

OPTIMAL QUADRATURE FORMULAE FOR DIFFERENTIABLE FUNCTIONS

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1. Introduction. Let

$$(1) \quad Ly := y^{(r)} + a_{r-1}(x)y^{(r-1)} + \dots + a_0(x)y, \quad a \leq x \leq b,$$

be a given linear differential operator with coefficients $a_j \in C^{(j)}[a, b]$, $j = 0, \dots, r-1$. Define the classes

$$LW_q^r[a, b] := \left\{ f \in C^{(r-1)}[a, b] : f^{(r-1)} \text{ abs. cont., } \|Lf\|_q \leq 1 \right\}.$$

Given the multiplicities $(\nu_k)_1^n$, $1 \leq \nu_k \leq r$, and some specified conditions \mathcal{B} on the boundary terms, we study here the question of existence and characterization of a quadrature formula (q.f.) of the form

$$(2) \quad I(f) := \int_a^b f(x)dx \approx \sum_{j=0}^{r-1} A_j f^{(j)}(a) + \sum_{j=0}^{r-1} B_j f^{(j)}(b) + \sum_{k=1}^n \sum_{\lambda=0}^{\nu_k-1} a_{k\lambda} f^{(\lambda)}(x_k) =: Q(\mathcal{B}; f)$$

with minimal error in $LW_q^r[a, b]$ for $1 < q \leq \infty$.

Minimizing the error

$$R_q(\bar{a}, \bar{x}) := \sup \left\{ |I(f) - Q(\mathcal{B}; f)| : f \in LW_q^r[a, b] \right\}$$

of (2) we treat as free parameters not only the coefficients A_j , B_j , $a_{k\lambda}$ but also the location of the nodes $a < x_1 < \dots < x_n < b$. The extremal q.f. is called optimal of type $(\nu_1, \dots, \nu_n; \mathcal{B})$. The following two important kinds of boundary conditions \mathcal{B} are covered:

(i) Periodic Boundary Conditions (PBC)

$$A_j = -B_j, \quad j = 0, \dots, r-1.$$

(ii) Zero Boundary Conditions (ZBC)

$$A_j = 0, \quad j = \nu, \nu+1, \dots, r-1 \quad (0 \leq \nu \leq r)$$

$$B_j = 0, \quad j = \mu, \mu+1, \dots, r-1 \quad (0 \leq \mu \leq r).$$

Denote by $\Omega(\nu_1, \dots, \nu_n)$ the set of all systems

$$(3) \quad \bar{x} = \begin{pmatrix} x_1, \dots, x_n \\ \nu_1, \dots, \nu_n \end{pmatrix}$$

of points $(x_k)_1^n$, $a < x_1 < \dots < x_n < b$, of multiplicities ν_1, \dots, ν_n , respectively. The nodes \bar{x} are said to be optimal of type $(\nu_1, \dots, \nu_n; \mathcal{B})$ in $LW_q^r[a, b]$ if

$$R_q(\bar{x}) = \inf \left\{ R_q(\bar{z}) : \bar{z} \in \Omega(\nu_1, \dots, \nu_n) \right\},$$

where

$$R_q(\bar{z}) := \inf \left\{ R_q(\bar{a}, \bar{z}) : \text{over all systems } \bar{a} \text{ of coefficients } \{a_{k\lambda}\} \text{ and } \{A_j\}, \{B_j\}, \text{ satisfying the conditions } \mathcal{B} \right\}.$$

We assume in this paper that the operator L has the property W of Polya (see [7], p.426) in $[a, b]$. Then the null space N_L of L is an Extended Complete Tchebycheff (ECT) space and there exist r strictly positive functions $w_i \in C^{(r)}[a, b]$, $i = 1, \dots, r$, such that L can be factorized as

$$Lf = D_r D_{r-1} \dots D_1 f,$$

where the differential operators D_i are defined by

$$D_i(f(x)) := w_i(x) \frac{d}{dx} (f(x)/w_i(x)), \quad i = 1, \dots, r$$

(see [4], p.379). Denote, for convenience $D^{[j]} := D_j D_{j-1} \dots D_1$, $j = 1, \dots, r$.

