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On a Nonlocal Boundary Value Problem for a Quasilinear Equation of Mixed Type

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Using the Faedo - Galerkin method we prove the existence of a generalized solution of a nonlocal boundary-value problem for one second order quasilinear equation of mixed type in a bounded multidimensional cylindrical domain.

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1. Introduction

Let D be a bounded domain in the space \mathbf{R}^{m-1} of points $x^{'}=(x_1,\ldots,x_{m-1})$, where $m\geq 2$ is an integer. Let $G=\{x=(x^{'},x_m)\in\mathbf{R}^m:x^{'}\in D,\,0< x_m< h\},\,S=\{x\in\mathbf{R}^m:x^{'}\in\partial D,0< x_m< h\},h=const,\,S\in C^1.$

We consider the operator

$$\mathcal{L}u = \sum_{i,j=1}^{m-1} a_{ij}(x)u_{x_ix_j} + k(x)u_{x_mx_m} + \sum_{i=1}^m b_i(x)u_{x_i} + c(x)u - u|u|^{\rho} - f(x,u) ,$$

where
$$a_{ij} \in C^2(\overline{G})$$
, $a_{ij} = a_{ji}$ for $i, j = 1, ..., m - 1$;
$$\sum_{i,j=1}^{m-1} a_{ij}(x)\xi_i\xi_j \ge a_0 \sum_{i=1}^{m-1} \xi_i^2$$
, $\forall x \in \overline{G} \text{ and } \forall \xi' \in \mathbf{R}^{m-1}$, $a_0 = const > 0$; $k \in C^2(\overline{G})$, $k(x', 0) = k(x', h) = 0$ $\forall x' \in \overline{D}$; $c, b_i \in C^1(\overline{G})$ for $i = 1, ..., m$; $\rho = const > 0$. The function $f(x, t)$

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is defined in $G \times \mathbf{R}$ and $f \in \mathbf{CAR}$, i.e. f(x,t) is continuous with respect to t for almost every $x \in G$ and it is measurable with respect to x in G for every $t \in \mathbf{R}$ (see [5], 12.2). All the functions in this paper are real-valued.

The operator \mathcal{L} is elliptic, hyperbolic, parabolic at a point $x \in G$, if k(x) > 0, k(x) < 0, k(x) = 0 respectively. In our case \mathcal{L} is an operator of mixed type in G, because there are no restrictions on the sign of k(x) for $x \in G$.

We consider the following boundary value problem:

Find a function u(x) in \overline{G} such that

$$\mathcal{L}u=0 \text{ in } G,$$

(2)
$$u = 0 \text{ on } S, \ u(x',h) = \lambda u(x',0) \text{ in } D,$$

where $\lambda \neq 0$ is a given real constant.

A nonlocal problem for the linear equation

$$\mathcal{L}u = \sum_{i,j=1}^{m-1} a_{ij}(x)u_{x_ix_j} + k(x)u_{x_mx_m} + \sum_{i=1}^m b_i(x)u_{x_i} + c(x)u = f(x),$$

where k(x',0)=k(x',h)=0 $\forall x'\in \overline{D}$, with the boundary conditions (2) is investigated in [4] for $0<\lambda\leq 1$, in [7,8] for $0<|\lambda|<1$, in [9] for $\lambda\neq 0$. This problem is investigated also in [17] in the case where $-1<\lambda\leq 1$, $a_{ij}(x)=\delta_i^j$, δ_i^j is the Kronecker's symbol, $b_i=0$, $i,j=1,\ldots,m-1$, $k=k(x_m)$ and $k(h)\geq 0\geq k(0)$.

Nonlocal boundary value problems for different nonlinear equations of second order of mixed type are considered in [4], [6].

Let $Z = W_2^1(G) \cap L_{\rho+2}(G)$ be the linear normed space with a norm

(3)
$$||u|| = (||u||_{W_2^1(G)}^2 + ||u||_{L_{p+2}(G)}^2)^{1/2},$$

where $||v||_{L_r(G)} = (\int_G |v|^r dx)^{1/r}$, $1 \leq r < \infty$, and $||u||_{W_2^1(G)} = [\int_G (u^2 + \sum_{i=1}^m u_{x_i}^2) dx]^{1/2}$ are the norms in $L_r(G)$ and in the Sobolev space $W_2^1(G)$, respectively. Let X be the closure in the norm (3) of the set $\tilde{C}^2 = \{u \in C^2(\bar{G}) : u \text{ satisfies } (2)\}$ and let Y be the closure in the norm (3) of the set of all functions belonging to $C^2(\bar{G})$ and vanishing on S. In the sequel we suppose that $f(x, u(x)) \in L_2(G) \ \forall u \in L_{\rho+2}(G)$ and that for some constants $F_1 > 0, F_2 > 0, \sigma > 1$ the inequality

