Mathematica Balkanica

New Series Vol. 20, 2006, Fasc. 3-4

Numerical Solution of Monge-Ampere Equation

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We show that the numerical solution, of the fully non linear Monge-Ampre equation in two dimension, can be obtained by resolving an optimisation problem implying the resolution of a quasilinear Dirichlet problem. A gradient method is used. We give a no classical method to compute the gradient.

Key Words Monge-Ampre, finite elements, gradient method.

1. Introduction

In this paper we give a numerical solution of the following Monge-Ampre problem :

$$(\mathcal{P}_I) \left\{ \begin{array}{l} \det[D^2 u] = f^2(x, u) \ x \in \Omega \\ u_{|\Gamma} = 0, u \text{ convex on } \bar{\Omega}. \end{array} \right.$$

Where Ω is a smooth convex and bounded domain in \mathbb{R}^2 , $[D^2u]$ is the Hessian of u and $f \in \mathcal{C}^2(\bar{\Omega} \times \mathbb{R}), f > 0$ on $\bar{\Omega} \times \mathbb{R}$, and $\frac{\partial f}{\partial s}(x,s) \geq 0$.

The problem (\mathcal{P}_I) has a unique strictly convex solution $u_I \in \mathcal{C}^2(\bar{\Omega}) \cap W^{1,\infty}(\Omega)$ (see[1]).

We propose a variationnal method for the approximation of the solution u_I of (\mathcal{P}_I) as in [2]. We show that (\mathcal{P}_I) is equivalent to the following problem:

$$(\mathcal{P}_{II}) \min_{g \in V} J(g),$$

with

$$J(g) = \frac{1}{2} \int_{\Omega} [det[D^{2}u(g)] - f^{2}(x, u(g))]^{2} dx$$

where u(g) is solution of the Dirichlet problem

$$\mathcal{P}_g \left\{ \begin{array}{l} -\Delta u + 2f(.,u) = -g \\ u_{|\Gamma} = 0 \end{array} \right.$$

and we show that $u_I = u(\tilde{g})$, where $\tilde{g} = Arg(minJ(g))$

In section 2 we prove the equivalence between (\mathcal{P}_I) and (\mathcal{P}_{II}) and we use a Galerkin-finite elements to approximize the solution u(g) of (\mathcal{P}_g) . In section 3 we give a non classical method to compute the gradient of the functional J. In the end we give a numerical test.

2. An equivalent problem

Let us consider the following assumptions

- (H_1) $f \in C^2(\overline{\Omega} \times \mathbb{R}) \cap W^{2,\infty}(\overline{\Omega} \times \mathbb{R}).$
- (H_2) $f(x,s) \ge \alpha_0 > 0$, $\forall s \in \mathbb{R}_-, \forall x \in \Omega$.
- (H_3) $\frac{\partial f}{\partial s}(x,s) > 0, \forall s \in \mathbb{R}_-, \forall x \in \Omega.$
- (H_4) $s \longmapsto f(.,s)$ is convex $\forall s \in \mathbb{R}_-$.

2.1. The Problem (\mathcal{P}_{II})

Let λ_1 and λ_2 be the eigenvalues of the matrix $[D^2u]$. We have

$$\begin{cases} \lambda_1 + \lambda_2 &= \Delta u_I, \\ \lambda_1 \lambda_2 &= f(., u_I). \end{cases}$$

Then λ_1 and λ_2 are the solutions of

$$X^2 - \Delta u_I X + f^2(., u_I) = 0.$$

So

$$(\Delta u_I)^2 - 4f^2(., u_I) \ge 0.$$

Since u_I is convex and f > 0 we should have

$$\Delta u_I - 2f \ge 0.$$

If we put

$$\tilde{g} = \Delta u_I - 2f,$$

it is clear that u_I is solution of the following problem

(2.2)
$$\mathcal{P}_{\tilde{g}} \left\{ \begin{array}{l} -\Delta u + 2f(., u) = -\tilde{g} \\ u_{|\Gamma} = 0 \end{array} \right.$$

