

THE DESCARTES' RULE AND THE ČEBYŠEV'S SYSTEMS

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1. Some notations and definitions :

$R := (-\infty, +\infty)$ denotes the real line supplied with the classical algebraic, topological and order structures.

\hat{R} and \check{R} are two compactifications of R : $\hat{R} := R \cup \{*\infty\}$ and $\check{R} := \{-\infty\} \cup R \cup \{+\infty\} =: [-\infty, +\infty]$, where $*\infty, -\infty, +\infty$ are three new "infinite" elements. It is well-known that the topology and to a certain extent some algebraic properties are extended from R onto \hat{R} and \check{R} . Besides, \check{R} is totally ordered and \hat{R} is oriented and homeomorphic to any circumference.

Z is the set of all integers of R .

Let u and v be arbitrary elements of \check{R} . Then :

${}_u Z_v := \{k \in Z \mid k \geq u, k \leq v\}$. The set ${}_u Z_v$ is considered to be totally ordered by the relation $<$. Obviously : $_{-\infty} Z_{+\infty} = Z, {}_3 Z_2 = \emptyset, {}_1 Z_1 = \{1\}$, etc.

${}^u R^v$ is the set of all maps $c : {}_u Z_v \ni k \rightarrow c_k \in R$, or otherwise ${}^u R^v$ is the set of all ${}_u Z_v$ -ordered families or ${}_u Z_v$ -systems of real numbers $c := (c_k \in R \mid k \in {}_u Z_v)$.

${}^u O^v := (0_k = 0 \mid k \in {}_u Z_v) = (0, \dots, 0) \in {}^u R^v$ is the zero element of ${}^u R^v$.

$({}^u R^v)^* := {}^u R^v \setminus \{{}^u O^v\}$.

${}^u A^v$ is the alternation operator on ${}^u R^v$, that is

${}^u A^v : {}^u R^v \ni c = (c_k \mid k \in {}_u Z_v) \rightarrow {}^u A^v c := ((-1)^k \cdot c_k \mid k \in {}_u Z_v) \in {}^u R^v$.

V_c is the set of indices $k \in {}_{u+1} Z_v$ for which a given $c \in {}^u R^v$ has a variation, that is the set of numbers $k \in {}_{u+1} Z_v$ for which : either $c_k \cdot c_{k-1} < 0$ or $c_{k-1} = c_{k-2} = \dots = c_{k-m+1} = 0$ and $c_k \cdot c_{k-m} < 0$, for a certain $m \in {}_2 Z_{k-u}$.

$|M| := \text{Card } M$ is the cardinal number (or the number of elements) of a given set M .

2. Some systems of functions :

Hereafter let be given : a number $n \in {}_1Z_{+\infty}$ and a set \tilde{S} which is not supplied with any predetermined topology (it is convenient to suppose in addition that $|\tilde{S}| > n$) and let

$$(1) \quad \tilde{F} := (\tilde{f}_k : \tilde{S} \rightarrow R ; k \in {}_0Z_n)$$

be a fixed ${}_0Z_n$ -system (or a ${}_0Z_n$ -ordered family) of real-valued functions defined on the set \tilde{S} . For every $c \in {}^0R^n$, set :

$\tilde{F}_c : \tilde{S} \ni s \rightarrow \tilde{F}_c(s) := \sum (c_k \cdot \tilde{f}_k(s) ; k \in {}_0Z_n) \in R$. Such a function \tilde{F}_c is said to be a \tilde{F} -polynomial or more detailed a \tilde{F} -polynomial with a system c of coefficients.

$N(\tilde{F}_c; S_0) := \{s \in S_0 ; \tilde{F}_c(s) = 0\}$ is the set of all zeroes of the \tilde{F} -polynomial \tilde{F}_c on a given set S_0 , where $S_0 \subset \tilde{S}$. Obviously

$N(\tilde{F}({}_0Z_n); S_0) = S_0$ for every subset S_0 of the set \tilde{S} .

The system (1) is said to be a Čebyšev (Tchebyscheff; Chebyshev) system or a T-system on a set S_1 , $S_1 \subset \tilde{S}$, iff for every $c \in ({}^0R^n)^*$ the inequality $|N(\tilde{F}_c; S_1)| \leq n$ holds true.

The system (1) is said to be a Markov (Markoff) system or a M-system on a set $S_2 \subset \tilde{S}$, iff for every $m \in {}_0Z_n$ and every $c \in ({}^0R^n)^*$ for which $c_k = 0$, when $k \in {}_{m+1}Z_n$, the inequality $|N(\tilde{F}_c; S_2)| \leq m$ holds true.