Following the method developed by B.Bojanov in [1,2,3], we prove the existence of optimal quadrature formulae of arbitrary fixed type $(\nu_1, \dots, \nu_n; \mathcal{B})$ and give complete characterization of their coefficients. Our results extend those of K.Oskolkov [6] and M.Chahkiev [8], who treat the special case of L with characteristic polynomial having only real zeros, $\nu_1 = \dots = \nu_n = 1$, $\mathcal{B} = \text{PBC}$. In the next sections we sketch the main steps of the proof.

2. Quadrature formulae and L-monosplines. The proof of our existence theorem relies upon the connection between L-monosplines of least L_p -deviation and optimal quadrature formulae in the classes $LW_q^r[a, b]$. We assume that $1/q + 1/p = 1$, $1 \leq p < \infty$.

We briefly describe this connection below. Consider the L-monospline $S(t)$ of the form

$$(4) \quad S(t) = \int_t^x G_L(\tau; t) d\tau - \sum_{j=0}^{r-1} B_j G_L^{(j)}(b; t) - \sum_{k=1}^n \sum_{\lambda=0}^{v_k-1} a_{k\lambda} G_L^{(\lambda)}(x_k; t),$$

where $G_L(x; y)$ is the Green's function associated with L (see [7], p.424) and boundary conditions \mathcal{B} of the type

$$(5) \quad \begin{aligned} (i) \quad & S^{(j)}(a) = S^{(j)}(b), \quad j = 0, \dots, r-1 \quad (\text{PBC}), \\ (ii) \quad & S^{(j)}(a) = 0, \quad j = 0, \dots, r-\nu-1, \\ & S^{(j)}(b) = 0, \quad j = 0, \dots, r-\mu-1 \quad (\text{ZBC}). \end{aligned}$$

Suppose that $f \in \mathcal{L}W_q^r[a, b]$. Integration by parts produces the identity

$$(6) \quad \int_a^b S(t) Lf(t) dt = \int_a^b f(t) dt - \sum_{j=0}^{r-1} A_j f^{(j)}(a) - \sum_{j=0}^{r-1} B_j f^{(j)}(b) - \sum_{k=1}^n \sum_{\lambda=0}^{v_k-1} a_{k\lambda} f^{(\lambda)}(x_k).$$

This expression suggests a quadrature formula of the type (2). Let $\mathcal{S}(\bar{x}; \mathcal{B})$ denote the collection of L-monosplines $S(t)$ with knots \bar{x} , satisfying the boundary conditions \mathcal{B} . Now suppose that $S \in \mathcal{S}(\bar{x}; \mathcal{B})$. Then (6) induces a q.f. of the type (2) which is exact for all $f \in N_L$. Conversely, let (2) be given with arbitrary fixed coefficients $A_j, B_j, a_{k\lambda}$, satisfying the relation $I(f) = Q(\mathcal{B}; f)$ for $f \in N_L$. Then there exists $\tilde{S} \in \mathcal{S}(\bar{x}; \mathcal{B})$ in the form (4)-(5) and the remainder term of formula (2) is $\int_a^b S(t) Lf(t) dt$. Formula (2) can be expressed in terms of $D^{[i]}$ derivatives, since by Leibniz's rule, there exist c_{i0}, \dots, c_{ii-1} such that for all f

$$D^{[i]} f(x) = f^{(i)}(x) + \sum_{j=0}^{i-1} c_{ij}(x) f^{(j)}(x).$$

Then the resulting q.f. will be of the form

$$(7) \quad Q(\mathcal{B}; f) = \sum_{j=0}^{r-1} \alpha_j D^{[j]} f(a) + \sum_{j=0}^{r-1} \beta_j D^{[j]} f(b) + \sum_{k=1}^n \sum_{\lambda=0}^{v_k-1} \ell_{k\lambda} D^{[\lambda]} f(x_k).$$

