

STABILITY RESULTS FOR A CLASS OF NONLINEAR DIFFERENTIAL  
INCLUSIONS IN BANACH SPACES

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1. Introduction. We consider differential inclusions in nonseparable Banach spaces with dissipative type conditions on the right-hand side. Such type of differential inclusions is considered in [5]. Where the existence of solutions has been proved, adapting the Euler-Cauchy method, presented in [1]. In this work the Kamke function  $g: R \times R^+ \rightarrow R^+$  is used, where  $g(\cdot, s)$  is measurable,  $g(t, \cdot)$  - continuous. The differential equation  $\dot{s}(t) = g(t, s(t))$  has a solution on the whole interval  $[t_0, t_1]$  for every initial condition  $s(t_0) = s_0$ ,  $g(t, 0) = 0$ , and  $s(t) \equiv 0$  is the unique solution of the equation with the initial condition  $s(t_0) = 0$ .

Our results are new even in  $R^n$ . We prove a theorem corresponding to theorem 2.4.1. in [1].

Theorem ([1]). Assume that  $R_0 := [a, b] \times E$

(i)  $f \in C[R_0, E]$ ,  $|f(t, x)| \leq M$  on  $R_0$  and  $\alpha = \min(a, b/(M+1))$

(ii)  $\min_{v \in J(x-y)} \langle v, f(t, x) - f(t, y) \rangle \leq g(t, |x-y|) \cdot |x-y|$

where  $g$  is the Kamke function. Then?

1) There exists an unique solution of  $\dot{x} = f(t, x)$  for each initial condition  $x_0$  on  $[t_0, t_1]$

2) This solution depends continuously on  $f$  and  $x_0$ .

2. Notations. Let  $B$  and  $B^*$  be a Banach space and its conjugate. We denote by  $\mathcal{d}_f B$  and by  $\mathcal{d}co_f B$  the set of all closed bounded subsets of  $B$  and the set of all convex sets in  $\mathcal{d}_f B$ . The duality product between  $B$  and  $B^*$  will be denoted as  $\langle \cdot, \cdot \rangle$ . By  $\delta(\cdot, \mathcal{U})$  we mean the support function of the set  $\mathcal{U}$ . For the set  $C$  denote by  $\mathcal{d}C$  and  $coC$  the closed, respectively the convex hull of  $C$ . The function  $h(A, B)$  is the Hausdorff distance between the closed sets  $A$  and  $B$ . Further  $j: B \rightarrow \mathcal{d}co_f B^*$  is the duality mapping, i. e. for each  $x \in B, y \in j(x) \langle y, x \rangle = |x|^2$ , where  $|x|$  is the norm of  $x$ . When  $a \in B, A \in \mathcal{d}_f B$  then  $d(a, A) := \inf_{b \in A} |b - a|$ . The interval  $I := [0, T]$  is closed in  $\mathbb{R}$ . Through  $C(I, B)$  denote the space of all continuous functions on  $I$  with values in  $B$ , provided with the norm  $\|x(\cdot)\| := \max_{t \in I} |x(t)|$ . Through  $L_1(I, B)$  denote the space of all Bochner integrable functions from  $I$  to  $B$ , equipped with the norm  $\|x(\cdot)\|_{L_1} := \int_I |x(z)| dz$

3. The system description and the main result. Here we consider the system:

(1)  $\dot{x}(t) \in F(t, x(t)), x(0) = x_0, t \in I$ , under the assumptions:

A1. The function  $F(\cdot, \cdot)$  from  $I \times B$  to  $\mathcal{d}_f B$  is strongly measurable in  $t$  for each  $x$  and satisfies Scorza-Dragnoni condition on the bounded subsets of  $I \times B$ . ([3])

A2. The space  $B$  is such that  $j$  is upper semicontinuous with respect to the strong topologies of  $B$  and  $B^*$ .

A3. If  $x, y$  belong to  $B$  and  $\hat{x} \in F(t, x)$ , then for every  $\varepsilon > 0$  and  $J \in j(x - y)$  there exists  $\hat{y}_\varepsilon \in F(t, y)$  such that:

a)  $\langle J, \hat{x} - \hat{y}_\varepsilon \rangle \leq g(t, |x - y|) |x - y| + \varepsilon$

b)  $|\hat{x} - \hat{y}_\varepsilon| \leq \varepsilon + f(|x - y|)$ , where  $f: \mathbb{R}^+ \rightarrow \mathbb{R}^+$  is continuous and  $f(0) = 0$ .

Now we present our main result:

Theorem 1. Let  $\{F_n(t, x)\}_{n=1}^{\infty}$  be a sequence of maps with closed values in  $B$ , which satisfy A1-A3 (with the same  $\varphi$ ) and

$$h(F_n(t, x), F(t, x)) \xrightarrow{n \rightarrow +\infty} 0$$
 uniformly on each closed bounded subset of  $I \times B$ . Then:

i) Each solution  $y(\cdot)$  of (1) is a uniform limit of the corresponding solutions of

$$(2) \quad \dot{x}(t) \in F_n(t, x(t)), \quad x(0) = x_0.$$

ii) For every uniformly converging sequence  $\{y_n(\cdot)\}_{n=1}^{\infty}$  of the corresponding solutions of (2) with limit  $y(\cdot)$  there exists a uniformly convergent sequence of solutions of (1) with the same limit.