(4)
$$||f(x,u)||_{L_2(G)}^2 \le F_1 + F_2 ||u||_{L_{\rho+2}(G)}^{(\rho+2)/\sigma}$$

holds for every $u \in L_{\rho+2}(G)$. It is not difficult to establish (4), using 12.4 and 12.11 from [5] and the imbedding $L_{2\sigma}(G) \hookrightarrow L_2(G)$ (see [1]), if for example $\kappa \in L_{2\sigma}(G)$ and $F_0 = const \geq 0$ exist such that $|f(x,t)| \leq \kappa(x) + F_0|t|^{(\rho+2)/2\sigma}$ for almost every $x \in G$ and for every $t \in \mathbb{R}$. Since $u|u|^{\rho} \in L_{\eta}(G)$ for $u \in L_{\rho+2}(G)$ with $\eta = (\rho+2)/(\rho+1)$ where $\rho > 0$, then for $u, v \in Z$ we denote

$$B[u,v] \equiv -\int_{G} [(kv)_{x_{m}} u_{x_{m}} + \sum_{i,j=1}^{m-1} (a_{ij}v)_{x_{j}} u_{x_{i}}] dx$$

$$+ \int_{G} [\sum_{i=1}^{m} b_{i} u_{x_{i}} + cu - u |u|^{\rho} - f(x,u)] v dx.$$
(5)

Definition. A function u(x) is called a generalized solution of problem (1), (2), if $u \in X$ and

(6)
$$B[u,v] = 0 \ \forall v \in Y.$$

The main result in this paper is the following theorem.

Theorem 1. Let $k(x',x_m) > 0$ for $x' \in \bar{D}$ and $h_+ \leq x_m < h$ where $h_+ = const$, $0 < h_+ < h$; $a_{ij}(x',h) = a_{ij}(x',0)$ in \bar{D} , $i,j=1,\ldots,m-1$; c(x) = -M+g(x), where M = const > 0 and g(x) does not depend on M; $2b_m-k_{x_m} > 0$ in $G_0 = \{x \in \bar{G} : k(x) = 0\}$; and (4) be satisfied. Then a positive constant \bar{M} exists such that problem (1), (2) has a generalized solution for every $M \geq \bar{M}$.

Sections 2 and 3 of this paper contain some preliminary results. The proof of Theorem 1 is given in Section 4. It consists of three steps: 1) using the Faedo - Galerkin method we construct a sequence belonging to the Banach space X, which sequence is bounded in the norm (3); 2) that implies the existence of a subsequence weakly convergent in X to a function $u \in X$; 3) taking a limit in some integral equalities for this subsequence, we obtain (6).

Similar schemes of proofs are used for local boundary-value problems for quasilinear equations of mixed type in [2, 3, 15], for a nonlinear degenerating hyperbolic equation in [16], for quasilinear hyperbolic - parabolic equations in [12, 14] and others.

Some of the results of the present paper are published without proofs in [10].

2. Preliminary results

Lemma 1. i) Z is a Banach, separable and reflexive space.

ii) The spaces X and Y with the norm (3) are Banach, separable and reflexive.

Proof. i) The spaces $W_2^1(G)$ and $L_{\rho+2}(G)$ are Banach ones and $L_{\rho+2}(G)\hookrightarrow L_2(G)$ for $\rho>0$ (see [1]). Then Z also is a Banach space. Let $V=\{w=(w_0,w_1,\ldots,w_m,w_{m+1}): w_j\in L_2(G),\ j=0,1,\ldots,m,\ w_{m+1}\in L_{\rho+2}(G)\}$. Then V is a separable and reflexive Banach space with a norm $\|w\|_V=(\sum_{j=0}^m\|w_j\|_{L_2(G)}^2+\|w_{m+1}\|_{L_{\rho+2}(G)}^2)^{1/2}$ ([1], 1.22). From the imbedding $L_{\rho+2}(G)\hookrightarrow L_2(G)$ for $\rho>0$ and the definition of a generalized derivative (see [1]) it follows that the space $\tilde{V}=\{(v,v_{x_1},\ldots,v_{x_m},v):\ v\in Z\}$ is a closed subspace of V. Therefore \tilde{V} is a separable and reflexive Banach space under the norm $\|.\|_V$ ([1], 1.21). Let consider the linear one-to-one mapping $\mathcal{M}:\ Z\to \tilde{V}$ such that $\mathcal{M}v=(v,v_{x_1},\ldots,v_{x_m},v)\ \forall v\in Z$. From (3) it follows $\|\mathcal{M}v\|_V=\|v\|\ \forall v\in Z$. Hence Z is a separable and reflexive space.

ii) The proof is a consequence of i) and the fact that X and Y are closed subspaces of Z.

Lemma 2. A countable linearly independent set \mathbb{R} , consisting of functions from $C^2(\bar{G})$ vanishing on S, exists such that its linear span is dense in Y.

Proof. Let the set $\{v_j\}_{j=1}^{\infty} \subset Y$ be dense in Y. Let $\varepsilon_n > 0 \ \forall n \in \mathbb{N}$ and $\varepsilon_n \underset{n \to \infty}{\longrightarrow} 0$. For $j, n \in \mathbb{N}$ a function $\varphi_{jn} \in C^2(\bar{G})$, $\varphi_{jn}|_S = 0$, exists such that $\|v_j - \varphi_{jn}\| < \varepsilon_n$. Let $v \in Y$ and $\delta > 0$. We take $\varepsilon_{n_{\delta}} < \frac{\delta}{2}$ and $v_{j_{\delta}}$ with the properties $j_{\delta}, n_{\delta} \in \mathbb{N}$, $\|v - v_{j_{\delta}}\| < \frac{\delta}{2}$. Then $\|v - \varphi_{j_{\delta}n_{\delta}}\| \leq \|v - v_{j_{\delta}}\| + \|v_{j_{\delta}} - \varphi_{j_{\delta}n_{\delta}}\| < \frac{\delta}{2} + \varepsilon_{n_{\delta}} < \delta$. Arranging the countable set $\{\varphi_{jn}\}_{j,n=1}^{\infty}$ in a sequence ψ_1, ψ_2, \ldots we see that it is dense in Y and $\psi_j \in C^2(\bar{G}), \psi_j|_S = 0 \ \forall j \in \mathbb{N}$.

