end{array}
$$

$\llbracket \operatorname{export} m\left(p_{1}, \ldots, p_{n}\right) \operatorname{code\rrbracket } \rightleftharpoons \square \forall p_{1} \ldots \forall p_{n} \forall \mathbf{r}^{\prime}\left(\mathbf{r}^{\prime}=m\left(p_{1}, \ldots, p_{n}\right) \Leftrightarrow \llbracket \operatorname{code} \rrbracket_{\emptyset}\right)$ ，if $m$ returns a value $\llbracket$ export $m\left(p_{1}, \ldots, p_{n}\right)$ code $\rightleftharpoons \downarrow \forall p_{1} \ldots \forall p_{n}\left(m\left(p_{1}, \ldots, p_{n}\right) \Leftrightarrow \llbracket \operatorname{code} \rrbracket_{\emptyset}\right)$ ，if $m$ returns no value

The semantics of a component is the conjunction of the formulas $\llbracket \operatorname{export} m\left(p_{1}, \ldots, p_{n}\right)$ code】 for its exported methods．Declarations of imported methods carry only typing information．

## 3 Reasoning about timed programs in $P D C$ : pattern and examples

Let $C$ be a piece of code. Then the formula $\llbracket C \rrbracket_{V}$ contains the flexible function and relation symbols for the methods with calls in $C$. Let $m$ be such a method; let $m$ return no value for the sake of simplicity. Let $B$ be the body of $m$. By replacement of equivalents we can derive

$$
\llbracket \operatorname{export} m\left(p_{1}, \ldots, p_{n}\right) B \rrbracket \wedge \llbracket C \rrbracket_{V} \Rightarrow\left[\llbracket B \rrbracket_{\emptyset} / m\right] \llbracket C \rrbracket_{V},
$$

where the substitution $\left[\llbracket B \rrbracket_{\emptyset} / m\right]$ distributes over the boolean connectives, chop and quantifiers and $\left.\llbracket B \rrbracket_{\emptyset} / m\right] m\left(e_{1}, \ldots, e_{n}\right)$ is defined as $\left[e_{1} / p_{1}, \ldots, e_{n} / p_{n}\right] \llbracket B \rrbracket_{\emptyset}$. Assume that the satisfaction of a requirement $R e q_{C}$ written in $D C$ by $C$ is expressed as the equivalence

$$
\llbracket C \rrbracket_{V} \Rightarrow R e q_{C}
$$

and, according to a contract, $m$ is supposed to satisfy a requirement $R e q_{m}$, that is,

$$
\llbracket B \rrbracket_{\emptyset} \Rightarrow R e q_{m}
$$

is valid for every acceptable $B$. Then the formula

$$
\left[R e q_{m} / m\right] \llbracket C \rrbracket_{V} \Rightarrow R e q_{C}
$$

states that $C$ would satisfy $R e q_{C}$, provided that the imported implementation of $m$ satisfies $R e q_{M}$.
This setting enables reasoning about the probability distribution of the execution time of code that calls imported methods too. Let $C$ and $m$ be as above. Then the probability for $C$ to terminate within $d$ time units can be expressed as the $P D C$ term

$$
p\left(\llbracket C \rrbracket_{V} \wedge \int \neg N \leq d ; \top\right)
$$

where we use $\int \neg N$ to measure only non-negligible execution time spent on the execution of delay or by other processes. Now let $F_{m}$ be a rigid function symbol such that $F_{m}(x)$ denotes a lower bound for the probability for $m$ to terminate within time $x$. Let $P_{m}$ be the precondition for the successful execution of $m$. Let $\bar{p}$ abbreviate $p_{1}, \ldots, p_{n}$. Then

$$
\forall x\left(\ell=0 \Rightarrow p\left(P_{m}(\bar{p}) \wedge m(\bar{p}) \wedge \int \neg N>x ; \top\right)<1-F_{m}(x)\right) \vdash_{P I T L} p\left(\llbracket C \rrbracket_{V} \wedge \int \neg N \leq d ; \top\right) \geq c
$$

means that the probability for $C$ to terminate within $d$ time units is at least $c$. The correspondence between the assumption on the execution time of $m$ and the derived estimate of the execution time of $C$ can be expressed even more accurately, if we make $d$ and $F_{m}$ parameters in an appropriate expression $F_{C}$ in place of $c$ :

$$
\forall x\left(\ell=0 \Rightarrow p\left(P_{m}(\bar{p}) \wedge m(\bar{p}) \wedge \int \neg N>x ; \top\right)<1-F_{m}(x)\right) \vdash_{P I T L} p\left(\llbracket C \rrbracket_{V} \wedge \int \neg N>d ; \top\right)<1-F_{C}\left(d, F_{m}\right) .
$$

In general $F_{C}$ represents a mapping from distributions to distributions, but if the form of $F_{m}$ is known up to numerical parameters such as mean and variance, then $F_{C}$ can be defined as a mapping from their numerical domains instead of the space of distributions.

Example 1 Consider downloading e-mail, which consists of establishing a connection with a server, followed by the actual download. Let the code $C$ for this call two imported methods, $\operatorname{connect}()$ and $\operatorname{getMail}()$ :

```
var ok; call ok:= connect(); if ok then (call getMail(); stop) else stop
```

Let $F_{\text {connect }}(t)$ be the probability for connecting within time $t$. Let the amount of the e-mail be probabilistically distributed too and the probability for downloading it in time $t$ be $F_{\text {getMail }}(t)$. Then lower bounds $F_{C}$ for the distribution of the execution time of $C$ satisfy the formula:
$\ell=0 \Rightarrow p\left(\llbracket \mathbf{c a l l}\right.$ ok $\left.:=\operatorname{connect}() \rrbracket \wedge \int \neg N>t ; \top\right)<1-F_{\text {connect }}(t)$,
$\ell=0 \Rightarrow p\left(o k \wedge \llbracket\right.$ call $\left.\quad \operatorname{getMail}() \rrbracket \wedge \int \neg N>t ; \top\right)<1-F_{\text {getMail }}(t) \vdash_{P I T L} p\left(\llbracket C \rrbracket \wedge \int \neg N>t ; \top\right)<1-F_{C}(t)$
Since the time for connecting and the quantity of e-mail to download can be assumed independent,

$$
\begin{equation*}
F_{C}(t)=\int_{0}^{y} F_{\text {connect }}(y-t) d F_{\text {getMail }}(t) \tag{2}
\end{equation*}
$$

$F_{C}$ can be derived in PITL only approximately, because PITL does not capture taking the limits involved in the definition of the integral in (2). This corresponds to the established use of numerical approximations for distributions. Except for some thoroughly studied distributions, cummulative probability functions seldom have a closed form. Using contracts makes it natural to work with lower bounds and not exact probabilities. The latter may as well not exist. This makes approximations satisfactory. To derive such approximations for (2) in PITL, we find a sequence $A_{k}, k=0,1, \ldots$, of terms involving $F_{\text {connect }}, F_{\text {getMail }}$ and $t$ such that

$$
p\left(\llbracket C \rrbracket \wedge \int \neg N>t ; \top\right)<1-A_{k}
$$

for all $k$ can be derived in PITL and, by the definition of $\int, \lim _{k} A_{k}=F_{C}(t)$. Taking this limit briefly takes us outside PITL. The part of the derivation within PITL is a formalisation of a standard calculation. Let

$$
\begin{equation*}
\varphi_{t_{1}}^{t_{2}} \rightleftharpoons \varphi \wedge \int \neg N>t_{1} \wedge \int \neg N \leq t_{2} \tag{3}
\end{equation*}
$$

