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# STRICHARTZ TYPE ESTIMATES FOR OSCILLATORY PROBLEMS FOR SEMILINEAR WAVE EQUATION 

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Abstract. We treat the oscillatory problem for semilinear wave equation. The oscillatory initial data are of the type

$$
\begin{aligned}
u(0, x) & =h(x)+\varepsilon^{\sigma+1} e^{i l(x) / \varepsilon} b_{0}(\varepsilon, x) \\
\partial_{t} u(0, x) & =\varepsilon^{\sigma} e^{i l(x) / \varepsilon} b_{1}(\varepsilon, x) .
\end{aligned}
$$

By using suitable variants of Strichartz estimate we extend the results from [6] on a priori estimates of the approximations of geometric optics. The main improvement is the fact that we can obtain a priori estimates for the case $\sigma=1$, while in [6] we could treat only the case $\sigma>\frac{n}{2}-1$.

[^0]1. Introduction. We consider the following Cauchy problem for semilinear wave equation

$$
\left\{\begin{array}{l}
\left(\partial_{t t}-\Delta\right) u(t, x)=F_{\lambda}(u(t, x)) \quad(t, x) \in \mathbb{R}_{+}^{1+n}  \tag{1.1}\\
u(0, x)=f(x) \\
\partial_{t} u(0, x)=g(x)
\end{array}\right.
$$

where $f$ and $g$ belong to suitable Sobolev spaces, $F_{\lambda}(u)=u|u|^{\lambda-1}, n \geq 2$ and $\lambda=\frac{n+3}{n-1}$ is the conformally invariant exponent. In order to obtain a priori estimate of the solution to this classical equation, among the most important techniques we recall the standard energy estimate, that gives a control on $L^{2}$ norm of derivatives of the solution, the estimate of Von Wahl, that controles the $L^{\infty}$-norm of the solution and the Strichartz type estimate, that allows one to evaluate $L^{q}$-norm of the solution for a suitable $2 \leq q<\infty$.

Combining energy type estimate with Sobolev embedding, we studied in [6] the existence of local solutions to problem (1.1) for the case when
(i) the initial data $\left(u(0, x), \partial_{t} u(0, x)\right) \in H^{s+1}\left(\mathbb{R}^{n}\right) \times H^{s}\left(\mathbb{R}^{n}\right)$ are of oscillatory type (see (1.2) and (1.3)) and satisfy the minimal regularity assumption $s>\frac{n}{2}$ coming from the classical Sobolev embedding;
(ii) $\left|F^{(k)}(u)\right| \leq C(1+|u|)^{\lambda-k}$, for $\frac{n}{2} \leq k \leq \lambda$.

In this paper we apply a suitable generalization of Strichartz type estimate to control $L^{q}$-norm of solution to problem (1.1) in the case of oscillatory initial data of the form

$$
\begin{align*}
& f(x)=h(x)+\varepsilon^{\sigma+1} e^{i l(x) / \varepsilon} b_{0}(\varepsilon, x)  \tag{1.2}\\
& g(x)=\varepsilon^{\sigma} e^{i l(x) / \varepsilon} b_{1}(\varepsilon, x) \tag{1.3}
\end{align*}
$$

with $b_{0}, b_{1} \in O\left(\varepsilon^{0}\right)$ supported in $K=\left\{x \in \mathbb{R}^{n}:|x| \leq R\right\}, R>0$ (see Section 3 ). More precisely, we use the method of geometric optics and construct a solution of the form

$$
\begin{equation*}
u_{\varepsilon}(t, x)=H(t, x)+a(t, x, \theta ; \varepsilon) \tag{1.4}
\end{equation*}
$$

where $a(t, x, \theta ; \varepsilon)=\sum_{j=1}^{N} \varepsilon^{\sigma+j} a_{j}(t, x, \theta)+r_{N}(t, x, \theta ; \varepsilon), \theta=\frac{\varphi(t, x)}{\varepsilon}$ and the profiles $a_{j}(t, x, \theta)$ are smooth and $2 \pi$-periodic in $\theta$ (see [13]). Our main goal is to estimate the smallnest of $L^{q}$-norm of the remainder $r_{N}(t, x, \theta ; \varepsilon)$ as $\varepsilon \rightarrow 0$.