Let now Φ_1 be the first element of the sequence $\{\psi_j\}_{j=1}^{\infty}$ which is not equal to zero in \bar{G} . Let Φ_2 be the next element of $\{\psi_j\}_{j=1}^{\infty}$ such that Φ_1 and Φ_2 are linearly independent in \bar{G} . Let Φ_3 be the next element of $\{\psi_j\}_{j=1}^{\infty}$ such that Φ_1 , Φ_2 and Φ_3 are linearly independent in \bar{G} and so on. The set $\mathcal{R} = \{\Phi_1, \Phi_2, \Phi_3, \ldots\}$ is the needed because: 1) $\Phi_j \in C^2(\bar{G})$, $\Phi_j|_S = 0 \ \forall j \in \mathbb{N}$, 2) \mathcal{R} is an infinite, countable, linearly independent set, 3) the linear span of \mathcal{R} is dense in Y.

Lemma 3. ([13], Ch. 1, Lemma 1.3) If $\{w_r\}_{r=1}^{\infty}$ is a bounded sequence in $L_{\eta}(G)$, $1 < \eta < +\infty$, $w \in L_{\eta}(G)$ and $w_r \xrightarrow{r \to \infty} w$ almost everywhere in G, then $w_r \xrightarrow{r \to \infty} w$ weakly in $L_{\eta}(G)$.

On a Nonlocal Boundary Value Problem ...

Lemma 4. Let $u_1, u_2, \ldots, u_n \in \tilde{C}^2$, $\varphi \in C^2(\bar{G})$, $\varphi|_S = 0$. Let $\{\overrightarrow{\gamma}^r\}_{r=1}^{\infty} \in \mathbb{R}^n \text{ be convergent to } \overrightarrow{\gamma}^0 \in \mathbb{R}^n \text{ in the norm } |\overrightarrow{\gamma}| = [\sum_{s=1}^n (\gamma_s)^2]^{1/2}$ where $\overrightarrow{\gamma} = (\gamma_1, \ldots, \gamma_n)$. Then,

(7)
$$B\left[\sum_{s=1}^{n} \gamma_{s}^{r} u_{s}, \varphi\right] \underset{r \to \infty}{\longrightarrow} B\left[\sum_{s=1}^{n} \gamma_{s}^{0} u_{s}, \varphi\right].$$

Proof. We set $w_r(x) = \sum_{s=1}^n \gamma_s^r u_s(x)$ for $r \in \mathbb{N} \cup \{0\}$ and $\eta = \frac{\rho+2}{\rho+1}$, where $\rho > 0$. Using the Minkowski and Hölder inequalities we obtain

$$||w_{r}|w_{r}|^{\rho}||_{L_{\eta}(G)} = ||w_{r}||_{L_{\rho+2}(G)}^{\rho+1} \le \left(\sum_{s=1}^{n} |\gamma_{s}^{r}|||u_{s}||_{L_{\rho+2}(G)}\right)^{\rho+1}$$

$$\le c_{1}|\overrightarrow{\gamma}^{r}|^{\rho+1} \le c_{2}, \quad \forall r \in \mathbb{N},$$

because the convergent sequence $\{\overrightarrow{\gamma}^r\}_{r=1}^{\infty}$ is bounded. Here c_1 and c_2 are positive constants nondepending on $r \in \mathbb{N}$. Clearly $w_r(x) \underset{r \to \infty}{\longrightarrow} w_0(x) \ \forall x \in \overline{G}$. Then Lemma 3 implies

(8)
$$w_r |w_r|^{\rho} \underset{r \to \infty}{\longrightarrow} w_0 |w_0|^{\rho} \text{ weakly in } L_{\eta}(G).$$

The Minkowski inequality and the boundness of the sequence $\{\overrightarrow{\gamma}^r\}_{r=1}^{\infty}$, from (4), are used to get $\|f(x,w_r)\|_{L_2(G)}^2 \leq c_3 \ \forall r \in \mathbb{N}$. Since $1 < \eta < 2$, it follows that $\|f(x,w_r)\|_{L_\eta(G)} \leq c_4 \ \forall r \in \mathbb{N}$, where $c_4 = const > 0$ does not depend on $r \in \mathbb{N}$. The property $f \in \mathbf{CAR}$ implies $f(x,w_r(x)) \underset{r \to \infty}{\longrightarrow} f(x,w_0(x))$ for almost every $x \in G$. Then, inview of Lemma 3,

(9)
$$f(x, w_r(x)) \to f(x, w_0(x)) \text{ weakly in } L_\eta(G).$$

The convergences (8) and (9) and the fact that $w_r \underset{r \to \infty}{\longrightarrow} w_0$, $\frac{\partial w_r}{\partial x_i} \underset{r \to \infty}{\longrightarrow} \frac{\partial w_0}{\partial x_i}$ in $L_2(G)$, $i = 1, \ldots, m$, imply (7).