Every method call can terminate at most once. This implies the validity of the formulas connect $\Rightarrow \neg($ connect $; \ell \neq 0)$ and getMail $\Rightarrow \neg(\operatorname{getMail} ; \ell \neq 0)$ and enables an application of Seq to derive
$\ell=0 \wedge p($ connect $;$ getMail; $\top)=1 \Rightarrow$

for all $l, m \in\{0, \ldots, k-1\}$. Now by a repeated application of the PITL axiom $P_{+}$, and using that $F_{\text {connect }}(0)=0$, we obtain

$$
\begin{aligned}
& p\left((\text { connect } ; \text { getMail }) \wedge \int \neg N \leq t ; \top\right) \leq \sum_{l+m \leq k-1} p\left(\text { connect } \frac{\frac{(l+1) t}{\frac{l t}{k}}}{\frac{l}{k}} ; \text { getMail } \frac{\frac{(m+1) t}{\frac{m t}{k}}}{\frac{(1)}{k}} ; \top\right)+ \\
& \sum_{l+m=k} p\left(\text { connect } \frac{(l+1) t}{\frac{l t}{k}} ; \text { getMail } \frac{\frac{(m+1) t}{k}{ }_{\frac{k}{k}}^{k}}{k} ; \top\right) \\
& =\underbrace{\sum_{m \leq k-1} F_{\text {connect }}\left(\frac{(k-m+1) t}{k}\right)\left(F_{\text {getMail }}\left(\frac{(m+1) t}{k}\right)-F_{\text {getMail }}\left(\frac{m t}{k}\right)\right)}_{S_{k}}+B_{k}
\end{aligned}
$$

where $B_{k} \leq \max _{l \leq k-1} F_{\text {connect }}\left(\frac{(l+1) t}{k}\right)-F_{\text {connect }}\left(\frac{l t}{k}\right)$, and therefore $\lim _{k} B_{k}=0$. By the definition of Stieltjes integral, we have $\lim _{k} S_{k}=F_{C}(t)$. Hence we can take $A_{k}$ to be the expression on the right of $\leq$ above.

Note that Seq was formulated with $\varphi_{t_{1}}^{t_{2}}$ standing for $\varphi \wedge l \geq t_{1} \wedge \ell \leq t_{2}$, but it applies to (3) as well.
Example 2 Consider attempting to download 5 files in quick succession. With a server which allows at most 4 files to be downloading simultaneously, the 5 th request can be cancelled by the browser due to a timeout. We are interested in the probability of cancellation. Here follows an extremely simplified variant of the relevant browser code:

```
letrec }X\mathrm{ where 1
    X: if userRequest then 2
    (userRequest := false; }
    X|(\begin{array}{c}{\mathrm{ call handle := requestDownload(url, timeout);}}\\{\mathrm{ if handle! = null }}\\{\mathrm{ then (call download(handle); stop)}}\\{\mathrm{ else (call signalTimeout(url); stop)}}\end{array})}\begin{array}{c}{4}\\{5}\end{array}
    else X 9
```

A separate process is assumed to indicate the arrival of a new download request by setting the shared variable userRequest and placing the URL in the shared variable url. Let

$$
\alpha(R, T) \rightleftharpoons\binom{\left(\lceil\neg R\rceil ; \mathrm{K}^{R}(V) \wedge \neg \text { userRequest }\right)^{*} ;\lceil\neg R\rceil ; \mathrm{K}^{R}(V) \wedge \text { userRequest } ;}{\lceil\neg R\rceil ; \mathrm{K}^{R}(V \backslash\{\text { userRequest }\}) \wedge \text { userRequest }} \wedge \text { false } .
$$

and

$$
\beta(R, W, T) \rightleftharpoons\binom{\lceil\neg R\rceil ; \mathrm{K}^{R}(V \backslash\{\text { handle }\}) \wedge \text { handle } e^{\prime}=\text { requestDownload }(\text { url }, \text { timeout }) ;}{\lceil\neg R\rceil ; \mathrm{K}^{R}(V) \wedge \text { handle }!=\text { null } ;\lceil R\rceil ; \mathrm{K}^{R}(V) \wedge \text { download }(\text { handle }) \wedge \int \neg N=T ;\lceil W\rceil}
$$

According to the semantics of (4), $\alpha(R, T)$ describes the repeated execution of lines 2-3 and 9 until userRequest becomes true with $T$ denoting the overall execution time, and $\beta(R, W, T)$ corresponds to the execution of lines 4-6, with $R$ and $W$ describing the status of the thread created in order to complete the requested download, and $T$ denoting the download time. The scenario of launching the five downloads involves six threads: one for each download and one to keep the system ready for further requests. Let $R_{1}, \ldots, R_{6}, W_{1}, \ldots, W_{6}$ describe the status of the six threads. Then the scenario can be described by the formula

$$
\begin{equation*}
\exists R_{1} \ldots \exists R_{6} \exists W_{1} \ldots \exists W_{6}\left(\left\lceil W \Leftrightarrow \bigwedge_{i=1}^{6} W_{i}\right\rceil \wedge\left\lceil R \Leftrightarrow \bigvee_{i=1}^{6} R_{i}\right\rceil \wedge\left\lceil\bigwedge_{1 \leq i<j \leq 6} \neg\left(R_{i} \wedge R_{j}\right)\right\rceil \wedge \bigwedge_{i=1}^{6} \mathrm{~T}\left(R_{i}, W_{i}\right) \wedge \gamma\right)(5 \tag{5}
\end{equation*}
$$

where $\gamma$ describes the concurrent execution of the six threads and is written using the additional abbreviations:

$$
\alpha_{i}(T) \rightleftharpoons \alpha\left(R_{i+1} \vee \ldots \vee R_{6}, W_{i+1} \wedge \ldots \wedge W_{6}, T\right) \text { and } \beta_{i}(T) \rightleftharpoons \beta\left(R_{i}, W_{i}, T\right)
$$

With these abbreviations $\gamma$ can be written as

Here $T_{i}$ denotes the time between launching the $i$ th and the $i+1$ st download and $D_{i}$ denotes the duration of the $i$ th download, $i=1, \ldots, 5$. The formulas $\xi$ and $\eta$ denote

$$
\left.\left(\left\lceil\neg R_{5}\right\rceil ; \mathrm{K}^{R_{5}}(V \backslash\{\text { handle }\}) \wedge \text { handle }{ }^{\prime}=\text { requestDownload }(\text { url }, \text { timeout }) \wedge \int \neg N=x ; \top\right)\right)
$$

and

$$
\left(\left(\left\lceil\neg R_{6}\right\rceil ; \mathrm{K}^{R_{6}}(V) \wedge \neg \text { userRequest }\right)^{*} ; \top\right)
$$

and correspond to the thread for the 5th download and the thread for subsequent user requests after the 5th download request. The occurrences of T in them mark future behaviour which is not specified in our scenario. The semantics of letrec implies (5); this can be established using the validity of $\mu X . \varphi \Leftrightarrow[\mu X . \varphi / X] \varphi$. Assuming that the rate of downloading is the limiting factor for the working of the entire system, which allows us to ignore time taken for dialog, computation and by requestDownload for the first four downloads, the 5 th download becomes cancelled in case $x$ exceeds timeout, which is equivalent to

$$
\text { timeout }+\sum_{j=1}^{4} T_{i}<\min _{i=1}^{4}\left(D_{i}+\sum_{j=1}^{i-1} T_{j}\right)
$$