To compute \tilde{g} , we consider the functional

(2.3)
$$J(g) = \frac{1}{2} \int_{\Omega} [\det[D^2 u(g)] - f^2(x, u(g))]^2 dx$$

where u(g) is the solution of the Dirichlet problem

(2.4)
$$(\mathcal{P}_g) \left\{ \begin{array}{l} -\Delta u + 2f(., u) = -g \\ u_{|\Gamma} = 0. \end{array} \right.$$

We remark that J is well-defined if $u(g) \in W^{2,4}(\Omega)$ and $f^2(., u(g)) \in L^2(\Omega)$. We recall the following result:

Theorem 2.1. Under assumptions (H_3) and $g \in L^2(\Omega)$ the quasilinear elliptic problem (\mathcal{P}_q) has a unique solution $u(g) \in H_0^1(\Omega)$. (see[4]).

We have the following result:

Theorem 2.2. Problems (\mathcal{P}_I) and (\mathcal{P}_{II}) . are equivalents

Proof. By (2.2) we have $u_I = u(\widetilde{g})$ so $J(\widetilde{g}) = 0$.

Let \overline{g} a solution of (\mathcal{P}_{II}) then $J(\overline{g}) = 0$ so

$$\left\{ \begin{array}{l} \det[D^2u(\overline{g})] = f, \\ u(\overline{g})_{|\Gamma} = 0. \end{array} \right.$$

Since $\Delta u(\overline{g}) = 2f + \overline{g} > 0$ and $det[D^2u(\overline{g}) > 0$ we have $u(\overline{g})$ is strictly convex and from the uniqueness of solution for (\mathcal{P}_I) we get $u(\overline{g}) = u_I$.

Remark 2.3 From the previous section we can deduce that the computation by finite elements method of u_I is possible by resolving $(\mathcal{P}_{\widetilde{g}})$ if one has \widetilde{g} for this purpose we resolve (\mathcal{P}_{II}) .

3. The numerical resolution of (\mathcal{P}_{II})

To numerical resolve (\mathcal{P}_{II}) we start linearizing (\mathcal{P}_g) by considering a sequence of linear problems which are resolved by finite elements method. To compute \tilde{g} we use a gradient method.

3.1. Resolution of the problem (\mathcal{P}_g)

3.1.1. Linearisation of the problem (\mathcal{P}_g) We assume that

$$g \in H^1_+(\Omega) = \{ v \in H^1(\Omega) / v \ge 0 \}$$

We consider a sequence of linear problems: Let u^0 a solution of

(3.1)
$$\mathcal{P}_0 \left\{ \begin{array}{ll} -\Delta u^0 & = -g \\ u_{|\Gamma}^0 & = 0. \end{array} \right.$$

We have, since $g \ge 0$, by standard maximum principle : $u^0 \le 0$ and we have

$$||u^0||_{H_0^1(\Omega)} \le C||g||_2.$$

Let us consider, for $k = 1, \dots, n \dots$, the problem (\mathcal{P}_k) given by :

$$\mathcal{P}_k \left\{ \begin{array}{l} -\Delta u^k + 2 \frac{\partial f}{\partial s}(., u^{k-1}) u^k = F(u^{k-1}), \\ u^k_{|\Gamma} = 0, \end{array} \right.$$

where

$$F(u^{k-1}) = -g + 2\frac{\partial f}{\partial s}(., u^{k-1})u^{k-1} - 2f(., u^{k-1}).$$

Assume that $u^k \leq 0$ and $u^k \in H^1_0(\Omega)$ for $1 \leq k \leq n$, where u^k is the solution of $(\mathcal{P}_k)_{1 \leq k \leq n}$.

We consider the problem in u^{n+1} :

(3.4)
$$\mathcal{P}_{n+1} \begin{cases} -\Delta u^{n+1} + 2 \frac{\partial f}{\partial s}(., u^n) u^{n+1} = F(u^n) \\ u_{|\Gamma}^{n+1} = 0 \end{cases}$$

where

(3.5)
$$F(u^n) = -g + 2\frac{\partial f}{\partial s}(., u^n)u^n - 2f(., u^n)$$

Remark 3.1.