The system (1) is said to be a variationally Descartes system or a vD-system on a set S_3 , $S_3 \subset \tilde{S}$, iff for every $c \in ({}^0R^n)^*$ the inequality $|N(\tilde{F}_c; S_3)| \leq |V_c|$ holds true.

The system (1) is said to be an alternationally Descartes system or an aD-system on a set S_4 , $S_4 \subset \tilde{S}$, iff for every $c \in ({}^0R^n)^*$ the inequality $|N(\tilde{F}_c; S_4)| \leq |V({}_0A_n c)|$ holds true.

The system (1) is said to be a variationally strictly Descartes system or a vsD-system on a set S_5 , $S_5 \subset \tilde{S}$, iff for every $c \in ({}^0R^n)^*$ $|V_c| - |N(\tilde{F}_c; S_5)|$ is a non-negative even number.

The system (1) is said to be an alternationally strictly Descartes system or an asD-system on a set S_6 , $S_6 \subset \tilde{S}$, iff for every $c \in ({}^0R^n)^*$ $|V({}_0A_n c)| - |N(\tilde{F}_c; S_6)|$ is a non-negative even number.

If there exist sets S_7 , S_8 and S_9 for which : $S_7 \subset S_9$, $S_8 \subset S_9$, $S_9 \subset \tilde{S}$, $S_7 \cap S_8 = \emptyset$ and the set $S_9 \setminus (S_7 \cup S_8)$ contains at most two different elements and if the system (1) : ...

(I) ... is a vD-system on S_7 and is an aD-system on S_8 , then the system (1) is said to be a Descartes or a D-system on S_9 .

(II) ... is a vsD-system on S_7 and is an asD-system on S_8 , then the system (1) is said to be a strictly Descartes or a sD-system on S_9 .

From now on (from the type of a system) the symbol E will denote any one fixed symbol among the symbols : T, M, vD, aD, D, vsD,

asD, sD ; and the symbol e will denote a or v .

The E-system (1) on some set S_1 , $S_1 \subset \tilde{S}$, is said to be an $E_{s'}$ -system on S_1 , where $s' \in \tilde{S}$, iff $\tilde{f}_k(s') = 0$ for $k \in {}_1Z_n$ and $\tilde{f}_0(s') \neq 0$.

Let the system (1) be an E-system on some set S_2 , where $S_2 \subset \tilde{S}$ and the set S_2 is totally ordered by a given relation r . If for all $k \in {}_1Z_n$ the functions \tilde{f}_k are strictly r -monotonous on the set S_2 (that is, $\tilde{f}_k(s_1) < \tilde{f}_k(s_2)$ every time when $s_1 r s_2$ for $s_1, s_2 \in S_2$ and $k \in {}_1Z_n$) and $\tilde{f}_0(s) \neq 0$ for any $s \in S_2$, then the system (1) is said to be an E^r -system on the set S_2 .

If the system (1) is an $E_{s'}$ -system on S_3 and at the same time an E^r -system on S_3 then (1) is said to be an $E_{s'}^r$ -system on the set S_3 , where $S_3 \subset \tilde{S}$, $s' \in \tilde{S}$ and r is a relation of total order on S_3 .

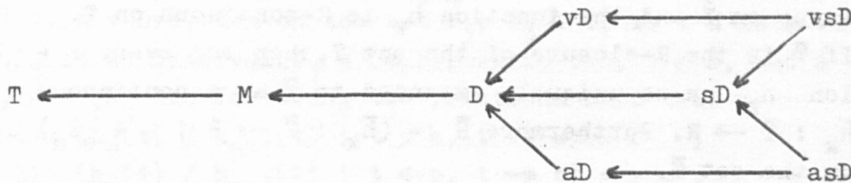
For an arbitrary number t' , $t' \in \mathbb{R}$, and for an arbitrary set T^0 , $T^0 \subset \mathbb{R}$, it will denote $aT_{t'}^0 := (-\infty, t') \cap T^0$ and $vT_{t'}^0 := (t', +\infty) \cap T^0$.

3. Some Propositions :

In the terms introduced above, the following generalizations and complements to some results considered in [1] and [2] are established :

Proposition 1 : There are several maps of inclusion between the above-mentioned types of function systems.

1^o. Some of them form the following diagram :



2^o. Let $s' \in \tilde{S}$ and r be a relation of total order on a set S_0 , $S_0 \subset \tilde{S}$. Then similar diagrams are valid if all the symbols in the above diagram are supplied : ...