Let $F(l, t)$ be a lower bound for the probability for download do complete a download of length $l$ within time $t$. It can be assumed that $F(a l, a t)=F(l, t)$ for all $a>0$ and that $F(l, t)=0$ in case $\frac{l}{t}$ exceeds the top transmission rate $v$. Let $l_{i}$ be the length of the $i$ th download, $i=1, \ldots, 5$. Let $l_{i}>v\left(T_{1}+T_{2}+T_{3}+T_{4}\right)$ for $i=1, \ldots, 4$, that is, none of the downloads can be over before all of them have been launched, for the sake of simplicity. Then the probability $P_{i}$ for $i \in\{1, \ldots, 4\}$ to be the first download to complete, and to complete before the timeout for the pending 5th download is at least

$$
\int_{\left\{\left\langle q_{1}, \ldots, q_{4}\right\rangle: l_{i}-q_{i} \leq l_{j}-q_{j}, j=1, \ldots, 4\right\}} \frac{\partial}{\partial q} F(q, t)\left(l_{i}-q_{i}, \text { timeout }\right) . \prod_{k=1}^{4} F^{\prime}\left(q_{k}, \sum_{s=k}^{4} T_{s}\right) d q_{1} \ldots d q_{4}
$$

The probability for the 5 th download not to be cancelled is $P_{1}+\ldots+P_{4}$. Approximations of the above integral can be derived in PITL using Seq much like in Example 1.

Using a contract in which the execution time of download is approximated by a distribution depending just the amount of data to transmit is too crude. A more accurate calculation is possible by taking the amount of competing traffic in account, but the form of contract that we propose does not enable it.

## 4 Probabilistic timed designs

A design $\langle P, R\rangle$, usually written as $P \vdash R$, describes a computation by a precondition $P$, an input-output relation $R$. $P$ constrains the initial values $v$ of the variables, and $R$ is a relation between $v$ and the final values $v^{\prime}$ of the variables, which holds if $v$ initially satisfy $P$. A probabilistic timed design $\langle P, R, F\rangle$ additionally includes an execution time distribution $F . F(v, t)$ is a lower bound for the probability for the computation to terminate within time $t$, provided that $P(v)$ holds. A hard bound $d$ on execution time can be expressed by a $F$ satisfying $F\left(d^{\prime}\right)=1$ for all $d^{\prime} \geq d$.

### 4.1 Describing designs in $P D C$

The property of method $m$ encoded by $\langle P, R, F\rangle$ can be written as the PITL formulas

$$
m \Rightarrow\left(P(v) \Rightarrow R\left(v, v^{\prime}\right)\right) \text { and } \ell=0 \Rightarrow p(P(v) \wedge m \wedge \ell>t ; \top)<1-F(v, t)
$$

The first one is for the functional behaviour of $m$. The second one states that if $P(v)$ holds, then $m$ to takes more than $t$ time units with probability less than $1-F(v, t)$. $F$ is just a lower bound, because an exact probability need not exist.

### 4.2 Refinement of probabilistic timed designs

Design $D_{1}=\left\langle P_{1}, R_{1}, F_{1}\right\rangle$ refines design $D_{2}=\left\langle P_{2}, R_{2}, F_{2}\right\rangle$, written $D_{1} \sqsubseteq D_{2}$, if

$$
\forall x\left(P_{2}(x) \Rightarrow P_{1}(x)\right), \forall x \forall x^{\prime}\left(R_{1}\left(x, x^{\prime}\right) \Rightarrow R_{2}\left(x, x^{\prime}\right)\right), \text { and } \forall x \forall t\left(F_{2}(x, t) \leq F_{1}(x, t)\right)
$$

This means that $D_{1}$ has a weaker or equivalent precondition and a stronger or equivalent input-output relation, and on average terminates at least as fast as $D_{2}$. Obviously if $D_{1} \sqsubseteq D_{2}$, then

$$
P_{1}(v) \wedge m \Rightarrow R_{1}\left(v, v^{\prime}\right) \text { and } \forall x\left(\ell=0 \Rightarrow p\left(P_{1}(v) \wedge m \wedge \ell>x ; \top\right)<1-F_{1}(v, x)\right)
$$

entail

$$
P_{2}(v) \wedge m \Rightarrow R_{2}\left(v, v^{\prime}\right) \text { and } \forall x\left(\ell=0 \Rightarrow p\left(P_{2}(v) \wedge m \wedge \ell>x ; \top\right)<1-F_{2}(v, x)\right)
$$

## 5 Probabilistic timed contracts

The execution time of a method depends on the execution times of the methods which have calls in its body.
Definition 3 (component declaration) A component declaration is a pair $\left\langle M_{i}, M_{e}\right\rangle$ where $M_{i}$ and $M_{e}$ are disjoint sets of declarations for imported and exported methods, respectively.

Definition 4 (probabilistic timed contract) Let $\left\langle M_{i}, M_{e}\right\rangle$ be a component declaration and $V_{m}$ be the set of the valuations for the variables of declaration $m, m \in M_{i} \cup M_{e}$. The tuple $C=\left\langle D_{m}: m \in M_{i} \cup M_{e}\right\rangle$ is a contract for $\left\langle M_{i}, M_{e}\right\rangle$, if $D_{m}$ are of the form $\left\langle P_{m}, R_{m}, F_{m}\right\rangle$ where
(i) $\left\langle P_{m}, R_{m}\right\rangle$ is a (non-probabilistic) design for $m, m \in M_{i} \cup M_{e}$.
(ii) $F_{m}$ is a variable of type $V_{m} \times \mathbf{R}_{+} \rightarrow[0,1]$ for method declarations $m \in M_{i}$ and is meant to denote a distribution of the execution time of implementations of $m$.
(iii) For declarations $m \in M_{e}, F_{m}$ an expression for the distibution of the execution time of an implementation of declaration $m$ as in probabilistic designs in terms of $F_{n}, n \in M_{i}$.

We denote $\left\{n \in M_{i}: F_{n}\right.$ occurs in $\left.F_{m}\right\}$ by $C_{i, m}$. Semantically, if $m \in M_{e}$, then the type of $F_{m}$ is

$$
\left(\prod_{n \in C_{i, m}} V_{n} \times \mathbf{R}_{+} \rightarrow[0,1]\right) \rightarrow\left(V_{m} \times \mathbf{R}_{+} \rightarrow[0,1]\right)
$$

Syntactically we assume that $F_{m}$ is an expression such as, e.g., (2). A contract $C$ is meant to express that if the methods $m \in M_{i}$ satisfy their corresponding designs $D_{m}$ and the distribution variables $F_{m}$ are
assigned lower bounds for the distributions of their execution times, then the methods from $M_{e}$ satisfy their corresponding designs and the expressions $F_{m}$ evaluate to lower bounds for the distributions of their execution times too. If $C_{i, m}=0$ then $\left\langle P_{m}, R_{m}, F_{m}\right\rangle$ is essentially a probabilistic timed design.