We denote $\mathcal{P}(x_m)=(x_m^2-2hx_m+\delta)\exp(-\nu h),$ where $\nu=const>0$ is such that

(10)
$$\min(\lambda^2, |\lambda|^{\rho+2}) > \exp(-\nu h)$$

and the constant δ satisfies the inequalities

(11)
$$\min[\alpha(|\lambda|^{\rho+2}), \alpha(\lambda^2)] > \delta > h^2$$

with $\alpha(y) = h^2 y (y - \exp(-\nu h))^{-1}, y \neq \exp(-\nu h)$. Let $\mu = const > 0, \psi \in C^2(\bar{G}), \ \psi(x) = 0 \text{ for } x \in G_0 \cup G_- \text{ and } \psi(x) > 0 \text{ for } x \in G_+, \text{ where } G_+ = \{x \in \bar{G} : k(x) > 0\}, \ G_- = \{x \in \bar{G} : k(x) < 0\}.$ We denote $p(x_m) = \mathcal{P}(x_m) \exp(\nu x_m), \ q(x) = -\mu \psi(x) \exp(\nu x_m) \text{ and } l(u) \equiv p(x_m) \frac{\partial u}{\partial x_m} + q(x)u.$

Lemma 5. Let $\nu > 0$ satisfying (10) be fixed and $k(x', x_m) > 0$ for $x' \in \bar{D}$ and $h_+ \leq x_m < h$, where $0 < h_+ < h$. Let $\mu > \frac{\lambda}{H_0}$, if $\lambda > 1$, where $H_0 = \min_{x' \in \bar{D}} \int_{h_+}^{h} \frac{\psi(x', t)}{\mathcal{P}(t)} dt$. Then for every $\varphi \in C^2(\bar{G})$, which vanishes on S, there exists a unique function $u_{\varphi} \in \tilde{C}^2$ such that

$$l(u_{\varphi}) \equiv p \frac{\partial u_{\varphi}}{\partial x_m} + q u_{\varphi} = \varphi$$
 in G .

Remark . Obviously $\mathcal{P}(x_m) \geq (\delta - h^2) \exp(-\nu h) > 0 \ \forall x_m$. Hence $H_0 > 0$.

Proof. Under our assumptions for μ we get for every $x' \in \bar{D}$

$$-\lambda + \exp(\int_0^h \frac{\mu \psi(x',t)}{\mathcal{P}(t)} dt) \ge -\lambda + \exp(\mu H_0) \ge -\lambda + 1 + \mu H_0 > 0.$$

Then one can verify that the function

$$u_{\varphi}(x', x_m) = \left\{ \int_0^{x_m} \frac{\varphi(x', \theta)}{\mathcal{P}(\theta) \exp(\nu \theta)} \exp\left(\int_{\theta}^0 \frac{\mu \psi(x', t)}{\mathcal{P}(t)} dt\right) d\theta - \left[\int_0^h \frac{\varphi(x', \theta)}{\mathcal{P}(\theta) \exp(\nu \theta)} \exp\left(\int_{\theta}^h \frac{\mu \psi(x', t)}{\mathcal{P}(t)} dt\right) d\theta\right] \left[-\lambda + \exp\left(\int_0^h \frac{\mu \psi(x', t)}{\mathcal{P}(t)} dt\right)\right]^{-1} \exp\left(\int_0^{x_m} \frac{\mu \psi(x', t)}{\mathcal{P}(t)} dt\right)$$

possesses the needed properties. Let u_{φ} , \tilde{u}_{φ} be two functions with these properties and $U=u_{\varphi}-\tilde{u}_{\varphi}$. Then $U\in \tilde{C}^2$ and l(U)=0 in G, i.e. for fixed $x'\in D$

$$\frac{\partial U}{\partial x_m} - \frac{\mu \psi(x', x_m)}{\mathcal{P}(x_m)} U = 0, \ 0 < x_m < h; \ U(x', h) = \lambda U(x', 0).$$

Solving this nonlocal problem we find

$$U(x', x_m) = C(x') \exp(\int_0^{x_m} \frac{\mu \psi(x', t)}{\mathcal{P}(t)} dt), \ 0 \le x_m \le h,$$

where the constant C(x') satisfies

$$C(x')[-\lambda + \exp(\int_0^h \frac{\mu \psi(x',t)}{\mathcal{P}(t)} dt)] = 0.$$

Hence C(x') = 0 and $u_{\varphi} = \tilde{u}_{\varphi}$ in \bar{G} .