- i) Since $-g \le 0$, $u^n \le 0$, and $f(.,u^n) \ge 0$ we have with (H_2) and (H_3) : $F(u^n) \le 0$. So by the maximum principle $u^{n+1} \le 0$.
- ii) Since Ω is a bounded domain of \mathbb{R}^2 , by Sobolev imbedding theorem we have u^n and $g \in L^4(\Omega)$. By assumption (H_1) we have $F(u^n) \in L^4(\Omega)$. So $u^{n+1} \in W^{2,4}(\Omega) \cap W_0^{1,4}(\Omega)$.
- iii) Using the coercivity of the variational formulation of (\mathcal{P}_{n+1}) we have :

$$(3.6) ||u^{n+1}||_{H^1} \le C||F(u^n)||_2 \le C(\Omega, ||g||_2, ||f||_{\infty}, ||\partial_s f||_{\infty}).$$

3.1.2 The Convergence We need the following lemma

Lemma 3.2. Let \mathcal{L}_n be the linear operator

$$\mathcal{L}_n(\omega) = -\Delta\omega + 2\frac{\partial f}{\partial s}(., u^n)\omega$$

if we note $\omega_n = u(g) - u^n$, where u^n is the solution of (\mathcal{P}_n) and u(g) of (\mathcal{P}_g) . Then $\exists \theta \in]0,1[$ such that

(3.7)
$$\mathcal{L}_n(\omega_{n+1}) = -\frac{\partial^2 f}{\partial s^2}(., u^n + \theta\omega_n)\omega_n^2$$

Proof. We have

$$\begin{cases} -\Delta u(g) + f(., u(g)) = -g \\ -\Delta u^{n+1} + \frac{\partial f}{\partial s}(., u^n)u^{n+1} = F(u^n) \end{cases}$$

subtracting, with Taylor formula and $\theta \in]0,1[$, gives

$$-\Delta\omega_{n+1} + 2\frac{\partial f}{\partial s}(., u^n)\omega_{n+1} = 2g(., u^n) - 2f(., u(g)) + 2\frac{\partial f}{\partial s}(., u^n)\omega_n$$
$$= -\frac{\partial^2 f}{\partial s^2}(., u^n + \theta\omega_n)\omega_n^2.$$

Consider now the sequence $(u^n)_{n\in\mathbb{N}}$. We have the following:

Proposition 3.3.

(3.8)
$$u(g) \le \dots \le u^{n+1} \le u^n \le \dots \le u^0 \le 0.$$

Proof.

(1) We first show that $u^{n+1} - u^n \le 0$ Let $\omega_0 = u^1 - u^0$, we have

$$\begin{cases} -\Delta u^1 + 2\frac{\partial f}{\partial s}(., u^0)u^1 = F(u^0) \\ -\Delta u^0 = -g \end{cases}$$

subtracting gives

$$-\Delta\omega_0 + 2\frac{\partial f}{\partial s}(., u^0)\omega_0 = -2f(., u^0) \le 0,$$

then by the maximum principle $\omega_0 \leq 0$. Subtracting (\mathcal{P}_{n+1}) and (\mathcal{P}_n) we obtain under assumption (H_4) and Lemma3.3

$$-\Delta\omega_n + 2\frac{\partial f}{\partial s}(., u^n)\omega_n = -\frac{\partial g}{\partial s^2}(., u^{n-1} + \theta\omega_{n-1})\omega_{n-1}^2 \le 0.$$

By maximum principle we have $\omega_n \leq 0$.

(2) We show now that, $u(g) \leq u^n$, $\forall n$. By Lemma3.3, we see that the function $\omega_{n+1} = u(g) - u^{n+1}$ satisfy

$$-\Delta\omega_{n+1} + 2\frac{\partial f}{\partial s}(., u^n)\omega_{n+1} = -\frac{\partial^2 f}{\partial s^2}(., u^n + \theta\omega_n)\omega_n^2 \le 0$$

and then $\omega_{n+1} \leq 0$.