A similar problem for $q=2$ has been considered by J. L. Joly, G. Métivier and J. Rauch in [12] in the semilinear dissipative case $F=F\left(\nabla_{t, x} u\right)$, for which
they studied some nonlinear effects of focusing. Nonlinear geometric optics was applied also by D. Ludwig to construct an asymptotic solution of the reduced wave equation near a smooth convex caustic and near a cusped caustic ([14]). Nonlinear phenomena of caustics in geometric optics were studied recently by R. Carles, which provided a precise description of radial solution of wave equations for space dimension three (see [3] and [4]). For the case $F=F_{\lambda}(u)=u|u|^{\lambda-1}$ the problem for $q=2$ have been studied in [6] under the condition $\lambda \geq \frac{n}{2}$, since a combination between energy type estimate and classical Sobolev embedding is used. This restriction is not satisfactory, because implies $\sigma \geq s>\frac{n}{2}-1$ and this is far away from the desired value $\sigma=1$.

To avoid this complicated restriction we use recent techniques to examine global existence of solutions based on Strichartz estimate. For this reason below we give a brief sketch of results in this direction.

In [10] F. John showed that when $n=3$ there exists a critical value of $\lambda$, i. e. $\lambda_{c r}(3)=1+\sqrt{2}$, with the property that global existence of all small solutions holds if $\lambda>\lambda_{c r}(3)$ but no such result can occur if $\lambda<\lambda_{c r}(3)$. He assumed only that initial data were sufficiently smooth and compactly supported, but he not considered the critical case $\lambda=\lambda_{\text {cr }}(3)$.

The number $1+\sqrt{2}$ appeared first in a paper of W. Strauss on scattering for semilinear Schrödinger equation (cf. [18, 19]). This led him to conjecture that if $n \geq 2$, then global solutions to problem (1.1) with small initial data should always exist if $\lambda>\lambda_{c r}(n)$. Here the critical exponent $\lambda_{c r}(n)$ is the positive solution to the quadratic equation

$$
\begin{equation*}
(n-1) \lambda_{c r}^{2}-(n+1) \lambda_{c r}-2=0 \tag{1.5}
\end{equation*}
$$

R. T. Glassey proved this conjecture for $n=2$ by showing that problem (1.1) has global solution for small data if $\lambda>\lambda_{c r}(2)$ (see [9]); the critical value $\lambda=\lambda_{c r}(n)$ was studied by J. Shaeffer who proved blow-up for $n=2,3$. In [17] T. C. Sideris generalised the blow-up result of F. John to dimensions $n \geq 4$; more precisely he showed that if $\lambda_{c r}(n)$ is the positive root of (1.5), for $1<\lambda<\lambda_{c r}(n)$ and for suitable initial data the solution of problem (1.1) blows-up.

In [7] V. Georgiev, H. Lindblad and C. D. Sogge have considered problem (1.1) with initial data of the form $u(0, x)=\varepsilon f(x), \partial_{t} u(0, x)=\varepsilon g(x)$ and have determined, for a given $n$ and $\varepsilon>0$ small enough, the sharp range of $\lambda$ for wich one has global weak solutions. For this purpose a suitable weighted Strichartz estimate is proposed in [7].

In this work we apply the classical Strichartz estimate combined with space-time decay results due to I. Segal (cf. [16]) and prove that, under suitable assumptions on $\lambda$ and $F_{\lambda}$ and in the case of small initial data, the $L^{q}$-norm of
the solution to problem (1.1) satisfies

$$
\|u\|_{L^{q}\left(\mathbb{R}_{+}^{1+n}\right)} \leq C \delta
$$

for $q=2 \frac{n+1}{n-1}$ and some constant $C>0$ independent of $\delta$ (cf. Theorem 2.1). Here below small initial data condition means that