3. An a-priori estimate

Lemma 6. Let the assumptions of Theorem 1 hold. Then, with the notations introduced before in Lemma 5, constants $\nu > 0$ and $\mu > 0$ satisfying the conditions of Lemma 5 exist such that the a-priory estimate

(12)
$$B[u,l(u)] \ge \beta_1 ||u||_{W_2^1(G)}^2 + \beta_2 ||u||_{L_{\rho+2}(G)}^{\rho+2} - \beta_3$$

takes place $\forall u \in \tilde{C}^2$ and $\forall M \geq \bar{M}(\nu, \mu)$, where $\beta_1, \beta_2, \beta_3$ are positive constants nondepending on u.

Proof. Taking v = l(u) in (5) for $u \in \tilde{C}^2$ and integrating by parts in B[u, l(u)], we get

$$B[u,l(u)] = \int_{G} [-(kp)_{x_{m}} - kq + b_{m}p] u_{x_{m}}^{2} dx$$

$$- \int_{G} kpu_{x_{m}x_{m}} u_{x_{m}} dx + \int_{G} pu_{x_{m}} \sum_{j=1}^{m-1} (-\sum_{i=1}^{m-1} a_{ijx_{i}}) u_{x_{j}} dx - \int_{G} p \sum_{i,j=1}^{m-1} a_{ij} u_{x_{i}x_{m}} u_{x_{j}} dx$$

$$- \int_{G} q \sum_{i,j=1}^{m-1} a_{ij} u_{x_{i}} u_{x_{j}} dx - \int_{G} (M - g) q u^{2} dx$$

$$+ \int_{G} [b_{m}q - (kq)_{x_{m}} - (M - g)p] u_{x_{m}} u dx$$

$$+ \int_{G} q u \sum_{j=1}^{m-1} (b_{j} - \sum_{i=1}^{m-1} a_{ijx_{i}}) u_{x_{j}} dx$$

$$- \int_{G} u \sum_{i,j=1}^{m-1} a_{ij} q_{x_{i}} u_{x_{j}} dx - \int_{G} q |u|^{\rho+2} dx$$

$$-\int_{G} p|u|^{\rho} u u_{x_{m}} dx - \int_{G} f(x,u)(p u_{x_{m}} + q u) dx = \sum_{s=1}^{12} I_{s}.$$

Integrating by parts and using (2), (10) and (11) we have

$$I_4 = \frac{1}{2} \int_D \sum_{i,j=1}^{m-1} a_{ij}(x',0) u_{x_i}(x',0) u_{x_j}(x',0) [p(0) - \lambda^2 p(h)] dx'$$

$$+\frac{1}{2}\int_{G}\sum_{i,j=1}^{m-1}(a_{ij}p)_{x_{m}}u_{x_{i}}u_{x_{j}}\,dx\geq\frac{1}{2}\int_{G}\sum_{i,j=1}^{m-1}(a_{ij}p)_{x_{m}}u_{x_{i}}u_{x_{j}}\,dx,$$

$$I_2 = \frac{1}{2} \int_C (kp)_{x_m} u_{x_m}^2 \, dx.$$

The zeroes of $Q(t)=t^2+2(\frac{1}{\nu}-h)t+\delta-\frac{2h}{\nu}$ are $t_1=h-\frac{1}{\nu}-\sqrt{\mathcal{D}}$ and $t_2=h-\frac{1}{\nu}+\sqrt{\mathcal{D}}$, where $\mathcal{D}=\frac{1}{\nu^2}+h^2-\delta$. Let $\bar{\nu}=\max[\frac{2}{(h-h_+)},\frac{6}{h\lambda^2},-\frac{1}{h}\ln(\min(\lambda^2,|\lambda|^{\rho+2}))]$ and $\nu>\bar{\nu}$. Then (10) holds and from (11) it follows

(14)
$$h^{2} < \delta < h^{2} \lambda^{2} (\lambda^{2} - \exp(-\nu h))^{-1}.$$

Since $\exp(\nu h) > 1 + \nu h + 2^{-1}\nu^2 h^2 + 6^{-1}\nu^3 h^3$, then $\lambda^2 \exp(\nu h) - 1 > \nu^2 h^2$. Hence $h^2 \lambda^2 (\lambda^2 - \exp(-\nu h))^{-1} < h^2 + \nu^{-2}$ and from (14) follows that $0 < \mathcal{D} < \nu^{-2}$. Thus $h_+ < h - \frac{2}{\nu} < t_1 < t_2 < h \ \forall \nu > \bar{\nu}$. Since $Q(h) = \delta - h^2 > 0$, then

$$\nu \mathcal{P}(t) + \mathcal{P}'(t) = \nu \exp(-\nu h)Q(t) < 0 \text{ for } t_1 < t < t_2 \text{ and } \nu > \bar{\nu}.$$

Therefore for every $\nu > \bar{\nu}$ a constant $\bar{\mu}(\nu) > 0$ exists with the property $p'(x_m) - 2q(x) > 0$ in $\bar{G} \ \forall \mu > \bar{\mu}(\nu)$.

In the same way as in the proof of Theorem 1 in [9], we show that for some $\bar{\bar{\nu}}=const>0$ and for arbitrary fixed $\nu>\bar{\bar{\nu}}$ a constant $\bar{\bar{\mu}}(\nu)>0$ can be found such that for every $\mu>\bar{\bar{\mu}}(\nu)$

(15)
$$\sum_{s=1}^{5} I_s \ge \int_G p(\tilde{c}_1 u_{x_m}^2 + \tilde{c}_2 \sum_{i=1}^{m-1} u_{x_i}^2) dx,$$

where $\tilde{c}_1 = \tilde{c}_1(\mu, \nu) > 0$, $\tilde{c}_2 = \tilde{c}_2(\nu) > 0$.