Further the set of solutions of (2) depends continuously on the initial condition  $x_0$ . ■

#### 4. Proof of the main result.

We essentially use theorem 2 from [2], which says:

Theorem ([2]). Let  $F$  and  $G$  mapping  $I$  into  $d_2 B$  be strongly measurable, and  $f(\cdot)$  be strongly measurable selection of  $F(\cdot)$ .

Then for each positive  $\varepsilon$  and each strongly measurable essentially bounded function  $s: I \rightarrow B^*$  there exists a strongly measurable selection  $g(\cdot)$  of  $G(\cdot)$  such that:

$$\langle s(t), f(t) - g(t) \rangle < \delta(s(t), F(t)) - \delta(s(t), G(t)) + \varepsilon;$$

One can choose  $g$  such that:

$$\langle s(t), f(t) - g(t) \rangle > \delta(s(t), F(t)) - \delta(s(t), G(t)) - \varepsilon;$$

Definition 1. Let  $\varepsilon > 0$ . The function  $y(\cdot)$  is said to be  $\varepsilon$ -solution of (1) if  $y(\cdot)$  is differentiable a. e. in  $I$  and satisfies the following conditions:

i)  $y(t) = x_0 + \int_0^t \dot{y}(\tau) d\tau$ ; here  $\dot{y}$  denotes the derivative of  $y$ .

ii)  $d(\dot{y}(t), F(t, y(t))) < f_\varepsilon$  a. e. in  $I$ , here  $f_\varepsilon$  is a positive func-

tion with  $L_1$  norm less than  $\varepsilon$ .

The Euler broken are defined only for continuous functions. We shall give a proper definition also in case  $F(t, x)$  is strongly measurable. Let  $\{0 = \tau_0 < \tau_1 < \dots < \tau_n = T\}$  be subdivision of  $I$ .

Definition 2. Euler broken is called any function  $z(t)$  such that

$z(t) \equiv z(\tau_i) + \int_{\tau_i}^t f(s) ds$ . Here  $f(\cdot)$  is strongly measurable selection of  $F(t, z(\tau_i))$  for  $t \in [\tau_i, \tau_{i+1})$ , which existence is proved in [2]. We determine

$z(\tau_{i+1})$  as  $\lim_{t \rightarrow \tau_{i+1}} z(t)$ ,  $z(0) = x_0$

Following [1] and [5] one can prove that under the assumptions A1-A3 for each  $\varepsilon > 0$  there exists an  $\varepsilon$ -solution and that this  $\varepsilon$ -solution is extendable on the whole interval  $I$ .

Lemma 1. Let  $\varepsilon_1, \varepsilon_2$  be positive numbers and  $x(\cdot)$  be  $\varepsilon_1$ -solution of (1). Then there exists  $\varepsilon_2$ -solution  $y(\cdot)$  of (1) such that:

$|x(t) - y(t)| \leq v(t)$ , where

$$v'(t) = g(t, |x(t) - y(t)|) + \varepsilon_1 + 2\varepsilon_2 + \varepsilon_2^2/2, \quad v(0) = 0.$$

Proof: It is known (see [6]) that the left derivative of the norm  $d|x(t) - y(t)|$  exists a. e. in  $I$  and:

$$d|x(t) - y(t)| \leq 1/|J(t)| \langle J(t), \dot{x}(t) - \dot{y}(t) \rangle, \quad \text{where}$$

$J(t) \in j(x(t) - y(t))$ . Using theorem 2 from [2] and assumptions A2 and

A3, we can construct  $\dot{y}(t)$  such that  $y(\cdot)$  satisfies the conditions

of the lemma. More precisely: let  $\{\tau_1, \dots, \tau_{n_1}\}$  be the partition of  $I$  corresponding to  $x$ . We set  $\dot{y}(t) \equiv \dot{x}(t)$  on  $[0, \tau_1)$ , where  $\tau_1$  is

the maximal number such that  $y(t)$  is an  $\varepsilon_2$ -solution ( $\varepsilon_2 > \varepsilon_1$ ). In

accordance with theorem 2 in [2] and A3 we choose  $\dot{y}(\cdot)$  as a selection

of  $F(t, y(\tau_1))$  such that:

$$d|x(t) - y(t)| \leq 1/|J(\tau_1)| \langle J(\tau_1), \dot{x}(t) - \dot{y}(t) \rangle + d(\dot{x}, F(t, x)) + d(\dot{y}, F(t, y)) + \varepsilon_2^2/2 <$$

$$< 1/|J(\tau_1)| \langle J(\tau_1), \dot{x}(t) - \dot{y}(t) \rangle + \varepsilon_1 + \varepsilon_2 + \varepsilon_2^2/2,$$