$$
\begin{equation*}
\|f\|_{H^{\frac{1}{2}\left(\mathbb{R}^{n}\right)}}+\|g\|_{L^{2}\left(\mathbb{R}^{n}\right)} \leq \delta \tag{1.6}
\end{equation*}
$$

for some sufficiently small $\delta>0$.
Using the above estimate we avoid the application of energy method by a combination of Hölder and Young inequalities, that yields the following estimate for the $L^{q}$-norm of $a(t, x, \theta ; \varepsilon)=u_{\varepsilon}(t, x)-H(t, x)$

$$
\|a(\cdot, \cdot, \theta ; \varepsilon)\|_{L^{q}\left(\mathbb{R}_{+}^{1+n}\right)} \leq C \varepsilon^{\sigma}
$$

Our main goal is to justify the asymptotic expansion (1.4); in particular, by a standard application of Hölder inequality and using local estimates of Strichartz type in the case of variable coefficients (see [2]) we prove the following

Theorem 1.1. For any $N \geq 1$ the remainder $r_{N}(t, x ; \varepsilon)$ satisfies the estimate

$$
\left\|r_{N}(\cdot, \cdot, \theta ; \varepsilon)\right\|_{L^{q}([0, T] \times\{|x| \leq R+t\})} \leq C_{N} \varepsilon^{\sigma+N+1}
$$

where the constant $C_{N}>0$ is independent of $\varepsilon$.
The plan of the work is the following.
In Section 2 we obtain a global a priori space-time estimate on the solution to problem (1.1) in the assumption that initial data $(f, g) \in H^{\frac{1}{2}}\left(\mathbb{R}^{n}\right) \times L^{2}\left(\mathbb{R}^{n}\right)$ satisfy (1.6).

In Section 3 we construct an approximate solution to problem (1.1), (1.2), (1.3) trough the method of geometric optics; see [15] and [20] for a complete reference on this subject. Then in last section we use the same arguments of Section 2 to estimate $L^{q}$-norm of the remainder $r_{N}(t, x, \theta ; \varepsilon)$ as $\varepsilon \rightarrow 0$.
2. Space-time estimate of Strichartz type. We consider solutions to the following Cauchy problem for semilinear wave equation

$$
\left\{\begin{array}{l}
\left(\partial_{t t}-\Delta\right) u(t, x)=F_{\lambda}(u(t, x)) \quad(t, x) \in \mathbb{R}_{+}^{1+n}  \tag{2.1}\\
u(0, x)=f(x) \\
\partial_{t} u(0, x)=g(x)
\end{array}\right.
$$

we assume that

$$
\begin{equation*}
(f, g) \in H^{\frac{1}{2}}\left(\mathbb{R}^{n}\right) \times L^{2}\left(\mathbb{R}^{n}\right) \tag{1}
\end{equation*}
$$

$$
\begin{equation*}
F_{\lambda}(u)=u|u|^{\lambda-1}, \text { with } \lambda=\frac{n+3}{n-1} . \tag{2}
\end{equation*}
$$

We start with the following standard result
Theorem 2.1. Let $u(t, x)$ be the solution to problem (2.1). Suppose the assumptions $\left(\mathbf{h}_{\mathbf{1}}\right)$ and $\left(\mathbf{h}_{\mathbf{2}}\right)$ are satisfied and the initial data satisfy the estimate

$$
\|f\|_{H^{\frac{1}{2}\left(\mathbb{R}^{n}\right)}}+\|g\|_{L^{2}\left(\mathbb{R}^{n}\right)} \leq \delta
$$

where $\delta$ is sufficiently small. Then

$$
\|u\|_{L^{q}\left(\mathbb{R}_{+}^{1+n}\right)} \leq C \delta
$$

for $q=2 \frac{n+1}{n-1}$ and some constant $C>0$ independent of $\delta$.
Proof. Using classical Strichartz estimate and its generalization due to M. Bezard (see [1]) and results of I. Segal about space-time decay for solutions to wave equation (see [16]), we get for $u$ the following estimate