Since k(x',0) = k(x',h) = 0 in \bar{D} , then q(x',0) = q(x',h) = 0 in \bar{D} . Integrating by parts and using (2), we obtain

$$I_7 = \frac{1}{2} \int_G [(M-g)p - b_m q + (kq)_{x_m}]_{x_m} u^2 dx + \frac{1}{2} \int_D \{ [p(0)]_{x_m} (M-g)p - b_m q + (kq)_{x_m} \}_{x_m} u^2 dx + \frac{1}{2} \int_D \{ [p(0)]_{x_m} (M-g)p - b_m q + (kq)_{x_m} \}_{x_m} u^2 dx + \frac{1}{2} \int_D \{ [p(0)]_{x_m} (M-g)p - b_m q + (kq)_{x_m} \}_{x_m} u^2 dx + \frac{1}{2} \int_D \{ [p(0)]_{x_m} (M-g)p - b_m q + (kq)_{x_m} \}_{x_m} u^2 dx + \frac{1}{2} \int_D \{ [p(0)]_{x_m} (M-g)p - b_m q + (kq)_{x_m} \}_{x_m} u^2 dx + \frac{1}{2} \int_D \{ [p(0)]_{x_m} (M-g)p - b_m q + (kq)_{x_m} \}_{x_m} u^2 dx + \frac{1}{2} \int_D \{ [p(0)]_{x_m} (M-g)p - b_m q + (kq)_{x_m} \}_{x_m} u^2 dx + \frac{1}{2} \int_D \{ [p(0)]_{x_m} (M-g)p - b_m q + (kq)_{x_m} \}_{x_m} u^2 dx + \frac{1}{2} \int_D \{ [p(0)]_{x_m} (M-g)p - b_m q + (kq)_{x_m} \}_{x_m} u^2 dx + \frac{1}{2} \int_D \{ [p(0)]_{x_m} (M-g)p - b_m q + (kq)_{x_m} \}_{x_m} u^2 dx + \frac{1}{2} \int_D \{ [p(0)]_{x_m} (M-g)p - b_m q + (kq)_{x_m} \}_{x_m} u^2 dx + \frac{1}{2} \int_D \{ [p(0)]_{x_m} (M-g)p - b_m q + (kq)_{x_m} \| ($$

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$$-\lambda^{2} p(h) M + [\lambda^{2} p(h) g(x', h) - p(0) g(x', 0)] u^{2}(x', 0) dx',$$

$$I_{8} = -\frac{1}{2} \int_{G} u^{2} \sum_{j=1}^{m-1} (q b_{j} - \sum_{i=1}^{m-1} a_{ijx_{i}} q)_{x_{j}} dx,$$

$$I_{9} = \frac{1}{2} \int_{G} u^{2} \sum_{i,j=1}^{m-1} (a_{ij} q_{x_{i}})_{x_{j}} dx.$$

We fix $\nu > \max(\bar{\nu}, \ \bar{\nu})$ and $\mu > \max(\bar{\mu}(\nu), \ \bar{\mu}(\nu))$. Then a constant $\bar{M}(\nu, \mu) > 0$ exists such that

$$\sum_{s=6}^{9} I_s = \frac{1}{2} M \{ \int_G (p' - 2q) u^2 dx + \int_D [p(0)] dx \}$$

$$-\lambda^2 p(h) [u^2(x', 0)] dx' \} + \tilde{I} \ge \tilde{c}_3 \int_G p u^2 dx$$
(16)

 $\forall M > \bar{M}(\nu,\mu)$, where $\tilde{c}_3 = \tilde{c}_3(\mu,\nu,M) > 0$. Let us note that in (16) the term \tilde{I} does not depend on M.

Further, using (2), (10) and (11) we find

$$I_{11} = -\frac{1}{\rho+2} \int_{G} p \frac{\partial}{\partial x_{m}} (|u|^{\rho+2}) dx = \frac{1}{\rho+2} \{ \int_{G} p' |u|^{\rho+2} dx + \int_{D} |u(x',0)|^{\rho+2} [p(0) - |\lambda|^{\rho+2} p(h)] dx' \} \ge \frac{1}{\rho+2} \int_{G} p' |u|^{\rho+2} dx.$$

Obviously $p'(x_m) - (\rho + 2)q(x) \ge p'(x_m) - 2q(x)$ in \bar{G} . Then for $\nu > \max(\bar{\nu}, \bar{\nu})$ and $\mu > \max(\bar{\mu}(\nu), \bar{\mu}(\nu))$ the estimate

(17)
$$I_{10} + I_{11} \ge \tilde{c}_4 \int_G |u|^{\rho+2} dx$$

holds with $\tilde{c}_4 = \tilde{c}_4(\mu, \nu) > 0$.

