

## Local spline approximation and nonparametric density estimation

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**Abstract.** This note gives the order of approximation of  $L^p$  functions on the real line by certain linear local positive spline operators. By means of these operators characterizations of Lipschitz classes and of the saturation class are given. The linear method in question is used to construct simple for computation estimators of densities and distributions. Moreover, it follows that this method of estimation is optimal as far as the mean  $L^p$  deviation is considered.

**1. Introduction.** In this note we consider approximation by splines of order  $r \geq 1$  i.e. of degree  $r - 1$  corresponding to the uniform mesh  $\{t_i = ih, i \in Z\}$ , with the step  $h > 0$ , where  $Z$  is the set of all integers. It is assumed that all the knots are simple. All the  $B$ -splines corresponding to this mesh can be defined by means of the cardinal spline of order  $r$

$$N^{(r)}(x) = r[0, \dots, r; (\cdot - x)_+^{r-1}],$$

where  $[s_0, \dots, s_r; f]$  denotes the divided difference of  $f$  taken at the points  $s_0, \dots, s_r$ . Namely,

$$N_{i,h}^{(r)}(x) = N^{(r)}\left(\frac{x - t_i}{h}\right).$$

It is well known that

$$(1.1) \quad \sum_{i \in Z} N_{i,h}^{(r)}(x) = 1 \quad \text{for } x \in R,$$

where  $R = (-\infty, \infty)$ . For later convenience introduce

$$M_{i,h}^{(r)}(x) = \frac{1}{h} N_{i,h}^{(r)}(x).$$

Now, since

$$\int_R N^{(r)}(x) dx = 1,$$

it follows that

$$(1.2) \quad \int_R M_{i,h}^{(r)}(x) dx = 1.$$

The approximating operators can now be defined for any  $f \in L_{loc}^1(R)$  as follows

$$(1.3) \quad Q_h^{(r)}(f; x) = \sum_{i \in Z} (f, M_{i,h}^{(r)}) N_{i,h}^{(r)}(x),$$

where

$$(f, g) = \int_R f(x)g(x) dx.$$

Since the coefficient functional

$$f \mapsto (f, M_{i,h}^{(r)})$$

is local for each admissible pair  $i, h$  i.e. its support is contained in the support of  $N_{i,h}^{(r)}$ , these operators are *local spline operators* in de Boor's terminology [2]. It also follows by (1.1) and (1.2) that these operators have in addition the following properties:  $Q_h^{(r)}(f) \geq 0$  for  $f \geq 0$  and  $Q_h^{(r)}(1) = 1$ . It is important to realize that they are not projections except for the case  $r = 1$  (see [5]) but their  $L^p$  norms are equal to 1, i.e. for all  $1 \leq p \leq \infty$

$$\|Q_h^{(r)}(f)\|_p \leq \|f\|_p \quad \text{for } f \in L^p(R),$$

where

$$\|f\|_p = \left( \int_R |f(x)|^p dx \right)^{\frac{1}{p}}.$$

Moreover, for  $f \in L^1(R)$

$$\int_R f = 1 \quad \text{implies} \quad \int_R M_{i,h}^{(r)} = 1.$$

Consequently, the operator

$$Q_h^{(r)} : L^1(R) \rightarrow L^1(R)$$

takes probability densities into probability densities, and it appears to be good for constructing nonparametric density estimators.

We now assume that we are given a probability space  $(\Omega, \mathcal{F}, Pr)$  and a simple sample of size  $n$  i.e. a sequence  $X_1, \dots, X_n$  of i.i.d. real valued random variables such that their common distribution has a density  $f$ . The standard way of producing estimators for  $f$  is given by formula

$$(1.4) \quad f_{h,n}(x) = \frac{1}{n} \sum_{j=1}^n Q_h^{(r)}(x, X_j),$$

where

$$(1.5) \quad Q_h^{(r)}(x, y) = \sum_{i \in \mathbb{Z}} M_{i,h}^{(r)}(x) N_{i,h}^{(r)}(y).$$

Clearly, the kernel  $Q_h^{(r)}(x, y)$  is nonnegative and symmetric, and in each variable it is a linear combination of  $B$ -splines. Thus, its values can be calculated by the numerically stable algorithm due to C. de Boor, M. G. Cox and L. Mansfield (see e.g. [2]).

Next section contains the main result on order of approximation by the local spline operators in question. Section 3 contains one of the results on estimation of densities. More details on nonparametric density estimation by splines will be published elsewhere in our joint work with G. Krzykowski.

**2. Order of approximation by the local spline operators.** In order to state the results we recall the definition of the modulus of smoothness of order  $k$

$$\omega_{k,p}(f; \delta) = \sup_{|t| < \delta} \|\Delta_t^k f\|_p,$$

where  $\Delta_t^k$  is the  $k$ -th order progressive difference with step  $t$ .

To prove the main theorem of this section the following is needed.