Definition 5 (refinement of probabilistic timed contracts) Let $C$ and $C^{\prime}$ be probabilistic timed contracts for $\left\langle M_{i}, M_{e}\right\rangle$ and $\left\langle M_{i}^{\prime}, M_{e}^{\prime}\right\rangle$, respectively. Let $C=\left\langle\left\langle P_{m}, R_{m}, F_{m}\right\rangle: m \in M_{i} \cup M_{e}\right\rangle$ and $C^{\prime}=$ $\left\langle\left\langle P_{m}^{\prime}, R_{m}^{\prime}, F_{m}^{\prime}\right\rangle: m \in M_{i}^{\prime} \cup M_{e}^{\prime}\right\rangle$. Then, $C^{\prime}$ refines $C$, written $C^{\prime} \sqsubseteq C$, if
(i) $M_{i}^{\prime} \subseteq M_{i}, M_{e}^{\prime} \supseteq M_{e}$;
(ii) $\left\langle P_{m}, R_{m}\right\rangle \sqsubseteq\left\langle P_{m}^{\prime}, R_{m}^{\prime}\right\rangle$ for $m \in M_{i}^{\prime},\left\langle P_{m}^{\prime}, R_{m}^{\prime}\right\rangle \sqsubseteq\left\langle P_{m}, R_{m}\right\rangle$ for $m \in M_{e}$;
(iii) $F_{m}(v, t) \leq F_{m}^{\prime}(v, t)$ for $m \in M_{e}, v \in V_{m}, t \in \mathbf{R}_{+}$regardless of the values of $F_{n}, n \in M_{i}$.

### 5.1 Composing probabilistic timed contracts

Let $A^{k}=\left\langle M_{i}^{k}, M_{e}^{k}\right\rangle$ and $C^{k}=\left\langle\left\langle P_{m}^{k}, R_{m}^{k}, F_{m}^{k}\right\rangle: m \in M_{i}^{k} \cup M_{e}^{k}\right\rangle, k=1,2$, be two component declarations and probabilistic timed contracts for them, respectively. $A^{1}$ and $A^{2}$ are composable, if $M_{e}^{1} \cap M_{e}^{2}=\emptyset$. $C^{1}$ and $C^{2}$ are composable, if $A^{1}$ and $A^{2}$ are composable, and $D_{m}^{k} \sqsubseteq D_{m}^{2-k}$ for $m \in M_{e}^{k} \cap M_{i}^{2-k}, k=1,2$. The composition of $C^{1}$ and $C^{2}$, written $C^{1} \cup C^{2}$, is $\left\langle\left\langle P_{m}, R_{m}, F_{m}\right\rangle: m \in M_{i}^{1} \cup M_{e}^{1} \cup M_{i}^{2} \cup M_{e}^{2}\right\rangle$ where:
(i) $P_{m}(v) \rightleftharpoons P_{m}^{1}(v) \wedge P_{m}^{2}(v), R_{m}\left(v, v^{\prime}\right) \rightleftharpoons R_{m}^{1}\left(v, v^{\prime}\right) \wedge R_{m}^{2}\left(v, v^{\prime}\right)$ and $F_{m}=F_{m}^{1}=F_{m}^{2}$ for $m \in M_{i}^{1} \cap M_{i}^{2}$;
(ii) $P_{m}=P_{m}^{k}$ and $R_{m}=R_{m}^{k}$ for $m \in M_{e}^{k} \cup\left(M_{i}^{k} \backslash M_{i}^{2-k}\right), k=1,2$;
(iii) $F_{m}=F_{m}^{k}$ for $m \in M_{i}^{k} \backslash M_{i}^{2-k}, k=1,2$.

To facilitate the understanding, we first define $F_{m}, m \in M_{e}^{1} \cup M_{e}^{2}$, in case $C^{1}$ and $C^{2}$ allow no circular dependency between the methods, that is, if there is no sequence $m_{0}, \ldots, m_{2 s-1}$ such that $m_{r} \in M_{e}^{1} \cap M_{i}^{2}$ for $r=1,3, \ldots, 2 s-1, M_{r} \in M_{e}^{2} \cap M_{i}^{1}$ for $r=0,2, \ldots, 2 s-2$ and $m_{r} \in C_{i, m_{r+1} \bmod 2 s}^{2-r}, r=0, \ldots, 2 s-1$. Given that there is no circular dependency, we can define dependency depth of $m$ from $C^{1} \cup C^{2}$ as the length $s$ of the longest sequence of the form $m_{1}, \ldots, m_{s}$ such that $m_{1} \in C_{i, m}$ and $m_{r+1} \in C_{i, m_{r}}^{k}$, where $k$ is such that $m_{r} \in M_{e}^{k}$, for $r=1, \ldots, s-1$, and we can define $F_{m}$ by induction on the dependency depth of $m$ by the clauses:
$F_{m}=F_{m}^{k}$ for $m \in M_{e}^{k}$ of dependency depth 0 ;
$F_{m}=\left[F_{n} / F_{n}^{k}: n \in C_{i, m}^{k}\right] F_{m}^{k}$ for $m \in M_{e}^{k}$ of nonzero dependency depth.
Note that the substitution replaces $F_{n}^{k}$ with the expression for it from $C^{2-k}$, in case $n \in M_{e}^{2-k}$. Otherwise $F_{n}^{k}$ is not affected by this substitution.

If thereare circular dependencies between $C^{1}$ and $C^{2}$, then the $F_{m}$ s for the exported methods in $C^{1} \cup C^{2}$ should be a solution of the system of equations

$$
X_{m}=\left[X_{n} / F_{n}^{k}: n \in C_{i, m}\right] F_{m}^{k}
$$

Solving it without restrictions on $F_{m}^{k}$ can be hard ${ }^{2}$, but if $F_{m}^{k}$ and monotonic, then $X_{m}$ can be obtained as the limits of the sequences $X_{m}^{j}, j<\omega$, where $X_{m}^{0} \equiv 0$ and

$$
X_{m}^{j+1}=\left[X_{n}^{j} / F_{n}^{k}: n \in C_{i, m}^{k}\right] F_{m}^{k} \text { for } m \in M_{e}^{k} .
$$

Observe that $X_{m}^{0} \equiv 0$ implies that $X_{m}^{1}$ would give non-zero termination probability only to runs of $m$ with no calls to other imported methods; $X_{m}^{2}$ would give non-zero probability for runs with calls to imported methods which themselves lead to no further calls, etc. Since $F_{m}^{k}$ are meant to be under-approximations, and the monotonicity of $F_{m}^{k}$ entails $X_{m}^{s} \leq X_{m}^{s+1} \leq \lim _{j} X_{m}^{j}$ for all $s<\omega, X_{m}^{s}$ can be used as $F_{m}$ instead of $\lim _{j} X_{m}^{j}$ for sufficiently large $s$, to achieve a crude, but less expensive approximation.

## Concluding remarks

Here we focused just on soft requirements on execution time, but we believe that the approach can be used to capture other QoS requirements involving probability as well. The notion of QoS originated from telecommunications. Our examples come from everyday use of the Internet and need no expertise to understand. However, we believe that our technique would work just as well in other areas such as embedded systems.