$$
\begin{equation*}
\|u\|_{L^{q}\left(\mathbb{R}_{+}^{1+n}\right)} \leq C\left\|F_{\lambda}\right\|_{L^{p}\left(\mathbb{R}_{+}^{1+n}\right)}+C\|f\|_{H^{\frac{1}{2}\left(\mathbb{R}^{n}\right)}}+C\|g\|_{L^{2}\left(\mathbb{R}^{n}\right)} \tag{2.2}
\end{equation*}
$$

for $p=2 \frac{n+1}{n+3}$. In particular, by our assumption on initial data, we have

$$
\begin{equation*}
\|u\|_{L^{q}\left(\mathbb{R}_{+}^{1+n}\right)} \leq C\left\|F_{\lambda}\right\|_{L^{p}\left(\mathbb{R}_{+}^{1+n}\right)}+C \delta \tag{2.3}
\end{equation*}
$$

Since $F_{\lambda}(u)=u|u|^{\lambda-1}$, the definition of $L^{p}$-norm yields

$$
\begin{aligned}
\left\|F_{\lambda}\right\|_{L^{p}\left(\mathbb{R}_{+}^{1+n}\right)} & =\left(\left.\left.\int_{\mathbb{R}_{+}^{1+n}}|u| u\right|^{\lambda-1}\right|^{p} d t d x\right)^{\frac{1}{p}} \\
& =\left(\int_{\mathbb{R}_{+}^{1+n}}|u|^{\lambda p} d t d x\right)^{\frac{1}{\lambda p} \lambda}=\|u\|_{L^{\lambda p}\left(\mathbb{R}_{+}^{1+n}\right)}^{\lambda}=\|u\|_{L^{q}\left(\mathbb{R}_{+}^{1+n}\right)}^{\lambda},
\end{aligned}
$$

because by our choice is $\lambda p=q$; then

$$
\begin{equation*}
\|u\|_{L^{q}\left(\mathbb{R}_{+}^{1+n}\right)} \leq C_{1}\|u\|_{L^{q}\left(\mathbb{R}_{+}^{1+n}\right)}^{\lambda}+C_{2} \delta \tag{2.4}
\end{equation*}
$$

Now we need the following
Lemma 2.2. Let $u_{-1}(t, x)=0$ and for $k=0,1,2, \ldots$ let $u_{k}(t, x)$ defined recursively by requiring

$$
\left\{\begin{array}{l}
\left(\partial_{t t}-\Delta\right) u_{k}=F_{\lambda}\left(u_{k-1}\right) \\
u_{k}(0, x)=f(x) \\
\partial_{t} u_{k}(0, x)=g(x)
\end{array}\right.
$$

Set $X_{k}=\left\|u_{k}\right\|_{L^{q}\left(\mathbb{R}_{+}^{1+n}\right)}$ and $Y_{k}=\left\|u_{k}-u_{k-1}\right\|_{L^{q}\left(\mathbb{R}_{+}^{1+n}\right)}$. Then
(a)

$$
X_{k} \leq 2 X_{0} \quad \text { and }
$$

(b) $\quad 2 Y_{k+1} \leq Y$
for $k=0,1,2, \ldots$

Proof. From (2.4) it follows that $X_{k} \leq C_{1} X_{k-1}^{\lambda}+C_{2} \delta$. Using this, we can prove inductively that
(c)

$$
X_{k} \leq 2 C_{2} \delta
$$

For $k=0$ it is obvious. Suppose (c) is true for $k-1$; then $X_{k} \leq C_{1}\left(2 C_{2} \delta\right)^{\lambda}+C_{2} \delta$. The inequality $X_{k} \leq 2 C_{2} \delta$ is true if $C_{1}\left(2 C_{2} \delta\right)^{\lambda} \leq C_{2} \delta$, i.e. $\delta^{\lambda-1} \leq \frac{1}{2^{\lambda} C_{1} C_{2}^{\lambda}}$.