Remark 3.4. Assumption H_3 with (3.6) and (3.8) implies that \mathcal{P}_g has a solution which is giving by

$$u(g) = Inf(u^n).$$

Remark 3.5. Let $\mathcal{E}_{n+1} = u^{n+1} - u(g)$ the error between the solution of (\mathcal{P}_{n+1}) and the solution of $(\mathcal{P}(g))$. By Lemma3.3, we have

$$-\Delta \mathcal{E}_{n+1} + 2\frac{\partial f}{\partial s}(., u^n)\mathcal{E}_{n+1} = \frac{\partial^2 f}{\partial s^2}(., u^n - \theta \mathcal{E}_n)\mathcal{E}_n^2,$$

so we obtain

$$\|\mathcal{E}_{n+1}\|_{H^1} \le C \|\mathcal{E}_n\|_{H^1}^2,$$

which implies that the convergence is quadratic.

3.2. Computation of the gradient of J.

To compute the gradient of the functional J considered in (2.3), we consider the weak solution of (\mathcal{P}_g) , and we assume that \mathcal{T}_h is a triangulation of Ω . Thus J can be written

(3.10)
$$J(g) = \frac{1}{2} \sum_{\ell=1}^{N} \int_{K_{\ell}} [\det[D^{2}u(g)] - f^{2}(x, u(g))]^{2} dx$$

where N is the number of triangles K_{ℓ} and u(g) is given by :

(3.11)
$$u(g) = \sum_{i=1}^{N_h^0} \mathcal{E}_i(g)\varphi_i$$

with $(\varphi_i)_{i=1,\cdots,N_h^0}$ the basic functions of Galerkin-finite elements of order two . If

$$(3.12) \quad \varphi_{i\ell}(x,y) = \alpha_{i\ell}x^2 + \beta_{i\ell}y^2 + \gamma_{i\ell}xy + \delta_{i\ell}x + \eta_{i\ell}y + \tau_{i\ell} \quad , i = 1 \cdots 6$$

are the basic functions on K_{ℓ} , we have :

$$(3.13) \quad \det[D^2 u(g)]_{|K_{\ell}} = 4(\sum_{i=1}^{6} \mathcal{E}_i(g)\alpha_{i\ell})(\sum_{i=1}^{6} \mathcal{E}_j(g)\beta_{j\ell}) - (\sum_{k=1}^{6} \mathcal{E}_k(g)\gamma_{k\ell})^2$$

and

(3.14)
$$J(g) = \frac{1}{2} \sum_{\ell=1}^{N} (A_{\ell} D_{\ell}^{2}(g) - 2B_{\ell}(g) D_{\ell}(g) + C_{\ell}(g))$$

where

$$A_{\ell} = Area(K_{\ell}), \quad B_{\ell}(g) = \int_{K_{\ell}} f^{2}(x, u(g(x))dx$$

and

$$D_{\ell}(g) = \det[D^2 u(g)]_{|K_{\ell}}, \quad C_{\ell}(g) = \int_{K_{\ell}} f^4(x, u(g(x))) dx$$

So if we write

$$(3.15) g = \sum_{m=1}^{N_h} g_m \varphi_m$$

we have:

$$(3.16)\frac{\partial J}{\partial g_m} = \sum_{\ell=1}^{N} \{ (A_{\ell} D_{\ell}(g) - B_{\ell}(g)) \frac{\partial D_{\ell}(g)}{\partial g_m} - D_{\ell}(g) \frac{\partial B_{\ell}}{\partial g_m}(g) + \frac{1}{2} \frac{\partial C_{\ell}(g)}{\partial g_m} \}$$

with

(3.17)
$$\frac{\partial B_{\ell}(g)}{\partial g_m} = \int_{K_{\ell}} \frac{\partial f^2}{\partial s} (., u(g)) \Phi_{m,\ell} dx$$

(3.18)
$$\frac{\partial C_{\ell}(g)}{\partial g_m} = \int_{K_{\ell}} \frac{\partial f^4}{\partial s} (., u(g)) \Phi_{m,\ell} dx.$$