Using Peano's remainder formula (see [5], p.10), the L-monospline $S(t)$ corresponding to this q.f. can be written as

$$(8) \quad S(t) = \int_t^b G_L(\tau; t) d\tau - \sum_{j=0}^{r-1} \beta_j D^{[j]} G_L(b; t) - \\ - \sum_{k=1}^n \sum_{\lambda=0}^{\nu_k-1} \ell_{k\lambda} D^{[\lambda]} G(x_k; t).$$

It is clear from the described one-to-one correspondence between q.f. and L-monosplines that

$$R_q(\bar{x}) = \inf \left\{ \sup \left\| \int_a^b S(t) Lf(t) dt \right\| : f \in LW_q^r[a, b] \right\} : S \in \mathcal{S}(\bar{x}; \mathcal{R}) = \\ = \min \left\{ \|S\|_p : S \in \mathcal{S}(\bar{x}; \mathcal{R}) \right\} = \\ = \|S(\bar{x}; \cdot)\|_p.$$

Moreover, the existence of an optimal quadrature formula of the type $(\nu_1, \dots, \nu_n; \mathcal{R})$ in $LW_q^r[a, b]$ is equivalent to the existence of a L-monospline of least L_p deviation of the type $(\nu_1, \dots, \nu_n; \mathcal{R})$.

3. Characterisation results and existence. Denote for convenience,

$$LW_0(\bar{x}; \mathcal{R}) := \left\{ f \in LW_q^r[a, b] : f \text{ satisfies FBC or ZBC, } \right. \\ \left. f^{(\lambda)}(x_k) = 0, k = 1, \dots, n, \lambda = 0, \dots, \nu_k - 1 \right\}.$$

The following lemmas characterize the optimal quadrature formula.

Lemma 1. Given \mathcal{R} and $1 < q \leq \infty$, for every fixed system of nodes $\bar{x} \in \Omega(\nu_1, \dots, \nu_n)$ there exists a unique function $F(\bar{x}; t) \in LW_0(\bar{x}; \mathcal{R})$, such that $I(F(\bar{x}; \cdot)) = R_q(\bar{x})$.

Lemma 2. Let $1 \leq p < \infty$. Suppose that the knots (3) are optimal of the type $(\nu_1, \dots, \nu_n; \mathcal{R})$. Then

$$a_{k, \nu_k - 1} F^{(\nu_k)}(\bar{x}; x_k) = 0, \text{ for } \nu_k < r \text{ and} \\ S(\bar{x}; x_k - 0) = S(\bar{x}; x_k + 0), \text{ for } \nu_k = r, \text{ if } r \text{ is even.}$$

Denote the number of zeros of S in (a, b) , counting multiplicities, by $Z(S; (a, b))$. Let us also set $\sigma_k = 1$ if ν_k is odd, and zero otherwise.

Lemma 3. Let $S(t)$ be an arbitrary L-monospline of the form (8) with $a < x_1 < \dots < x_n < b$. Then

$$Z(S; (a, b)) \leq r + \sum_{k=1}^n (\nu_k + \sigma_k) - S^+(S(b), D^{[1]} S(b), \dots, D^{[r]} S(b)) \\ - S^+(S(a), -D^{[1]} S(a), \dots, (-1)^r D^{[r]} S(a)).$$

Further,

$$(9) \quad Z(S; (-\infty, +\infty)) \leq r + \sum_{k=1}^n (\nu_k + \sigma_k).$$

Moreover, when equality holds in (9), the next two statements are

valid :

If ν_k is odd then $l_{k\lambda} > 0$, $\lambda = 0, 2, \dots, \nu_k - 1$,
 $(-1)^{r_D} D^{[i]} S(t) > 0$, $i = 0, \dots, r$, for $t >$ the last zero,
 $(-1)^{i_D} D^{[i]} S(t) > 0$, $i = 0, \dots, r$, for $t <$ the first zero.