(I) ...only with upper indices r ; (II) ...only with lower indices s' ; (III) ...with upper indices r and lower indices s' at the same time.

Proposition 2 : For the system (1) and a certain matrix

$J := (j_{km} \in \mathbb{R} \mid k, m \in {}_0Z_n)$ the following function system can be formed

$$(2) \quad J\tilde{f} := ((J\tilde{f})_k : S \rightarrow \mathbb{R} \mid k \in {}_0Z_n),$$

where $(J\tilde{f})_k(s) := \sum (j_{km} \cdot \tilde{f}_m(s) \mid m \in {}_0Z_n)$, for every $k \in {}_0Z_n$ and $s \in \tilde{S}$.

In this case :

1^o. If (1) is a T-system on a set S_1 , $S_1 \subset \tilde{S}$, and J is an arbitrary non-degenerate matrix (that is, if $\det J \neq 0$), then (2) is a T-system on the set S_1 .

2^o. If (1) is a M-system on a set S_2 , $S_2 \subset \tilde{S}$, and J is an arbitrary non-degenerate, lower-triangular matrix (that is, if :

$\det J \neq 0$, $j_{kk} \neq 0$ and $j_{km} = 0$, for : $k \in {}_0Z_n$ and $m \in {}_{k+1}Z_n$, then (2) is a M-system on the set S_2 .

3°. If (1) is a D-system (an eD-system) on a set S_3 , $S_3 \subset \tilde{S}$, and J is an arbitrary non-degenerate, non-negative, lower-triangular matrix (that is, if : $\det J \neq 0$, $j_{kk} > 0$, $j_{kl} \geq 0$ and $j_{km} = 0$, for : $k \in {}_0Z_n$, $l \in {}_0Z_{k-1}$ and $m \in {}_{k+1}Z_n$) then (2) is a D-system (an eD-system) on the set S_3 .

4°. If (1) is a sD-system (an esD-system) on a set S_4 , $S_4 \subset \tilde{S}$, and J is a strictly-positive diagonal matrix (that is, if : $j_{kk} > 0$ and $j_{km} = 0$, for : $k \in {}_0Z_n$ and $m \in ({}_0Z_{k-1} \cup {}_{k+1}Z_n)$, and consequently $\det J \neq 0$), then (2) is a sD-system (an esD-system) on the set S_4 .

Proposition 3 : Let be given : a number $n \in {}_1Z_{+\infty}$, a set \dot{S} and an E-system $\dot{F} := (\dot{f}_k : \dot{S} \rightarrow R ; k \in {}_0Z_n)$ on the set \dot{S} .

1°. Then a set \dot{T} , $\dot{T} \subset R$, and a bijection $\dot{B} : \dot{S} \rightarrow \dot{T}$ exist. Moreover, if $\dot{T} \neq \dot{R}$, then, without loss of generality, this bijection can be replaced by other (say, again \dot{B}), for which $*\infty \notin \dot{B}(\dot{S})$.

2°. Let $T := \dot{T} \setminus \{*\infty\}$, $\dot{h}_k : \dot{T} \ni t \rightarrow \dot{h}_k(t) := \dot{f}_k(\dot{B}^{-1}(t)) \in R$ and $h_k := \dot{h}_k|_T$, for every $k \in {}_0Z_n$, then the systems $\dot{H} := (\dot{h}_k : \dot{T} \rightarrow R ; k \in {}_0Z_n)$ and $H := (h_k : T \rightarrow R ; k \in {}_0Z_n)$ are E-systems on the sets \dot{T} and T respectively.

3°. Under these conditions, for every $k \in {}_0Z_n$, the function \dot{h}_k is \dot{R} -continuous on \dot{T} and the function h_k is R -continuous on T .

4°. If \bar{T} is the R -closure of the set T , then for every $k \in {}_0Z_n$, the function h_k can be uniquely extended to \bar{T} as a continuous function $\bar{h}_k : \bar{T} \rightarrow R$. Furthermore $\bar{H} := (\bar{h}_k : \bar{T} \rightarrow R ; k \in {}_0Z_n)$ is an E-system on the set \bar{T} .

5°. Besides, there exist : a uniquely defined R -closed set \underline{T} (that is, $\bar{T} = \underline{T}$) and (maybe non-uniquely defined) an E-system $\underline{H} := (\underline{h}_k : \underline{T} \rightarrow R ; k \in {}_0Z_n)$ on the set \underline{T} , such that : (I) $T \subset \underline{T} \subset R$; (II) $\underline{h}_k|_T = h_k$ if $k \in {}_0Z_n$; (III) $\underline{T} \supset \underline{T}$ every time, when $T \subset \underline{T} \subset R$ and there is an E-system $\underline{H} := (\underline{h}_k : \underline{T} \rightarrow R ; k \in {}_0Z_n)$ on the set \underline{T} , for which $\underline{h}_k|_T = h_k$ if $k \in {}_0Z_n$.

