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## On a Type of Sasakian Manifold

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In this paper concircularly flat Sasakian manifold and a Sasakian manifold satisfying  $R(X, Y) \cdot C^* = 0$  have been studied.

### Introduction

Let  $M^n$  be a contact Riemannian manifold with a contact form  $\eta$ , the associated vector field  $\xi$ ,  $(1-1)$  tensor field  $\Phi$  and the associated Riemannian metric  $g$ . If  $\xi$  is a Killing vector field, then  $M^n$  is called a  $K$ -contact Riemannian manifold [1], [2]. A  $K$ -contact Riemannian manifold is called Sasakian [2] if

$$(1) \quad (\nabla_X \Phi)(Y) = g(X, Y)\xi - \eta(Y)X,$$

holds, where  $\nabla$  denotes the operator of covariant differentiation with respect to  $g$ . This paper deals with a type of Sasakian manifold in which

$$(2) \quad R(X, Y) \cdot C^* = 0$$

where  $C^*$  is the concircular curvature tensor [3] defined by

$$(3) \quad C^*(X, Y)Z = R(X, Y)Z - \frac{r}{n(n-1)}[g(Y, Z)X - g(X, Z)Y],$$

$R$  is the curvature tensor,  $r$  is the scalar curvature and  $R(X, Y)$  is considered as a derivation of the tensor algebra at each point of the manifold for tangent vectors  $X, Y$ . In this connection we mention the works of K. Sekigawa [4], Z. I. Szabo [5], L. Verstraelen [6], M. Petrovic-Torgasev and L. Verstraelen [7] who studied Riemannian manifolds or hypersurfaces of such manifolds satisfying the conditions similar to it. It is easy to see that  $R(X, Y) \cdot R = 0$  implies  $R(X, Y) \cdot C^* = 0$ . So it is meaningful to undertake the study of manifolds satisfying the condition (2).

In this paper it is proved that if a Sasakian manifold  $M^n (n \geq 2)$  is concircularly flat then it is locally isometric with a unit sphere  $S^n(1)$ . Also it is proved that if in a Sasakian manifold the relation (2) holds, then it is also locally isometric with a unit sphere  $S^n(1)$ .

### 1. Preliminaries

Let  $S$  denotes the Ricci tensor of type (0,2) of  $M^n$ . It is known that in a Sasakian manifold  $M^n$ , besides the relation (1) the following relations hold [1], [2], [8]

$$(1.1) \quad \Phi(\xi) = 0$$

$$(1.2) \quad \eta(\xi) = 1$$

$$(1.3) \quad \Phi^2(X) = -X + \eta(X)\xi$$

$$(1.4) \quad g(\Phi X, \Phi Y) = g(X, Y) - \eta(X)\eta(Y)$$

$$(1.5) \quad g(\xi, X) = \eta(X)$$

$$(1.6) \quad \nabla_X \xi = -\Phi X$$

$$(1.7) \quad S(X, \xi) = (n-1)\eta(X)$$

$$(1.8) \quad g(R(\xi, X)Y, \xi) = g(X, Y) - \eta(X)\eta(Y)$$

$$(1.9) \quad R(\xi, X)\xi = -X + \eta(X)\xi$$

and

$$(1.10) \quad (\nabla_X \Phi)(Y) = R(\xi, X)Y$$

for any vector fields  $X, Y$ .

The above results will be used in the next section.

### 2. Sasakian manifold satisfying $C^*(X, Y)Z = 0$

Let us suppose that in a Sasakian manifold

$$(2.1) \quad C^*(X, Y)Z = 0.$$

Then

$$(2.2) \quad R(X, Y)Z = \frac{r}{n(n-1)} [g(Y, Z)X - g(X, Z)Y]$$

or,

$$(2.3) \quad g(R(X, Y)Z, W) = \frac{r}{n(n-1)} [g(Y, Z)g(X, W) - g(X, Z)g(Y, W)].$$

Putting  $X = W = \xi$  in (2.3) we get

$$g(R(\xi, Y)Z, \xi) = \frac{r}{n(n-1)} [g(Y, Z)g(\xi, \xi) - g(\xi, Z)g(Y, \xi)]$$

or,

$$g(Y, Z) - \eta(Y)\eta(Z) = \frac{r}{n(n-1)} [g(Y, Z) - \eta(Y)\eta(Z)],$$

by (1.8), (1.2), (1.5)  
or,

$$\left[\frac{r}{n(n-1)} - 1\right] [g(Y, Z) - \eta(Y)\eta(Z)] = 0.$$

Then either

$$r = n(n-1) \text{ or, } g(Y, Z) = \eta(Y)\eta(Z).$$

Now if  $g(Y, Z) = \eta(Y)\eta(Z)$ , then from (1.4) we get

$$g(\Phi Y, \Phi Z) = 0$$

which is not possible

Therefore  $r = n(n-1)$ .