( because  $d(\dot{x}, F(t, x)) < \varepsilon_1$  and  $d(\dot{y}, F(t, y)) < \varepsilon_2$ ). Since  $j(\cdot)$  is upper semicontinuous, there exists  $\chi$  such that the conditions of lemma 1 are fulfilled also on  $[\chi_1, \chi_2)$ . Proceeding in the same manner we determine  $\chi_3$  such that the lemma is true also on  $[\chi_2, \chi_3)$  and so on. We shall prove that  $y(\cdot)$  is extendable on the whole interval  $I$ . Suppose the contrary, that is  $\chi_1 < \chi_2 < \dots < \chi_n < \dots < \chi < T$ . Using the continuity of  $x(\cdot), y(\cdot), F(t, \cdot)$  and the use of  $j(\cdot)$  one can continue as in [1] p. 39, and obtain contradiction. Then finally:

$\|x(t) - y(t)\| \leq v(t)$ , where  $\dot{v}(t) = g(t, \|x(t) - y(t)\|) + \varepsilon_1 + 2\varepsilon_2 + \varepsilon_2^2/k$  and  $v(0) = 0$ . The proof is complete. ■

Proof of theorem 1: Let  $x(\cdot)$  be a solution of (1). From the conditions of the theorem it follows that there exists a neighbourhood  $U$  of  $x$  such that  $\lim(F_i(t, z), F(t, z)) = 0$  uniformly in  $I \times U$ . Hence for every  $\varepsilon > 0$  there exists  $n(\varepsilon)$  such that  $x_n(\cdot)$  is  $\varepsilon$ -solution of (2) when  $n \geq n(\varepsilon)$ . The function  $F_i(\cdot, \cdot)$  satisfies the assumptions A1-A3, where the function  $g(\cdot, \cdot)$  is the same as one for  $F(\cdot, \cdot)$ . Then since  $g$  is continuous with respect to the second argument, following [5] we obtain that for each fixed  $\varepsilon > 0$  it is possible to determine a sequence of  $\varepsilon_n$ -solutions  $x_n(\cdot)$  of [2] (where  $\varepsilon_1 > \varepsilon_2 > \dots > \varepsilon_n > \dots \rightarrow 0$ ) such that:

$$\|x(\cdot) - x_n(\cdot)\| \leq \sum_{i=1}^{\infty} v_i(t) \quad . \text{ Here}$$

$v_i(0) = 0$   $\dot{v}_i(t) = g(t, v_i(t)) + \varepsilon_i + \varepsilon_{i+1} + \varepsilon_i^2/2$  (we set  $\varepsilon_0 = \varepsilon$ ). The difficulty is to choose  $\{x_i(\cdot)\}_{i=1}^{\infty}$ , so that it would be a Cauchy sequence. Since  $g(t, \cdot)$  is continuous, after determining  $x_i(\cdot)$  one can choose  $\dot{x}_{i+1}(\cdot)$  on each interval:  $[\chi_j^{(i+1)}, \chi_{j+1}^{(i+1)})$  as  $\varepsilon_{i+1}^2$  projection of  $x_i(\cdot)$  on the set  $F(t, x_{i+1}(\chi_i))$ . Such a choice is possible thanks to proposition 1 in [2]. Here  $\{\chi_j^{(i)}\}_{j=1}^{\infty}$  is the corresponding to  $x_i$  partition of the interval  $I$ . Now using assumption A3 one can prove that:

$$\|x_i(t) - x_{i+1}(t)\| \leq v_i(t) + \varepsilon_{i+1}^2 / 2.$$

Moreover following [5] one can prove that  $\{x_i(\cdot)\}_{i=1}^{\infty}$  is indeed a Cauchy sequence in  $L_1(I, B)$ . It follows from the properties of  $g$  (see [1]) that the first part is proved. The proof of the second part is similar. ■

Remark. If we use the generalised Euler broken and assume that  $F(\cdot, \cdot)$  is continuous we can prove such a result for arbitrary Banach space  $B$  (without assumption A2). The generalised Euler broken are constructed as the standard Euler broken, but we permit points of density for the subdivision  $\{t_i\}_{i=1}^{\infty}$ . Assuming that  $F$  has convex and (strongly) compact values one can prove theorem 1 when A3 is relaxed by:

A3\* For every  $x, y$  from  $B$  and each  $J \in j(x-y)$

$$\delta(J, F(t, x)) - \delta(J, F(t, y)) \leq g(t, |x-y|) |x-y|.$$

(see [7]).

Example. Let  $C_0$  be the space of all bounded sequences such that  $\lim_{i \rightarrow \infty} |x_i| = 0$ , provided with the norm  $\|x\| := \max_i |x_i|$ . Then the following system satisfies all the assumptions of theorem 1:

$$\begin{aligned} x_n &\geq \text{sign}(-x_n) \cdot |x_n|^{1/2} \cdot |x_{n+1}|^{1/3} + 1/n - |x_n|^{2/3}, \\ x_n &\leq \text{sign}(-x_n) \cdot |x_n|^{1/2} \cdot |x_{n+1}|^{1/3} + 1/n + |x_n| + 1, \quad n=1 \div \infty. \end{aligned}$$

## References

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