6°. Moreover, if \dot{F} is a T-system on \dot{S} , and $t' \in R$, then there exist such uniquely defined matrix J , for which the system $J\underline{H}$ is an $eD_{t'}$ -system on the set $e\underline{T}_{t'}$, and a $D_{t'}$ -system on the set \underline{T} .

7°. Let $s^* := \dot{B}^{-1}(*\infty)$, $S := \dot{S} \setminus \{s^*\}$ and $B := \dot{B}|_S$. Then by means of the map $B^{-1} : T \rightarrow S$, any structure (for example : the topology, the total order, etc.) which is defined on the set T can be transferred onto the set S .

8°. More generally, there exist non-uniquely defined set \underline{S} and a bijection $\underline{B} : \underline{S} \rightarrow \underline{T}$, such that $\underline{S} \supset S$ and $\underline{B}|_S = B$. Then by means of the

map $B^{-1} : \underline{T} \rightarrow \underline{S}$ every \underline{T} -structure can be transferred onto the set \underline{S} .

9°. Finally, much of the constructions performed on the sets T , \underline{T} , etc. can be returned to the sets S , its extension \underline{S} and their subsets. In particular, if $\underline{f}_k : \underline{S} \ni s \rightarrow \underline{f}_k(s) := \underline{h}_k(B^{-1}(s)) \in R$, for every $k \in {}_0Z_n$, then $\underline{F} := (\underline{f}_k : \underline{S} \rightarrow R \mid k \in {}_0Z_n)$ is an E-system on the set \underline{S} and $\underline{JF} := ((\underline{Jf})_k : \underline{S} \rightarrow R \mid k \in {}_0Z_n)$ is a D-system (an eD-system) on the set \underline{S} (on the set $B^{-1}e_{\underline{T}}$).

Remark 1 : In proposition 3 it is not supposed any predefined topology on the set S . This differs from the well-known assumption (cf. [1]), where a topology on the set S exists and much more S is compact with respect to it. Note also that the sets \bar{T} and $\underline{\bar{T}}$ are R -closed, but they are not necessarily R -compact.

Proposition 4 : Let $n \in {}_1Z_{+\infty}$, T be a subset of R and $H := (h_k : T \rightarrow R \mid k \in {}_0Z_n)$ be a system of functions. A necessary and sufficient condition for the system H to be : ...

(I) ... a vD-system on some set T_1 , $T_1 \subset T$, is : for every $m \in {}_1Z_n$ and for two arbitrarily chosen strictly increasing systems of numbers $(k_p \in {}_0Z_n \mid p \in {}_0Z_m)$ and $(t_q \in T_1 \mid q \in {}_0Z_m)$, where $m \in {}_1Z_n$, the inequality $\det(h_{k_p}(t_q) \mid p, q \in {}_0Z_m) > 0$ holds true.

(II) ...an aD-system on some set T_2 , $T_2 \subset T$, is : the system $AH := ((-1)^k \cdot h_k : T \rightarrow R \mid k \in {}_0Z_n)$ is a vD-system on the set T_2 .

(III) ...a vsD-system on the set T_3 , $T_3 \subset T$, is : H is a vD-system on T_3 ; T_3 is an interval $T_3 = (a, b)$, where : $a, b \in R$, and $a < b$; for every $m \in {}_1Z_n$ the following two relations hold true :

$$\begin{aligned} \lim (h_m(t) / h_{m-1}(t) \mid t > a, t \rightarrow a) &= 0 \quad , \\ \lim (h_m(t) / h_{m-1}(t) \mid t < b, t \rightarrow b) &= +\infty \quad . \end{aligned}$$

(IV) ...an asD-system on some set T_4 , $T_4 \subset T$, is : the system AH is a vsD-system on the set T_4 .

Remark 2 : The last proposition and the following simple example show that there is an error in [2], part 5, chapter 1, problem 41.