Now putting the value of  $r$  in (2.2) we get the manifold is of constant curvature unity. Hence we can state the following theorem:

**Theorem 1.** *A concircularly flat Sasakian manifold  $M^n (n \geq 2)$  is locally isometric with a unit sphere  $S^n(1)$ .*

### 3. Sasakian manifold satisfying $R(X, Y) \cdot C^* = 0$

We have

$$\begin{aligned} \eta(C^*(X, Y)Z) &= g(C^*(X, Y)Z, \xi) \\ &= g(R(X, Y)Z - \frac{r}{n(n-1)} [g(Y, Z)X - g(X, Z)Y], \xi) \\ &= -[\eta(Y)g(Z, X) - \eta(X)g(Z, Y)] \\ &\quad - \frac{r}{n(n-1)} [\eta(X)g(Y, Z) - \eta(Y)g(X, Z)], \end{aligned}$$

by (1.5), (1) and (1.10)  
or,

$$(3.1) \quad \eta(C^*(X, Y)Z) = \left[\frac{r}{n(n-1)} - 1\right] [\eta(Y)g(Z, X) - \eta(X)g(Z, Y)].$$

Putting  $X = \xi$  in (3.1) we get

$$(3.2) \quad \eta(C^*(\xi, Y)Z) = \left[\frac{r}{n(n-1)} - 1\right] [\eta(Z)\eta(Y) - g(Y, Z)].$$

Again putting  $Z = \xi$  in (3.1) we get

$$(3.3) \quad \eta(C^*(X, Y)\xi) = 0.$$

Now

$$(R(X, Y) \cdot C^*)(U, V)W = R(X, Y)C^*(U, V)W - C^*(R(X, Y)U, V)W \\ - C^*(U, R(X, Y)V)W - C^*(U, V)R(X, Y)W.$$

In virtue of (2) we get

$$(3.4) \quad R(X, Y)C^*(U, V)W - C^*(R(X, Y)U, V)W - C^*(U, R(X, Y)V)W \\ - C^*(U, V)R(X, Y)W = 0.$$

Therefore

$$g[R(\xi, Y)C^*(U, V)W, \xi] - g[C^*(R(\xi, Y)U, V)W, \xi] \\ - g[C^*(U, R(\xi, Y)V)W, \xi] - g[C^*(U, V)R(\xi, Y)W, \xi] = 0.$$

From this it follows that

$$(3.5) \quad C^*(U, V, W, Y) - \eta(Y)\eta(C^*(U, V)W) + \eta(U)\eta(C^*(Y, V)W) \\ + \eta(V)\eta(C^*(U, Y)W) + \eta(W)\eta(C^*(U, V)Y) - g(Y, U)\eta(C^*(\xi, V)W) \\ - g(Y, V)\eta(C^*(U, \xi)W) - g(Y, W)\eta(C^*(U, V)\xi) = 0,$$

where  $g(C^*(U, V)W, Y) = C^*(U, V, W, Y)$ .

Putting  $Y = U$  in (3.5) we get

$$(3.6) \quad C^*(U, V, W, U) - \eta(U)\eta(C^*(U, V)W) + \eta(U)\eta(C^*(U, V)W) \\ + \eta(V)\eta(C^*(U, U)W) + \eta(W)\eta(C^*(U, V)U) - g(U, U)\eta(C^*(\xi, V)W) \\ - g(U, V)\eta(C^*(U, \xi)W) - g(U, W)\eta(C^*(U, V)\xi) = 0.$$

Let  $\{e_i\}$ ,  $i = 1, 2, \dots, n$  be an orthonormal basis of the tangent space at any point. Then the sum for  $1 \leq i \leq n$  of the relation (3.6) for  $U = e_i$  gives

$$(3.7) \quad \eta(C^*(\xi, V)W) = \frac{1}{n-1} [S(V, W) - \frac{r}{n}g(V, W) \\ + (\frac{r}{n(n-1)} - 1)(n-1)\eta(W)\eta(V)].$$

Using (3.1) and (3.7) it follows from (3.5) that

$$(3.8) \quad C^*(U, V, W, Y) + \frac{r}{n(n-1)}g(Y, U)g(V, W) - \frac{r}{n(n-1)}g(U, W)g(Y, V) \\ - \frac{1}{(1-n)}[S(U, W)g(Y, V) - S(V, W)g(Y, U)] = 0.$$

From (3.2) and (3.7) we get

$$(3.9) \quad S(Y, Z) = (n-1) [g(Y, Z)].$$

Using (3.9), the relation (3.8) reduces to

$$(3.10) \quad 'C^*(U, V, W, Y) = \left[ \frac{r}{n(n-1)} - 1 \right] [g(Y, V)g(U, W) - g(Y, U)g(V, W)].$$

From (3) and (3.10) we get

$$(3.11) \quad 'R(U, V, W, Y) = [g(Y, U)g(V, W) - g(Y, V)g(U, W)],$$

where

$$'R(U, V, W, Y) = g(R(U, V)W, Y).$$

Hence we can state the following theorem:

**Theorem 2.** *If in a Sasakian manifold  $M^n (n \geq 2)$  the relation  $R(X, Y) \cdot C^* = 0$  holds, then it is locally isometric with a unit sphere  $S^n$  (1).*

For a concircularly symmetric Riemannian manifold we have  $\nabla C^* = 0$ . Hence for such a manifold  $R(X, Y) \cdot C^* = 0$  holds. Thus we have the following Corollary of the above theorem:

**Corollary.** *A concircularly symmetric Sasakian manifold  $M^n (n \geq 2)$  is locally isometric with a unit sphere  $S^n$  (1).*

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