**LEMMA 2.1.** *Let  $f$  satisfy the Lipschitz condition*

$$\omega_{1,\infty}(f; \delta) \leq M \cdot \delta \quad \text{for } \delta > 0.$$

Then

$$\|f - Q_h^{(r)}(f)\|_\infty \leq M \cdot r \cdot h \quad \text{for } h > 0.$$

**PROOF:** We may assume without loss of generality that for given  $x \in R$  there is  $i \in \mathbb{Z}$  such that  $t_i < x < t_{i+1}$ . Now,

$$\begin{aligned} f(x) - Q_h^{(r)}(f)(x) &= \sum_{i-r < j \leq i} N_{j,h}^{(r)}(x) \int_{t_j}^{t_{j+r}} M_{j,h}^{(r)}(y) (f(x) - f(y)) dy, \\ |f(x) - Q_h^{(r)}(f)(x)| &\leq M \sum_{i-r < j \leq i} N_{j,h}^{(r)}(x) \int_{t_j}^{t_{j+r}} M_{j,h}^{(r)}(y) |x - y| dy, \\ &\leq M \cdot r \cdot h \sum_{i-r < j \leq i} N_{j,h}^{(r)}(x) \int_{t_j}^{t_{j+r}} M_{j,h}^{(r)}(y) dy = M \cdot r \cdot h. \end{aligned}$$

In what follows  $W_p^k(R)$  denotes the Sobolev space over  $R$  with the index of smoothness  $k$  and the exponent of integration  $p$ .

**LEMMA 2.2.** *Let  $r \geq 2$  and let  $f_0$  be a linear function on  $R$ . Then*

$$Q_h^{(r)}(f_0) = f_0.$$

**PROOF:** We know already that the operator  $Q_h^{(r)}$  reproduces constants. It is therefore sufficient to prove the Lemma for  $f_0(x) = x$ . However, by known formula (see e.g. [8])

$$f_0(x) = \sum_{i \in \mathbb{Z}} h(i + \frac{r}{2}) N_{i,h}^{(r)}(x).$$

On the other hand, Peano's formula for divided difference gives

$$\int_R y M_{i,h}^{(r)}(y) dy = \frac{1}{1+r} [ih, \dots, (i+r)h; s^{r+1}] = (i + \frac{r}{2})h,$$

whence by the previous identity and by the definition of  $Q_h^{(r)}$  we infer the desired equality.

Next lemma was earlier applied in [7] (see also [1]) in the case of Bernstein polynomials and as it appears it is natural to use the same idea in the case of our local spline operators.

LEMMA 2.3. Let  $f \in W_p^2(R)$  and let  $\text{support } f \subset \langle a, b \rangle$  for some finite  $a, b \in R$ . Then for all  $x \in R$  we have

$$f(x) = - \int_R K_{a,b}(x, y) D^2 f(y) dy,$$

where  $D = \frac{d}{dx}$  and for  $y \in \langle a, b \rangle$

$$K_{a,b}(x, y) = \frac{1}{b-a} \min(x-a, y-a) \min(b-x, b-y).$$

PROOF: Using Peano's formula for divided differences

$$[a, x, b; f] = \frac{1}{2} \int_R M(a, x, b; y) D^2 f(y) dy$$

we find

$$f(x) = \frac{b-x}{b-a} f(a) + \frac{x-a}{b-a} f(b) - \int_a^b K_{a,b}(x, y) D^2 f(y) dy,$$

and this completes the proof.

THEOREM 2.4. Let  $r \geq 2$ ,  $p, 1 \leq p \leq \infty$ , be given and let  $f \in L^p$ . Then

$$\|f - Q_h^{(r)}(f)\|_p \leq 8(2r^2 + 1) \omega_{2,p}(f; h) \quad \text{for } 0 < h < 1.$$

PROOF: Since the  $L^p$ -norms of the operators  $Q_h^{(r)}$  are equal to 1 and  $\omega_{2,p}(f; h) \leq 4\|f\|_p$  it is sufficient to prove the result for  $f \in L^p(R)$  with compact support. Using Steklov means we define in the standard way the smoothing of  $f$  of order  $k$ , i.e.

$$g(x) = - \sum_{j=1}^k (-1)^{j+k} \binom{k}{j} \int_0^1 \cdots \int_0^1 f(x + jh(s_1 + \cdots + s_k)) ds_1 \dots ds_k.$$

The function  $g$  is in  $W_p^k(R)$ . If the support of  $f$  is contained in  $\langle a', b' \rangle$ , then the support of  $g$  is contained in  $\langle a, b \rangle$  with  $b' = b$  and  $a = a' - k^2 h$ . Moreover,

$$f(x) - g(x) = \int_0^1 \cdots \int_0^1 \Delta_{h(s_1 + \cdots + s_k)}^k f(x) ds_1 \dots ds_k,$$

whence

$$(2.5) \quad \|f - g\|_p \leq k^k \omega_{k,p}(f; h).$$

It also follows that

$$D^k g(x) = - \sum_{j=1}^k (-1)^{j+k} \frac{1}{(jh)^k} \binom{k}{j} \Delta_{jh}^k f(x).$$