[^2]
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## A Proof systems

## A. 1 Proof system for $I T L$ with infinite intervals

The following axioms and rules have been shown to form a complete proof system for $I T L$ with infinite intervals when added to a Hilbert-style proof system for classical first-order predicate logic and appropriate axioms about an abstract domain of durations in [WX04]:
$(A 2) \quad((\varphi ; \psi) ; \chi) \Leftrightarrow(\varphi ;(\psi ; \chi))$
$(R) \quad(\varphi ; \psi) \Rightarrow \varphi,(\psi ; \varphi) \Rightarrow \varphi$ if $\varphi$ is rigid
(B) $\quad(\exists x \varphi ; \psi) \Rightarrow \exists x(\varphi ; \psi),(\psi ; \exists x \varphi) \Rightarrow \exists x(\psi ; \varphi)$ if $x$ has no free occurrences in $\psi$
(L1) $\quad(\ell=x ; \varphi) \Rightarrow \neg(\ell=x ; \neg \varphi),(\varphi ; \ell=x \wedge x \neq \infty) \Rightarrow \neg(\neg \varphi ; \ell=x)$
(L2) $\quad \ell=x+y \wedge x \neq \infty \Leftrightarrow(\ell=x ; \ell=y)$
(L3) $\quad \varphi \Rightarrow(\ell=0 ; \varphi), \varphi \wedge \ell \neq \infty \Rightarrow(\varphi ; \ell=0)$
(S1) $\quad(\ell=x \wedge \varphi ; \psi) \Rightarrow \neg(\ell=x \wedge \neg \varphi ; \chi)$
$(P 1) \quad \neg(\ell=\infty ; \varphi)$
$(P 2) \quad(\varphi ; \ell=\infty) \Rightarrow \ell=\infty$
$(P 3) \quad(\varphi ; \ell \neq \infty) \Rightarrow \ell \neq \infty$
$(N) \quad \frac{\varphi}{\neg(\neg \varphi ; \psi)}, \frac{\varphi}{\neg(\psi ; \neg \varphi)}$
(Mono) $\frac{\varphi \Rightarrow \psi}{(\varphi ; \chi) \Rightarrow(\psi ; \chi)}, \frac{\varphi \Rightarrow \psi}{(\chi ; \varphi) \Rightarrow(\chi ; \psi)}$

```

Using the first order logic axiom
\[
\left(\exists_{r}\right)[t / x] \varphi \Rightarrow \exists x \varphi
\]
is correct only if no variable in \(t\) becomes bound due to the substitution, and either \(t\) is rigid or (.;.) does not occur in \(\varphi\).

\section*{A. 2 Axioms and rules for \(D C\) with infinite intervals}

The axioms and rules below were proposed for \(D C\) with finite intervals and have been shown to be complete relative to validity in real-time \(I T L\) in [HZ92].
\begin{tabular}{ll}
\((D C 1)\) & \(\int \mathbf{0}=0\) \\
\((D C 2)\) & \(\int \mathbf{1}=\ell\) \\
\((D C 3)\) & \(\int S \geq 0\) \\
\((D C 4)\) & \(\int S_{1}+\int S_{2}=\int\left(S_{1} \vee S_{2}\right)+\int\left(S_{1} \wedge S_{2}\right)\) \\
\((D C 5)\) & \(\left(\int S=x ; \int S=y\right) \Rightarrow \int S=x+y\) \\
\((D C 6)\) & \(\int S_{1}=\int S_{2}\) if \(S_{1}\) and \(S_{2}\) are propositionally equivalent \\
\((I R 1)\) & \(\frac{[\ell=0 / A] \varphi \varphi \Rightarrow[A \vee(A ;\lceil S \rrbracket \vee \llbracket \neg S \rrbracket) / A] \varphi}{[\top / A] \varphi}\) \\
\((I R 2)\) & \(\frac{[\ell=0 / A] \varphi \varphi \Rightarrow[A \vee(\llbracket S \rrbracket \vee \llbracket \neg S \rrbracket ; A) / A] \varphi}{[\top / A] \varphi}\)
\end{tabular}

The completeness proof from [HZ92] involves two theorems which can be derived using the rules \(I R 1\) and \(I R 2\), instead of the rules themselves. The second of these theorems does not hold for infinite intervals and therefore we modify it appropriately:
(T1) \(\quad \ell=0 \vee(\lceil S\rceil ; \top) \vee(\llbracket \neg S \rrbracket ; \top)\)
(T2) \(\quad \ell=0 \vee \ell=\infty \vee(\top ; \llbracket S \rrbracket) \vee(\top ; \llbracket \neg S \rrbracket)\)
\(D C 1-D C 6, T 1\) and the infinite-interval variant of \(T 2\) form a relatively complete proof system for \(D C\) with infinite intervals.

\section*{A. 3 Proof system for PITL}

PITL is a conservative extension of ITL. Adding the axioms and a proof rule below to the proof system for \(I T L\) leads to a system which is complete for PITL with respect to a generalisation of the \(\mathbf{R}\)-based semantics, where \(\overline{\mathbf{R}}\) is replaced by an abstract domain and the probability measures are required to be only finitely aditive.
Extensionality
\[
\begin{array}{ll}
\left(P_{;}\right) & (\ell=x ; p(\psi)=y) \Rightarrow p((\ell=x ; \psi))=y \\
\left(P_{\infty}\right) & \ell=\infty \Rightarrow(\varphi \Leftrightarrow p(\varphi)=1) \\
\left(P_{\leq}\right) & \frac{\vdash(\varphi ; \ell=\infty) \Rightarrow(\psi \Rightarrow \chi)}{\vdash \varphi \wedge \ell<\infty \Rightarrow p(\psi) \leq p(\chi)}
\end{array}
\]

Arithmetics of probabilities
\[
\begin{array}{ll}
\left(P_{\perp}\right) & p(\perp)=0 \\
\left(P_{\top}\right) & p(\top)=1 \\
\left(P_{+}\right) & p(\varphi)+p(\psi)=p(\varphi \vee \psi)+p(\varphi \wedge \psi)
\end{array}
\]

\section*{A. 4 Useful theorems and derived rules for \(P I T L\)}

All the theorems and rules below except \(P_{;}^{\prime}\) are valid in general PITL models. \(P_{;}^{\prime}\) is valid in PITL models with global probability.
\[
\begin{aligned}
& \left(P_{\leq}^{\infty}\right) \quad \frac{(\varphi ; \ell=\infty) \vee(\varphi \wedge \ell=\infty) \Rightarrow(\psi \Rightarrow \chi)}{\varphi \Rightarrow p(\psi) \leq p(\chi)} \\
& \text { (PITL1) } \quad \frac{\varphi \Rightarrow \psi}{p(\varphi) \leq p(\psi)}, \frac{\varphi \Leftrightarrow \psi}{p(\varphi)=p(\psi)} \\
& (\text { PITL2 }) \quad p(\varphi)+p(\neg \varphi)=1 \\
& (\text { PITL3 }) \quad p(\varphi)<p(\psi) \Rightarrow p(\psi \wedge \neg \varphi) \neq 0 \\
& \text { (PITL4) } \quad p(\varphi)=p(\varphi \wedge \ell=\infty) \\
& \text { (PITL5) } \quad p(\varphi) \leq 1 \\