The proof of this result can be seen in [7], p.404.

Lemma 4. Let the multiplicities $(\nu_k)_1^n$ satisfy the inequalities $1 \leq \nu_k \leq r$, $k = 1, \dots, n$ and the following condition

(10) ν_k is even if $\nu_k < r$.

Then, for every system of knots $\bar{x} \in \Omega(\nu_1, \dots, \nu_n)$ the L-monomiospline $S(\bar{x}; t)$ has a maximal number of zeros.

Lemma 5. Let the multiplicities ν_k satisfy the condition (10). Then

$F(\bar{x}; t) \geq 0$, $t \in [a, b]$; $F(\bar{x}; t) > 0$, $t \notin (a, x_1, \dots, x_n, b)$,

$F^{(\nu_k)}(\bar{x}; x_k) > 0$ for $\nu_k < r$,

$F^{(\nu)}(\bar{x}; a) > 0$, $(-1)^{\nu} F^{(\mu)}(\bar{x}; b) > 0$, if $B = ZBC$.

Now, using these lemmas, it is seen as in [1], that the following theorems hold.

Theorem 1. Let $1 < q \leq \infty$ and let $(\nu_k)_1^n$ be arbitrary fixed integer numbers satisfying the inequalities $1 \leq \nu_k \leq r$, $\nu_1 + \nu_2 + \dots + \nu_n \geq r$. Then there exists an optimal quadrature formula of the form (2) (and (7)) in the class $LW_q^r[a, b]$. Moreover, the nodes and the coefficients of this q.f. satisfy the relations

$$(11) \quad \left\{ \begin{array}{l} a < x_1 < \dots < x_n < b, \\ l_{k, \nu_k - 1} = 0, l_{k\lambda} > 0, \lambda = 0, 2, \dots, \nu_k - 2, \\ a_{k, \nu_k - 1} = 0, a_{k, \nu_k - 2} > 0, \\ l_{k\lambda} > 0, \lambda = 0, 2, \dots, \nu_k - 1, a_{k, \nu_k - 1} > 0, \text{ if } \nu_k \text{ is odd,} \\ \alpha_j > 0, j = 0, \dots, \nu - 1, A_{\nu - 1} > 0, \\ (-1)^j \beta_j > 0, j = 0, \dots, \mu - 1, (-1)^{\mu - 1} B_{\mu - 1} > 0. \end{array} \right\} \text{if } \nu_k \text{ is even,}$$

Theorem 2. Let $1 < q \leq \infty$ and let $(\nu_k)_1^n$ be arbitrary fixed integer numbers satisfying the inequalities $1 \leq \nu_k \leq r$, $\nu_1 + \dots + \nu_n \geq 1$. Then there exists an optimal quadrature formula of the form

$$I(f) \approx \sum_{k=1}^n \sum_{\lambda=0}^{\nu_k-1} l_{k\lambda} D^{[\lambda]} f(x_k) \quad (\text{or } I(f) \approx \sum_{k=1}^n \sum_{\lambda=0}^{\nu_k-1} a_{k\lambda} f^{(\lambda)}(x_k)).$$

in the class $\tilde{LW}_q^r[a, b] := \{ f \in LW_q^r[a, b] : f \text{ is } (b-a) \text{- periodic} \}$.

Moreover, the coefficients of the optimal quadrature formula satisfy (11).

Using the relation between quadrature formulae and L -monosplines one can be reformulate Theorems 1 and 2 as existence theorems for L -monosplines of a preassigned type with minimal L_p - norm.

Acknowledgement. I wish to thankfully acknowledge the constant attention and valuable suggestions of Dr. B. Bojanov in the course of preparation of this paper.

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