Using the Hölder inequality, the inequality $|ab| \leq \frac{\varepsilon}{r} |a|^r + \frac{1}{r'} \varepsilon^{\frac{-r'}{r}} |b|^{r'}$ with $\varepsilon > 0$, $a, b \in \mathbb{R}$, r > 1, $\frac{1}{r} + \frac{1}{r'} = 1$, and the inequality (4), we obtain

(18)
$$\int_{G} |f(x,u)| (|pu_{x_{m}}| + |qu|) dx \leq \left(\frac{\tilde{c}_{5}F_{2}}{\varepsilon_{1}}\right)^{\sigma'} \frac{1}{\sigma'} \varepsilon_{2}^{\frac{-\sigma'}{\sigma'}} + \frac{\tilde{c}_{5}F_{1}}{\varepsilon_{1}} + \frac{\varepsilon_{2}}{\sigma} \int_{G} |u|^{\rho+2} dx + \frac{\varepsilon_{1}}{2} \int_{G} (u_{x_{m}}^{2} + u^{2}) dx ,$$

where $\varepsilon_1>0,\ \varepsilon_2>0,\ \frac{1}{\sigma'}+\frac{1}{\sigma}=1,\ \tilde{c}_5>0$ depends only on p and q.

Thus for $\nu > \max(\bar{\nu}, \bar{\nu})$, $\mu > \max(\bar{\mu}(\nu), \bar{\mu}(\nu))$ and $M \geq \bar{M}(\nu, \mu)$ from (13) and (15) - (18), with ε_1 , ε_2 sufficiently small, it follows the estimate (12).

4. Proof of Theorem 1

Lemma 5 implies the existence of a function $u_j \in \tilde{C}^2$ such that

(19)
$$l(u_j) \equiv p \frac{\partial u_j}{\partial x_m} + q u_j = \Phi_j \text{ in } G$$

for j=1,2,..., where the set $\{\Phi_j\}_{j=1}^{\infty}=\mathcal{R}$ is given in Lemma 2. We consider the nonlinear algebraic system

(20)
$$B[\sum_{r=1}^{n} \gamma_r u_r, \ \Phi_i] = 0, \ i = 1, 2, ..., n.$$

where the real constants $\gamma_1, \ldots, \gamma_n$ are unknown. Let

(21)
$$|||\overrightarrow{\gamma}||| = ||\sum_{r=1}^{n} \gamma_r u_r||_{L_{\rho+2}(G)},$$

where $\overrightarrow{\gamma} = (\gamma_1, \dots, \gamma_n)$. We have $l(\sum_{r=1}^n \gamma_r u_r) = \sum_{r=1}^n \gamma_r \Phi_r$ in view of (19). Since

 \mathcal{R} is a linearly independent set, then $\gamma_1 u_1(x) + \ldots + \gamma_n u_n(x) = 0$ in \bar{G} if and only if $\gamma_1 = \gamma_2 = \ldots = \gamma_n = 0$. One can verify that (21) is a norm in \mathbf{R}^n . Then for some positive constants N_1 and N_2 the inequalities $N_1 |\vec{\gamma}| \leq |||\vec{\gamma}||| \leq N_2 |\vec{\gamma}|$ hold $\forall \vec{\gamma} \in \mathbf{R}^n$, where the notation $|\cdot|$ is given in Lemma 4. These inequalities, (12) and (21) imply

(22)
$$B\left[\sum_{r=1}^{n} \gamma_{r} u_{r}, l\left(\sum_{r=1}^{n} \gamma_{r} u_{r}\right)\right] \geq 0 \ \forall \overrightarrow{\gamma} \in \mathbf{R}^{n}: \ |\overrightarrow{\gamma}| \geq K_{n}$$

with $K_n = N_1^{-1} (\beta_3 \beta_2^{-1})^{1/(\rho+2)}$.

Let consider the operator $A: \mathbb{R}^n \to \mathbb{R}^n$ such that

$$A(\overrightarrow{\gamma}) = (B[\sum_{r=1}^{n} \gamma_r u_r, \Phi_1], \dots, B[\sum_{r=1}^{n} \gamma_r u_r, \Phi_n]).$$

Using the linearity of B[u, v] with respect to v and (22), we get the estimate

$$\langle A(\overrightarrow{\gamma}), \overrightarrow{\gamma} \rangle \geq 0 \ \forall \overrightarrow{\gamma} \in \mathbf{R}^n : |\overrightarrow{\gamma}| \geq K_n,$$

where $\langle ., . \rangle$ is the scalar product in \mathbb{R}^n generating the norm |.|. Lemma 4 shows that the operator A is continuous. Then Lemma 4.3, Ch. 1, [13] implies the existence of a vector $\overrightarrow{\gamma}^n \in \mathbf{R}^n$ such that $|\overrightarrow{\gamma}^n| \leq K_n$ and $A(\overrightarrow{\gamma}^n) = \overrightarrow{0}$. Hence $\overrightarrow{\gamma}^n$ is a solution of the system (20).