& \text { (PITL6) } \quad \frac{\varphi}{p(\varphi)=1}, \frac{\neg \varphi}{p(\varphi)=0} \\
& \text { (PITL7) } \quad(\varphi ; \top) \Rightarrow p(\varphi ; \top)=1 \\
& \text { (PITL8) } \quad p(\varphi)=1 \wedge p(\psi)=x \Rightarrow p(\varphi \wedge \psi)=x \\
& \text { (PITL9) } \quad p(\varphi \Rightarrow \psi)=1 \Rightarrow(p(\varphi)=1 \Rightarrow p(\psi)=1) \\
& p(\varphi \Rightarrow \psi)=1 \Rightarrow(p(\psi)=0 \Rightarrow p(\varphi)=0) \\
& (\text { PITL10 }) \quad p(\varphi)+p(\psi)>1 \Rightarrow p(\varphi \wedge \psi)>0 \\
& \left(P_{;}^{\prime}\right) \quad \frac{\varphi \Rightarrow \neg(\varphi ; \ell \neq 0)}{(\varphi ; p(\psi)=x) \Rightarrow p(\varphi ; \psi)=x}
\end{aligned}
\]

Here follow the proofs of the above PITL theorems and derived rules. The purely \(I T L\) parts are skipped and marked "ITL" for the sake of brevity.
\(P_{\leq}^{\infty}:\)
\begin{tabular}{rlrl}
1 & \((\varphi ; \ell=\infty) \Rightarrow\) & \((\psi \Rightarrow \chi)\) & \\
2 & \(\varphi \wedge \ell<\infty \Rightarrow p(\psi) \leq p(\chi)\) & & assumption, ITL \\
3 & \(\ell=\infty \wedge \varphi \Rightarrow\) & \((p(\psi)=0 \wedge p(\chi)=0)\) & \\
& \(\vee(p(\psi)=0 \wedge p(\chi)=1)\) & & \\
& \(\vee(p(\psi)=1 \wedge p(\chi)=1)\) & \\
& & & \\
4 & \(\varphi \wedge \ell=\infty \Rightarrow p(\psi) \leq p(\chi)\) & & ITLL \\
5 & \(\ell<\infty \vee \ell=\infty\) & \(2,4,5\) \\
6 & \(\varphi \Rightarrow p(\psi) \leq p(\chi)\) & &
\end{tabular}

\section*{PITL1:}
\(1 \quad \varphi \Rightarrow \psi\)
assumption
\(2 \quad(\top ; \ell=\infty) \vee(\top \wedge \ell=\infty) \Rightarrow(\varphi \Rightarrow \psi) \quad 1, I T L\)
\(3 \quad p(\varphi) \leq p(\psi)\)
\(2, P_{\leq}^{\infty}\)

The second rule PITL1 is proved by two applications the first.
PITL2:
\begin{tabular}{lll}
1 & \(\varphi \wedge \neg \varphi \Leftrightarrow \perp\) & ITL \\
2 & \(p(\varphi \wedge \neg \varphi)=p(\perp)\) & \(1, P I T L 1\) \\
3 & \(p(\varphi \wedge \neg \varphi)=0\) & \(2, P_{\perp}\) \\
4 & \(\varphi \vee \neg \varphi \Leftrightarrow \top\) & ITL \\
5 & \(p(\varphi \vee \neg \varphi)=p(\top)\) & \(4, P I T L 1\) \\
6 & \(p(\varphi \wedge \neg \varphi)=1\) & \(5, P_{\top}\) \\
7 & \(p(\varphi)+p(\neg \varphi)=p(\varphi \wedge \neg \varphi)+p(\varphi \wedge \neg \varphi)\) & \(P_{+}\) \\
8 & \(p(\varphi)+p(\neg \varphi)=1\) & \(2,6,7, I T L\)
\end{tabular}

PITL3:
\begin{tabular}{lll}
1 & \(p(\psi) \leq p(\varphi \vee \psi)\) & \(P_{\leq}^{\infty}\) \\
2 & \(p(\varphi)+p(\psi \wedge \neg \varphi)=p(\varphi \wedge \psi \wedge \neg \varphi)+p(\varphi \vee \psi \wedge \neg \varphi)\) & \(P_{+}\) \\
3 & \(p(\varphi)+p(\psi \wedge \neg \varphi)=p(\varphi \vee \psi)\) & 2, PITL1,\(P_{\perp}\) \\
4 & \(p(\varphi)<p(\psi) \Rightarrow p(\varphi)<p(\varphi \vee \psi)\) & 1 \\
5 & \(p(\varphi)<p(\psi) \Rightarrow p(\psi \wedge \neg \varphi) \neq 0\) & 3,4
\end{tabular}

PITL4 is obtained by applying \(P_{\leq}^{\infty}\) to the \(I T L\) theorems
\[
(T ; \ell=\infty) \vee(T \wedge \ell=\infty) \Rightarrow(\varphi \Rightarrow \varphi \wedge \ell=\infty) \text { and }(T ; \ell=\infty) \vee(T \wedge \ell=\infty) \Rightarrow(\ell=\infty \wedge \varphi \Rightarrow \varphi) .
\]

PITL5:
\begin{tabular}{lll}
1 & \(\varphi \Rightarrow \top\) & \(I T L\) \\
2 & \(p(\varphi) \leq p(\top)\) & \(1, P I T L 1\) \\
3 & \(p(\varphi) \leq 1\) & \(2, P_{\top}\)
\end{tabular}

PITL6:
\begin{tabular}{lll}
1 & \(\top \Rightarrow \varphi\) & assumption \\
2 & \(p(\top) \leq p(\varphi)\) & 1, PITL1 \\
3 & \(1 \leq p(\varphi)\) & \(2, P_{\top}\) \\
4 & \(p(\varphi) \leq 1\) & PITL5 \\
5 & \(p(\varphi)=1\) & 3,4
\end{tabular}
\[
\begin{array}{ll}
\neg \varphi & \text { assumption } \\
p(\neg \varphi)=1 & 1, \text { PITL6 } \\
p(\varphi)=0 & \text { PITL2 }
\end{array}
\]

\section*{PITL7:}
\[
\begin{array}{lll}
1 & (\varphi ; \top ; \ell=\infty) \vee((\varphi ; \top) \wedge \ell=\infty) \Rightarrow(\top \Rightarrow(\varphi ; \top)) & I T L \\
2 & (\varphi ; \top) \Rightarrow p(\varphi ; \top)=1 & P_{\leq}^{\infty}
\end{array}
\]

\section*{PITL8:}
\[
\begin{array}{lll}
1 & p(\varphi)=1 \wedge p(\psi)=x \Rightarrow p(\varphi \wedge \psi)+p(\varphi \vee \psi)=1+x & P_{+} \\
2 & \varphi \Rightarrow(\varphi \vee \psi) & \text { ITL } \\
3 & p(\varphi) \leq p(\varphi \vee \psi) & 2, \text { PITL1 } \\
4 & p(\varphi)=1 \Rightarrow p(\varphi \vee \psi)=1 & 3, \text { PITL5 } \\
5 & p(\varphi)=1 \wedge p(\psi)=x \Rightarrow p(\varphi \wedge \psi)=x & 1,4
\end{array}
\]

\section*{PITL9:}
\[
\begin{array}{ll}
p(\varphi \Rightarrow \psi)=1 \wedge p(\varphi)=1 \Rightarrow p((\varphi \Rightarrow \psi) \wedge \psi)=1 & \text { PITL8 } \\
(\varphi \Rightarrow \psi) \wedge \psi \Rightarrow \psi & \\
p((\varphi \Rightarrow \psi) \wedge \psi) \leq p(\psi) & 2, \text { PITL1 } \\
p(\psi) \leq 1 & \text { PITL5 } \\
p(\varphi \Rightarrow \psi)=1 \Rightarrow(p(\varphi)=1 \Rightarrow p(\psi)=1) & 1-4 \\
p((\varphi \Rightarrow \psi) \Rightarrow(\neg \psi \Rightarrow \neg \varphi))=1 & \text { PITL6 } \\
p(\varphi \Rightarrow \psi)=1 \Rightarrow p(\neg \psi \Rightarrow \neg \varphi)=1 & 1, \text { PITL9 } \\
p(\neg \psi \Rightarrow \neg \varphi)=1 \Rightarrow(p(\neg \psi)=1 \Rightarrow p(\neg \varphi)=1) & \text { PITL9 } \\
p(\neg \psi \Rightarrow \neg \varphi)=1 \Rightarrow(p(\neg \psi)=0 \Rightarrow p(\neg \varphi)=0) & 3, \text { PITL2 } \\
p(\varphi \Rightarrow \psi)=1 \Rightarrow(p(\neg \psi)=0 \Rightarrow p(\neg \varphi)=0) & 2,4
\end{array}
\]

PITL10:
```