Where

(3.19)
$$\Phi_{m,\ell}(x) = \sum_{i=1}^{6} \frac{\partial \mathcal{E}_i(g)}{\partial g_m} \varphi_{i\ell}(x)$$

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and

$$\frac{\partial D_{\ell}(g)}{\partial g_{m}} = 4 \left(\sum_{i=1}^{6} \frac{\partial \mathcal{E}_{i}(g)}{\partial g_{m}} \alpha_{i\ell} \right) \left(\sum_{j=1}^{6} \mathcal{E}_{j}(g) \beta_{j\ell} \right)
+ 4 \left(\sum_{i=1}^{6} \mathcal{E}_{i}(g) \alpha_{i\ell} \right) \left(\sum_{j=1}^{6} \frac{\partial \mathcal{E}_{j}(g)}{\partial g_{m}} \beta_{j\ell} \right)
- 2 \left(\sum_{k=1}^{6} \mathcal{E}_{k}(g) \gamma_{k\ell} \right) \left(\sum_{k=1}^{6} \frac{\partial \mathcal{E}_{k}(g)}{\partial g_{m}} \gamma_{k\ell} \right)$$

So to compute the gradient of J we need

(3.21)
$$\frac{\partial \mathcal{E}_i(g)}{\partial q_m} \ i = 1, \dots, N_h^0, \ m = 1, \dots, N_h$$

We consider then equation (2.4) and after partial derivation we have by (3.15)

(3.22)
$$\begin{cases} -\Delta\omega_m + 2\frac{\partial f}{\partial s}(., u(g))\omega_m = -\varphi_m, \\ \omega_{m|\Gamma} = 0. \end{cases}$$

Where $\omega_m = \frac{\partial u(g)}{\partial g_m}$. Note too using (3.11) that

$$\frac{\partial u(g)}{\partial g_m} = \sum_{i=1}^{N_h^0} \frac{\partial \mathcal{E}_i(g)}{\partial g_m} \varphi_i$$

and (3.22) give

(3.23)
$$\omega_m = \sum_{i=1}^{N_h^0} \eta_i^m \varphi_i.$$

So resolving (3.22) by the use of the finite elements method we obtain with (3.23)

(3.24)
$$\frac{\partial \mathcal{E}_i(g)}{\partial g_m} = \eta_i^m \quad i = 1, \dots, N_h^0 \quad m = 1, \dots, N_h.$$

4. Numerical test

In order to test this method, we have shosen, an example of problem (\mathcal{P}_I) which we know its explicet solution. The latter is shosen in order to be compared to the computed solution.

Example Example 4.1. We take Ω the unit disque and

$$f((x,y),u) = 4(3 + 2Log(1+u))(1+u)^{2}$$
.

It's clear that f verifies all assuptions (H_1) , $(H_2,)$ (H_3) and (H_4) . The solution of (\mathcal{P}_I) is the following

$$u_I(x,y) = e^{(x^2+y^2-1)} - 1.$$

In Fig. 4.1 and Fig. 4.2 we present the computed solution obtained by applying this method at 10 iterations compared to the exact solution u_I .

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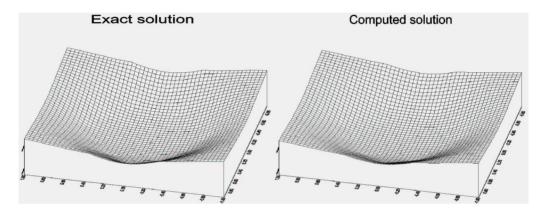


FIGURE 4.1. Graphs of u_I and the computed solution u=u(x,y).

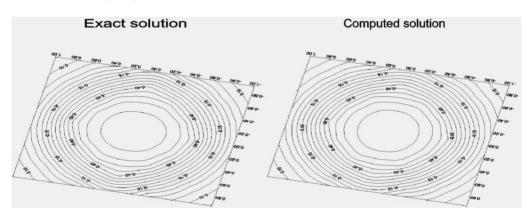


Figure 4.2. The contour plot of u_I and the computed solution.