Example 1 : For every $t \in R$ it has : $t^3+t-10 = (t^2+2t+5) \cdot (t-2) =$

$$= \begin{cases} 1 \cdot t \cdot (t+4) \cdot (t-3) - 1 \cdot t \cdot (t+4) + 17 \cdot t - 10 ; \\ 1 \cdot t \cdot (t+4) \cdot (t-2) - 2 \cdot t \cdot (t+4) + 17 \cdot t - 10 ; \\ 1 \cdot t \cdot (t+4) \cdot (t-1) - 3 \cdot t \cdot (t+4) + 17 \cdot t - 10 . \end{cases}$$

In these three cases it has respectively :

$$\begin{aligned} 2 \notin (3, +\infty) \quad \text{and} \quad |V| - |N| &= 3 - 0 = 3 \quad \text{is odd} ; \\ 2 \notin (2, +\infty) \quad \text{and} \quad |V| - |N| &= 3 - 0 = 3 \quad \text{is odd} ; \\ 2 \in (1, +\infty) \quad \text{and} \quad |V| - |N| &= 3 - 1 = 2 \quad \text{is even.} \end{aligned}$$

Proposition 5 : Let be given : $n \in {}_1Z_{+\infty}$, $T \subset R$, $t' \in \hat{T}$ and a $D_{t'}$ -system $H := (h_k : T \rightarrow R \mid k \in {}_0Z_n)$ on the set T , where \hat{T} is the narrowest R -interval, which contain the set T .

1°. There exist an interval $\check{T} = (\check{a}, \check{b})$, $T \subset \hat{T} \subset \check{T} \subset \mathbb{R}$, and a system $W := (w_k : \check{T} \rightarrow \mathbb{R} ; k \in {}_0Z_n)$ of functions non-decreasing on \check{T} and strictly increasing on T . They generate the following function system $I := (i_k : \check{T} \rightarrow \mathbb{R} ; k \in {}_0Z_n)$, where $i_0(t) = 1$, for $t \in \check{T}$ and

$i_k(t) := \int_{t_1}^t dw_1(t_1) \int_{t_1}^{t_2} dw_2(t_2) \dots \int_{t_1}^{t_{k-1}} dw_k(t_k)$ is an iterative (maybe improper) Stieltjes' integral for $k \in {}_1Z_n$ and $t \in \check{T}$. Furthermore $\lim (i_n(t) ; t \rightarrow \check{a}) = -\infty$ and $\lim (i_n(t) ; t \rightarrow \check{b}) = +\infty$.

2°. In these terms, for $k \in {}_0Z_n$ and $t \in T$ the representation $h_k(t) = h_0(t) \cdot i_k(t)$ holds true. Besides : I is a $D_t^<$ -system on T ; $eI := (i_k|_{eT_t} ; k \in {}_0Z_n)$ is an $eD_t^<$ -system on the set eT_t ; $eH := (h_k|_{eT_t} ; k \in {}_0Z_n)$ is an eD_t -system on the set eT_t ;

3°. Moreover, if \underline{T} is the largest subset of \check{T} on which all the functions w_k , for $k \in {}_1Z_n$, are strictly increasing ; if the function $\underline{h}_0 : \underline{T} \rightarrow \mathbb{R} \setminus \{0\}$ is a certain extension of the function $h_0 : T \rightarrow \mathbb{R}$ (obviously $h_0(T) \subset \mathbb{R} \setminus \{0\}$; and if for $k \in {}_1Z_n$, and $t \in \underline{T}$ one sets $\underline{h}_k(t) := \underline{h}_0(t) \cdot i_k(t)$, then $\underline{H} := (\underline{h}_k : \underline{T} \rightarrow \mathbb{R} ; k \in {}_0Z_n)$ is a : D_t -system on the set \underline{T} and an eD_t -system on the set $e\underline{T}_t$.

4°. Let $aw_k := \lim(w_k(t) ; t \in \underline{T}, t \downarrow)$, $vw_k := \lim(w_k(t) ; t \in \underline{T}, t \uparrow)$ for every $k \in {}_1Z_n$. Then the system \underline{H} is an esD_t -system on the set $e\underline{T}_t$ iff the set $e\underline{T}_t$ is an interval, and in the case when $e\underline{T}_t \neq \emptyset$ the equation $|ew_k| = +\infty$ holds true for every $k \in {}_1Z_n$.

5°. Conversely, if W is a system of functions which do not decrease on some \mathbb{R} -interval \check{T} and strictly increase on some subset T of \check{T} , and if $t' \in \check{T}$, then the system I generated by them is an $eD_t^<$ -system on eT_t , and a $D_t^<$ -system on T . By that, if the system H is formed by means of multiplication of a system I with some function $h_0 : T \rightarrow \mathbb{R} \setminus \{0\}$, then the system H is an eD_t -system on eT_t , and a D_t -system on T .

Remark 3 : The present investigations can be applied to the generalized moment problem, to extremal values problems, and to other questions of the constructive theory of functions.

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