Setting
$$U_n = \sum_{r=1}^n \gamma_r^n u_r$$
 we have $U_n \in \tilde{C}^2$ and

$$0 = \sum_{i=1}^n B[U_n, \Phi_i] \gamma_i^n = B[U_n, l(U_n)] \ \forall n \in \mathbf{N}.$$

Then (12) gives $\beta_1 \|U_n\|_{W_2^1(G)}^2 + \beta_2 \|U_n\|_{L_{\rho+2}(G)}^{\rho+2} \le \beta_3 \ \forall n \in \mathbb{N}$. Therefore the following estimates

(23)
$$||U_n||_{W_2^1(G)} \le \left(\frac{\beta_3}{\beta_1}\right)^{1/2}, \ ||U_n||_{L_{\rho+2}(G)} \le \left(\frac{\beta_3}{\beta_2}\right)^{1/(\rho+2)},$$

and

and
(24)
$$||U_n|| \le \left[\frac{\beta_3}{\beta_1} + \left(\frac{\beta_3}{\beta_2}\right)^{2/(\rho+2)}\right]^{1/2} \equiv \beta_4$$

hold $\forall n \in \mathbb{N}$. The set $\{v \in X : ||v|| \leq \beta_4\}$ is a closed, bounded and convex subset of the reflexive Banach space X (see Lemma 1, ii)). Then it is weakly closed ([5], 25.2) and hence, it is weakly compact in X ([5], 24.8 and 25.6). Therefore the inequality (24) implies the existence of a subsequence $\{U_{n_j}\}_{j=1}^{\infty}$ weakly convergent in X to $u \in X$. Our aim is to show that u is a generalized solution of problem (1), (2).

Let consider the linear continuous functional

$$\mathcal{F}_{\varphi}(v) = (v, \varphi)_1 \ \forall v \in W_2^1(G),$$

where $(.,.)_1$ is the scalar product in $W_2^1(G)$, generating the norm $\|.\|_{W_2^1(G)}$, and $\varphi \in W_2^1(G)$ is arbitrary and fixed. If $v \in X$, then $v \in W_2^1(G)$ and the inequalities

$$|\mathcal{F}_{\varphi}(v)| \leq \|v\|_{W_{2}^{1}(G)} \|\varphi\|_{W_{2}^{1}(G)} \leq \|v\| \|\varphi\|_{W_{2}^{1}(G)} \ \forall v \in X$$

imply that $\mathcal{F}_{\varphi} \in X^*$. Hence $\mathcal{F}_{\varphi}(U_{n_j}) \underset{j \to \infty}{\longrightarrow} \mathcal{F}_{\varphi}(u) \ \forall \varphi \in W_2^1(G)$, i.e. $U_{n_j} \underset{j \to \infty}{\longrightarrow} u$ weakly in $W_2^1(G)$ ([1], Riesz representation theorem 1.11). That is equivalent

to $U_{n_j} \xrightarrow[j \to \infty]{} u$ and $\frac{\partial U_{n_j}}{\partial x_i} \xrightarrow[j \to \infty]{} \frac{\partial u}{\partial x_i}$ weakly in $L_2(G)$, $i = 1, \ldots, m$ (see [11],Ch. 1, §5).

The first inequality of (23) and Rellich - Kondrashov imbedding theorem (see [1]) show that the subsequence $\{U_{n_j}\}_{j=1}^{\infty}$ can be choosen also convergent to u strongly in $L_2(G)$. Then a subsequence $\{U_{n_{j_r}}\}_{r=1}^{\infty}$ exists, which is convergent to u almost everywhere in G and which is bounded in $L_{\rho+2}(G)$ due to (23). Since for $\eta = (\rho+2)/(\rho+1)$

$$||v|v|^{\rho}||_{L_{\eta}(G)} = ||v||_{L_{\rho+2}(G)}^{\rho+1} \ \forall v \in L_{\rho+2}(G),$$

then Lemma 3 implies that $U_{n_{j_r}}|U_{n_{j_r}}|^{\rho}\underset{r\to\infty}{\longrightarrow}u|u|^{\rho}$ weakly in $L_{\eta}(G)$. Using the inequalities $1<\eta<2$, (4) and the second one of (23), we obtain the estimate

$$||f(x, U_{n_{j_r}}||_{L_{\eta}(G)} \le c_1[F_1 + F_2||U_{n_{j_r}}||_{L_{\rho+2}(G)}^{(\rho+2)/\sigma}]^{1/2} \le c_2$$

 $\forall r \in \mathbb{N}$, where c_1 , c_2 are positive constants, nondepending on $\{U_{n_{j_r}}\}_{r=1}^{\infty}$. We have $f(x, U_{n_{j_r}}(x)) \underset{r \to \infty}{\longrightarrow} f(x, u(x))$ almost everywhere in G, because $f \in \mathbf{CAR}$. Due to Lemma 3 this convergence is also weak in $L_{\eta}(G)$.

Therefore $B[U_{n_{j_r}}, \Phi_i] \xrightarrow{} B[u, \Phi_i] \ \forall i \in \mathbb{N}$ and then $B[u, \Phi_i] = 0 \ \forall i \in \mathbb{N}$. It is not difficult to obtain the estimate

$$B[w,v] \le (c_3||w|| + ||f(x,w)||_{L_2(G)})||v|| \ \forall w,v \in Z,$$

where $c_3 = const > 0$ is nondepending on w and v. Since B[w, v] is a linear form with respect to v and the linear span of $\{\Phi_j\}_{j=1}^{\infty}$ is dense in Y, according to Lemma 2, then (6) holds. Theorem 1 is proved.

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