

SMOOTH FUNCTIONS AND ZERO TRACES IN SOBOLEV SPACE

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1. Notations. Let  $\Omega \subset \mathbb{R}_N$  be a bounded domain. Then  $C^\infty(\bar{\Omega})$  denotes, as usual, the set of infinitely differentiable functions defined in  $\bar{\Omega}$ ,  $C_0^\infty(\Omega) \subset C^\infty(\bar{\Omega})$  is the subset of functions  $u$  with support  $\text{supp } u$  contained in  $\Omega$  and  $W^{1,p}(\Omega)$  ( $1 \leq p < +\infty$ ) stands for the usual Sobolev space.

We say that  $\Omega$  has a continuous boundary, or a Lipschitzian boundary, iff the boundary of  $\Omega$  can be locally described as a graph of a continuous function, or a Lipschitzian function, respectively, which locally divides  $\mathbb{R}_N$  into the exterior and the interior of  $\Omega$  (comp. [1, p.15] ).

Let  $\Gamma \subset \partial\Omega$  be a relatively open set ( i.e. an open subset of the metric space  $\partial\Omega$  ). We say that  $\Gamma$  has a continuous relative boundary  $\partial^*\Gamma$  iff it passes the following property:

Let  $x_0 \in \partial^*\Gamma$  and let  $U(x_0)$  be the neighbourhood of  $x_0$  in which  $\partial\Omega$  is described as a graph:  $x_N = a(x_1, \dots, x_{N-1})$ , as above. Then the projection of  $\partial^*\Gamma \cap U(x_0)$  on the hyperplane  $x_N = 0$  is a part of the boundary  $\partial G$  of the projection  $G$  of  $\Gamma \cap U(x_0)$  which is locally described by a continuous function ( of  $N-2$  variables ) in the sense analogous to that described above.

2. Lemma. Let

$$C_N = \{x \in \mathbb{R}_N : |x_i| < 1\}$$

be an  $N$ -dimensional open cube, and let us denote  $C_N^- = \{x \in C_N : x_N < 0\}$ . Let  $G \subset \bar{C}_N \subset C_{N-1}$  be a domain with a continuous boundary, and let  $\Gamma = G \times \{0\} \subset \partial C_N^-$ . Let  $u \in W^{1,p}(C_N^-)$  ( $1 \leq p < +\infty$ ) equals zero on  $\Gamma$  ( in the sense of traces ); let  $\text{supp } u \subset C_N^-$ .

Then there exists a sequence  $u_n, u_n \in C_0^\infty(C_N^-)$ , such that  $\text{supp } u_n \cap \Gamma = \emptyset$  and  $u_n \rightarrow u$  in  $W^{1,p}(C_N^-)$ .

Sketch of the proof:

(i) If  $u = 0$  for  $x_N = 0$  then we can extend  $u$  by zero to the whole  $C_N$ ; then  $u_\lambda(x) = u(x_1, \dots, x_{N-1}, x_N + \lambda) \rightarrow u(x)$  in  $W^{1,p}(C_N^-)$  if  $\lambda \rightarrow 0^+$ . Setting  $u_{\lambda,h} = u_\lambda * \omega_h$  with a mollifier  $\omega_h$  of diameter  $h$  we easily obtain  $u_{\lambda,h} \rightarrow 0$  for  $\lambda = \frac{1}{n}$ ,  $h = \frac{1}{2n}$ ,  $n \rightarrow +\infty$ , and, moreover,  $\text{supp } u_{\lambda,h} \subset C_N^-$ .

(ii) If  $u = 0$  in some neighbourhood of  $\bar{\Gamma}$  then choosing  $h = h(n)$  small enough we obtain that the sequence  $u_{-1/n, h(n)}$  has the desired property.

(iii) General case can be reduced to the cases (i), (ii) via partition of unity as follows: We cover  $\partial\Gamma$  by a finite number of open sets  $U_i \subset \bar{U}_i \subset C_N$  ( $i = 1, \dots, r$ ) such that  $\partial\Gamma \cap U_i$  is a graph (of a function of  $N-2$  variables). We add open sets  $U_0, U_{r+1}$  in such a manner that  $U_0, \dots, U_{r+1}$  forms covering of  $\text{supp } u$  and then we consider functions  $u_i = u \varphi_i$ , with  $\varphi_i$  being a partition of unity. The function  $u_0$  can be handled as in (i), and as for the function  $u_{r+1}$ , there can be applied (ii). The case  $1 \leq i \leq r$  can be dealt with as (ii) after a suitable shift in the direction of the plane  $x_N = 0$ .

3. Theorem. Let  $\Omega \subset \mathbb{R}_N$  be a bounded set with a Lipschitzian boundary. Let  $\Gamma \subset \partial\Omega$  be a relatively open set with a continuous boundary, and let  $M_\Gamma = \{u \in W^{1,p}(\Omega) : \text{trace } u = 0 \text{ on } \Gamma\}$  ( $1 \leq p < +\infty$ ).

Then the set  $\{u \in C^\infty(\Omega) : \text{supp } u \cap \Gamma = \emptyset\}$  is dense in  $M_\Gamma$ .

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This theorem is a consequence of the lemma above (cf. [2]) and can be proved using a partition of unity and the Lipschitz mapping  $y_i = c_i x_i$  ( $i = 1, \dots, N-1$ ),  $y_N = c_N(x_N - a(x_1, \dots, x_{N-1}))$  where  $a$  is a function (locally) describing the boundary  $\partial\Omega$  and  $c_i$  are "normalising coefficients".

### References

1. J. Nečas Les méthodes directes en théorie des équations elliptiques, Academia, Prague, 1967.
2. P. Doktor. On the density of smooth functions in certain subspaces of Sobolev space. *Comment. Math. Univ. Carolinae* 14,4 (1973), 609-622.

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