p(\varphi)+p(\psi)>1=>p(\varphi\wedge\psi)+p(\varphi\vee\psi)>1
p(\varphi\vee\psi)\leq1 PITL5
p(\varphi)+p(\psi)>1=>p(\varphi\wedge\psi)>0 1,2

```
\(P_{;}^{\prime}\) :
```

$(\varphi ; p(\psi)=x) \Rightarrow \exists t((\varphi \wedge \ell=t ; \top) \wedge(\ell=t ; p(\psi)=x))$
$(\varphi \wedge \ell=t ; \top) \Rightarrow p(\varphi \wedge \ell=t ; \top)=1$
$(\ell=t ; p(\psi)=x) \Rightarrow p(\ell=t ; \psi)=x$
$p(\varphi \wedge \ell=t ; \top)=1 \wedge p(\ell=t ; \psi)=x \Rightarrow p(\varphi \wedge \ell=t ; \psi)=x$
$(\varphi \wedge \ell=t ; \psi) \Rightarrow(\varphi ; \psi)$
$p(\varphi \wedge \ell=t ; \psi)=x \Rightarrow p(\varphi ; \psi) \geq x$
$\exists t((\varphi \wedge \ell=t ; \top) \wedge(\ell=t ; p(\psi)=x)) \Rightarrow \exists t(p(\varphi ; \psi) \geq x)$
$\exists t(p(\varphi ; \psi) \geq x) \Leftrightarrow p(\varphi ; \psi) \geq x$
$(\varphi ; p(\psi)=x) \Rightarrow p(\varphi ; \psi) \geq x$
$(\varphi ; p(\psi)=x) \Leftrightarrow(\varphi ; p(\neg \psi)=1-x)$
$(\varphi ; p(\neg \psi)=1-x) \Rightarrow p(\varphi ; \neg \psi) \geq 1-x$
$(p(\varphi ; \psi)>x \wedge p(\varphi ; \neg \psi) \geq 1-x) \vee(p(\varphi ; \psi) \geq x \wedge p(\varphi ; \neg \psi)>1-x)$
$\Rightarrow p((\varphi ; \psi) \wedge(\varphi ; \neg \psi))>0$
$(\varphi ; \psi) \wedge(\varphi ; \neg \psi) \wedge \neg(\varphi \wedge(\varphi ; \ell \neq 0) ; \top) \Rightarrow \perp$
$p((\varphi ; \psi) \wedge(\varphi ; \neg \psi) \wedge \neg(\varphi \wedge(\varphi ; \ell \neq 0) ; \top))=0$
$p(\neg(\varphi \wedge(\varphi ; \ell \neq 0) ; \top))=1$
$p((\varphi ; \psi) \wedge(\varphi ; \neg \psi))=0$
$p(\varphi ; \neg \psi) \geq 1-x \wedge p(\varphi ; \psi) \geq x \Rightarrow p(\varphi ; \psi) \leq x \wedge p(\varphi ; \neg \psi) \leq 1-x$
$(\varphi ; p(\psi)=x) \Rightarrow p(\varphi ; \psi)=x$

```

ITL
PITL7
\(P_{;}\)
PITLS, PITL1, ITL
ITL
5, PITL1
\(2-6, I T L\)
ITL
1,7,8
PITL2, ITL
like \(1-9\), but with \(\neg \psi\) as \(\psi\)

\section*{PITL10}

ITL
13, PITL6
assumption, PITL6
14, 15, PITL8
12, 16, ITL
\(9,11,17, I T L\)

\section*{A. 5 The rule \(S e q\)}

In the proof of the admissibility of \(S e q\) below \(\varphi \wedge \ell \geq l \wedge \ell \leq h\) is abbreviated by \(\varphi_{l}^{h}\).
```