Thus,

$$(2.6) \quad h^k \|D^k g\|_p \leq 2^k \omega_{k,p}(f; h).$$

In what follows it is enough to take  $k = 2$ . The next step is to prove

$$(2.7) \quad \|g - Q_k^{(r)}(g)\|_p \leq (2r^2)h^2 \|D^2 g\|_p.$$

The locality of the operators  $Q_k^{(r)}$  and Lemmas 2.2 and 2.3 imply

$$(2.8) \quad Q_k^{(r)}(g)(x) - g(x) = \int_{|x-y| < rh} (K_{a,b}(x, y) - Q_k^{(r)}(K_{a,b}(\cdot, y)(x))) D^2 g(y) dy.$$

Now, the function  $K_{(a,b)}(\cdot, y)$  for fixed  $y \in \langle a, b \rangle$  satisfies Lipschitz condition in the  $L^\infty$  norm with the constant  $M = 1$ . Lemma 2.1 and (2.8) then give

$$|Q_k^{(r)}(g)(x) - g(x)| \leq 2r^2 h^2 \frac{1}{2rh} \int_{|x-y| < rh} |D^2 g(y)| dy,$$

and this implies (2.7). Applying now the triangle inequality to the identity

$$f - Q_k^{(r)}(f) = (f - g) + (g - Q_k^{(r)}(g)) + Q_k^{(r)}(g - f)$$

we obtain

$$(2.10) \quad \|f - Q_k^{(r)}(f)\|_p \leq 2\|f - g\|_p + \|g - Q_k^{(r)}(g)\|_p.$$

Now, (2.10), (2.5), (2.6) and (2.7) give the inequality stated in the theorem.

Using the same methods as in [3], [4] we are able to establish the following

**THEOREM 2.11.** *Let us introduce for given natural  $r$  and  $k$  the equivalence*

$$(2.12) \quad \|f - Q_k^{(r)}\|_p = O(h^\alpha) \text{ as } h \rightarrow 0_+ \iff \omega_{k,p}(f; h) = (h^\alpha) \text{ as } h \rightarrow 0_+.$$

Then, condition (2.12) holds in the following domains:

- (i)  $r \geq 2$ ,  $k = 2$ ,  $0 < \alpha < 1 + \frac{1}{p}$ ,  $1 \leq p < \infty$ .
- (ii)  $r \geq 3$ ,  $k = 2$ ,  $0 < \alpha < 2$ ,  $1 \leq p \leq \infty$ .

**3. Density estimation.** To formulate the last result we introduce for  $0 < \alpha \leq 2$  and  $1 \leq p \leq \infty$

$$\psi(\alpha, p) = \begin{cases} \frac{1}{2\alpha+1}, & \text{if } 1 \leq p < 2; \\ \frac{1}{p\alpha+p-1}, & \text{if } 2 \leq p < 2 + \frac{1}{\alpha+1}; \\ \frac{1}{2\alpha+2}, & \text{if } p \geq 2 + \frac{1}{\alpha+1}. \end{cases}$$

**THEOREM 3.1.** Let  $1 \leq p \leq \infty$  and let  $f$  be a density on  $R$ . Let  $\alpha$ ,  $0 < \alpha < 2$ , and  $\beta$ ,  $0 < \beta \leq \psi(\alpha, p)$  be given. Moreover, let  $h = n^{-\beta}$ . Then the following conditions are equivalent:

(i) 
$$\omega_{3,p}(f; \delta) = O(\delta^\alpha) \quad \text{as } \delta \rightarrow 0_+,$$

(ii) 
$$(E\|f - f_{m,n}\|_p^p)^{\frac{1}{p}} = O\left(\frac{1}{n^{\alpha\beta}}\right) \quad \text{as } n \rightarrow \infty,$$

where  $E$  is the expectation operator with respect to the given probability space.

**EXAMPLE:** Direct computation shows that for the arcsin law density, i.e. for

$$f_0(x) = \frac{1}{\pi} \frac{1}{\sqrt{x(1-x)}}, \quad x \in \langle 0, 1 \rangle,$$

and  $f_0$  being zero elsewhere, we have for  $1 \leq p < 2$  and for each  $k \geq 1$

$$\omega_{k,p}(f_0; \delta) \sim \delta^{\frac{1}{p} - \frac{1}{2}} \quad \text{as } \delta \rightarrow 0_+.$$

Thus, for this density  $\alpha = \frac{1}{p} - \frac{1}{2}$  and the optimal choice for  $\beta$  is  $\beta = \frac{p}{2}$ .

The most interesting is the case  $p = 1$ . The optimal choice for  $\beta$ , given  $\alpha$  in  $(0, 2)$ , is  $\beta = \frac{1}{\alpha+1}$ . In particular, for  $\alpha = 2$  we obtain the celebrated exponent  $\alpha\beta = \frac{2}{3}$ . For more detailed discussion of these questions we refer e.g. to [6].

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