    \((\ell=0 \wedge p(\alpha ; \beta ; \top)=1 ; \top) \Rightarrow p(p(\alpha ; \beta ; \top)=1 \wedge \ell=0 ; \top)=1\)
    \((\alpha ; p(\beta ; \top)=x \wedge \ell=0) \Rightarrow p(\alpha ; \beta ; \top)=x\)
    \(\exists x((\alpha ; \top) \Rightarrow(\alpha ; p(\beta ; \top)=x \wedge \ell=0 ; \top))\)
    $P_{;}^{\prime}$, assumptions
ITL

```
\(4 \quad p(\alpha ; \beta ; \top)=1 \Rightarrow\)
    \(\exists x((\alpha ; \top) \Rightarrow p(\alpha ; \beta ; \top)=x \wedge(\alpha ; p(\beta ; \top)=x \wedge \ell=0 ; \top) \wedge p(\alpha ; \beta ; \top)=1)\)
    \(p(\alpha ; \beta ; \top)=1 \Rightarrow \exists x((\alpha ; \top) \Rightarrow(\alpha ; p(\beta ; \top)=1 \wedge \ell=0 ; \top))\)
    \(p(\alpha ; \beta ; \top)=1 \wedge(\alpha ; \top) \Rightarrow(\alpha ; p(\beta ; \top)=1 \wedge \ell=0 ; \top)\)
4, ITL
    \(p(p(\alpha ; \beta ; \top)=1 \wedge(\alpha ; \top) \Rightarrow(\alpha ; p(\beta ; \top)=1 \wedge \ell=0 ; \top))=1\)
    \(p(p(\alpha ; \beta ; \top)=1 ; \top)=1 \wedge p(\alpha ; \top)=1 \Rightarrow p(\alpha ; p(\beta ; \top)=1 \wedge \ell=0 ; \top)=1\)
    \(\ell=0 \wedge p(\alpha ; \beta ; \top)=1 \wedge p(\alpha ; \top)=1 \Rightarrow p(\alpha ; p(\beta ; \top)=1 \wedge \ell=0 ; \top)=1\)
    \(p(\alpha ; \beta ; \top)=1 \Rightarrow p(\alpha ; \top)=1\)
\(11 \ell=0 \wedge p(\alpha ; \beta ; \top)=1 \Rightarrow p(\alpha ; p(\beta ; \top)=1 \wedge \ell=0 ; \top)=1\)
9,10
PITL8
    \(p((\alpha ; p(\beta ; \top)=1 \wedge \ell=0 ; \top) \wedge(\alpha ; p(\beta ; \top) \neq 1 \wedge \ell=0 ; \top))=x\)
PITL6
\(13 p((\alpha ; p(\beta ; \top)=1 \wedge \ell=0 ; \top) \wedge(\alpha ; p(\beta ; \top) \neq 1 \wedge \ell=0 ; \top))=0\)
\(14 p(\alpha ; p(\beta ; \top)=1 \wedge \ell=0 ; \top)=1 \Rightarrow p(\alpha ; p(\beta ; \top) \neq 1 \wedge \ell=0 ; \top)=0\)
12, 13
\(\ell=0 \wedge p(\alpha ; \beta ; \top)=1 \Rightarrow p(\alpha ; p(\beta ; \top) \neq 1 \wedge \ell=0 ; \top)=0\)
11, 14
\(16 \quad \ell=0 \Rightarrow\left(p\left(\beta_{l_{2}}^{h_{2}} ; \top\right) \neq x_{2} \Rightarrow p(\beta ; \top) \neq 1\right)\)
\(\alpha_{l_{1}}^{h_{1}} \Rightarrow \alpha\)
    \(\left(\alpha_{l_{1}}^{h_{1}} ; p\left(\beta_{l_{2}}^{h_{2}} ; \top\right) \neq x_{2} \wedge \ell=0 ; \top\right) \Rightarrow(\alpha ; p(\beta ; \top) \neq 1 \wedge \ell=0 ; \top)\)
\(\left[E T_{\beta} \in\left[l_{2}, h_{2}\right]\right]_{x_{2}}\)
ITL
\(\ell=0 \wedge p(\alpha ; \beta ; \top)=1 \Rightarrow p\left(\alpha_{l_{1}}^{h_{1}} ; p\left(\beta_{l_{2}}^{h_{2}} ; \top\right) \neq x_{2} \wedge \ell=0 ; \top\right)=0\)
16, 17, ITL

15, 18, PITL6, PITL9
\(20 \neg(\alpha \wedge(\alpha ; \ell \neq 0) ; \top) \Rightarrow\)
\(\left(\left(\alpha_{l_{1}}^{h_{1}} ; p\left(\beta_{l_{2}}^{h_{2}} ; \top\right) \neq x_{2} \wedge \ell=0 ; \top\right) \Leftrightarrow\left(\alpha_{l_{1}}^{h_{1}} ; \top\right) \wedge\left(\alpha ; p\left(\beta_{l_{2}}^{h_{2}} ; \top\right) \neq x_{2} \wedge \ell=0 ; \top\right)\right)\)
ITL
\(21 p(\neg(\alpha \wedge(\alpha ; \ell \neq 0) ; \top))=1\)
assumption, PITL6
\(22 p\left(\alpha_{l_{1}}^{h_{1}} ; p\left(\beta_{l_{2}}^{h_{2}} ; \top\right) \neq x_{2} \wedge \ell=0 ; \top\right)=0 \Leftrightarrow\)
\(p\left(\left(\alpha_{l_{1}}^{h_{1}} ; \top\right) \wedge\left(\alpha ; p\left(\beta_{l_{2}}^{h_{2}} ; \top\right) \neq x_{2} \wedge \ell=0 ; \top\right)\right)=0\)
20, 21, PITL9
\(23 \alpha \wedge p\left(\alpha ; \beta_{l_{2}}^{h_{2}} ; \top\right) \neq x_{2} \Rightarrow \neg\left(\alpha ; p\left(\beta_{l_{2}}^{h_{2}} ; \top\right)=x_{2} \wedge \ell=0\right)\)
\(24 \neg\left(\alpha ; p\left(\beta_{l_{2}}^{h_{2}} ; \top\right)=x_{2}\right) \wedge \alpha \Rightarrow\left(\alpha ; p\left(\beta_{l_{2}}^{h_{2}} ; \top\right) \neq x_{2} \wedge \ell=0\right)\)
\(P_{;}^{\prime}\)
\(\alpha \wedge p\left(\alpha ; \beta_{l_{2}}^{h_{2}} ; \top\right) \neq x_{2} \Rightarrow\left(\alpha ; p\left(\beta_{l_{2}}^{h_{2}} ; \top\right) \neq x_{2} \wedge \ell=0\right)\)
ITL
\(26 \quad p\left(\left(\alpha_{l_{1}}^{h_{1}} ; \top\right) \wedge\left(\alpha ; p\left(\beta_{l_{2}}^{h_{2}} ; \top\right) \neq x_{2} \wedge \ell=0 ; \top\right)\right)=0 \Rightarrow\)
\(p\left(\left(\alpha_{l_{1}}^{h_{1}} ; \top\right) \wedge\left(\alpha \wedge p\left(\alpha ; \beta_{l_{2}}^{h_{2}} ; \top\right) \neq x_{2} ; \top\right)\right)=0\)
23, 24

25, PITL9, PITL6
\(27 \neg(\alpha \wedge(\alpha ; \ell \neq 0) ; \top) \Rightarrow\)
\(\left(\left(\alpha_{l_{1}}^{h_{1}} ; \top\right) \wedge\left(\alpha \wedge p\left(\alpha ; \beta_{l_{2}}^{h_{2}} ; \top\right) \neq x_{2} ; \top\right) \Leftrightarrow\left(\alpha_{l_{1}}^{h_{1}} \wedge p\left(\alpha ; \beta_{l_{2}}^{h_{2}} ; \top\right) \neq x_{2} ; \top\right)\right)\)
ITL
\(28 p\left(\left(\alpha_{l_{1}}^{h_{1}} ; \top\right) \wedge\left(\alpha \wedge p\left(\alpha ; \beta_{l_{2}}^{h_{2}} ; \top\right) \neq x_{2} ; \top\right)\right)=0 \Leftrightarrow p\left(\alpha_{l_{1}}^{h_{1}} \wedge p\left(\alpha ; \beta_{l_{2}}^{h_{2}} ; \top\right) \neq x_{2} ; \top\right)=0\)
21, 27, PITL9
\(\ell=0 \wedge p(\alpha ; \beta ; \top)=1 \Rightarrow p\left(\alpha_{l_{1}}^{h_{1}} \wedge p\left(\alpha ; \beta_{l_{2}}^{h_{2}} ; \top\right) \neq x_{2} ; \top\right)=0\)
\(19,22,26,28\)
\(30 \quad \ell=0 \wedge p\left(\alpha_{l_{1}}^{h_{1}} \wedge p\left(\alpha ; \beta_{l_{2}}^{h_{2}} ; \top\right) \neq x_{2} ; \top\right)=0 \Rightarrow\)
\(p\left(\left(\alpha_{l_{1}}^{h_{1}} ; \top\right) \wedge\left(\alpha ; \beta_{l_{2}}^{h_{2}} ; \top\right)\right)=x_{2} . p\left(\alpha_{l_{1}}^{h_{1}} ; \top\right)\)
\(31 \neg(\alpha \wedge(\alpha ; \ell \neq 0) ; \top) \Rightarrow\left(\left(\alpha_{l_{1}}^{h_{1}} ; \top\right) \wedge\left(\alpha ; \beta_{l_{2}}^{h_{2}} ; \top\right) \Leftrightarrow\left(\alpha_{l_{1}}^{h_{1}} ; \beta_{l_{2}}^{h_{2}} ; \top\right)\right)\)
\(32 \quad\left(\alpha_{l_{1}}^{h_{1}} ; \top\right) \wedge\left(\alpha ; \beta_{l_{2}}^{h_{2}} ; \top\right) \Leftrightarrow\left(\alpha_{l_{1}}^{h_{1}} ; \beta_{l_{2}}^{h_{2}} ; \top\right)\)
\(33 p\left(\left(\alpha_{l_{1}}^{h_{1}} ; \top\right) \wedge\left(\alpha ; \beta_{l_{2}}^{h_{2}} ; \top\right)\right)=p\left(\alpha_{l_{1}}^{h_{1}} ; \beta_{l_{2}}^{h_{2}} ; \top\right)\)
\(34 \quad \ell=0 \wedge p(\alpha ; \top)=1 \Rightarrow p\left(\alpha_{l_{1}}^{h_{1}} ; \top\right)=x_{1}\)
\(35 \quad \ell=0 \wedge p(\alpha ; \beta ; \top)=1 \Rightarrow p\left(\alpha_{l_{1}}^{h_{1}} ; \beta_{l_{2}}^{h_{2}} ; \top\right)=x_{2} . x_{1}\)
\(\bar{P}, \underline{P}\), assumptions
ITL
assumption, 31
32, PITL1
\(\left[E T_{\alpha} \in\left[l_{1}, h_{1}\right]\right]_{x_{1}}\)
\(10,29,30,33,34\)```


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[^1]:    ${ }^{1}$ Many authors write chop as $\varphi \frown \psi$ instead of $(\varphi ; \psi)$.

[^2]:    ${ }^{2}$ In practice $F_{m}^{k}$ can be non-monotonic: increasing the execution time of an imported method may indeed shorten the execution time of code which would abort if an imported method misses a deadline.