The proof of (b) is similar; the only difference is to replace (2.4) by

$$
\left\|F_{\lambda}\left(u_{k}\right)-F_{\lambda}\left(u_{k-1}\right)\right\|_{L^{p}\left(\mathbb{R}^{n}\right)} \leq\left\|u_{k}-u_{k-1}\right\|_{L^{q}\left(\mathbb{R}^{n}\right)}\left(\left\|u_{k}\right\|_{L^{q}\left(\mathbb{R}^{n}\right)}^{\lambda-1}+\left\|u_{k-1}\right\|_{L^{q}\left(\mathbb{R}^{n}\right)}^{\lambda-1}\right)
$$

Since $u_{k} \rightarrow u$ in $L^{q}\left(\mathbb{R}^{n}\right)$, the previous lemma completes the proof of the Theorem.
3. Construction of the approximate solution. In this section we consider problem (2.1) from the oscillatory point of view, i.e. we impose the following initial data

$$
\begin{align*}
& f(x)=h(x)+\varepsilon^{\sigma+1} e^{i l(x) / \varepsilon} b_{0}(\varepsilon, x)  \tag{3.1}\\
& g(x)=\varepsilon^{\sigma} e^{i l(x) / \varepsilon} b_{1}(\varepsilon, x) \tag{3.2}
\end{align*}
$$

here $\sigma \geq 1$ is an integer, the amplitudes $b_{0}, b_{1}$ are supported in $K=\left\{x \in \mathbb{R}^{n}\right.$ : $|x| \leq R\}$ and belong to the class $O\left(\varepsilon^{0}\right)$, namely are $C^{\infty}\left(\left[0, \varepsilon_{0}\right] \times \mathbb{R}^{n}\right)$ functions, for some small $\varepsilon_{0}$, so that for every compact set $M \subseteq \mathbb{R}^{n}$ and for every multiindex $\alpha$ there is a constant $C(\alpha, M)>0$ such that $\left|\partial_{x}^{\alpha} b_{j}(\varepsilon, x)\right| \leq C(\alpha, M) \varepsilon^{|\alpha|}$, for every $\varepsilon \in\left[0, \varepsilon_{0}\right]$ and for each $x \in M, j=0,1$. Note that in this assumption we have for $b_{j}(\varepsilon, x)$ an asymptotic expansion of the form $b_{j}(\varepsilon, x) \sim b_{j, 0}(x)+\varepsilon b_{j, 1}(x)+$ $\varepsilon^{2} b_{j, 2}(x)+\cdots$, for $j=0,1$; moreover we assume that $\nabla l \neq 0$ on a neighbourhood of $K$.

We look for solutions to problem (2.1) with initial data (3.1) and (3.2) of the form

$$
\begin{equation*}
u_{\varepsilon}(t, x)=H(t, x)+a(t, x, \theta ; \varepsilon) \tag{3.3}
\end{equation*}
$$

where $a(t, x, \theta ; \varepsilon)=\sum_{j=1}^{N} \varepsilon^{\sigma+j} a_{j}(t, x, \theta)+r_{N}(t, x, \theta ; \varepsilon), \theta=\frac{\varphi(t, x)}{\varepsilon}$ and the profiles $a_{j}(t, x, \theta)$ are smooth and $2 \pi$-periodic in $\theta$ (see [13]). For $u_{\varepsilon}$ we compute

$$
\left(\partial_{t t}-\Delta\right) u_{\varepsilon}=\left(\partial_{t t}-\Delta\right) H+\varepsilon^{\sigma-1} a_{1, \theta \theta}\left(\varphi_{t}^{2}-|\nabla \varphi|^{2}\right)+\varepsilon^{\sigma}\left[2 \partial_{\mu} \varphi \partial^{\mu} a_{1, \theta}+\right.
$$

$$
\begin{array}{r}
\left.a_{1, \theta}\left(\partial_{t t}-\Delta\right) \varphi+a_{2, \theta \theta}\left(\varphi_{t}^{2}-|\nabla \varphi|^{2}\right)\right]+\sum_{j=1}^{N} \varepsilon^{\sigma+j}\left[\left(\partial_{t t}-\Delta\right) a_{j}+2 \partial_{\mu} \varphi \partial^{\mu} a_{j+1, \theta}+\right. \\
\left.a_{j+1, \theta}\left(\partial_{t t}-\Delta\right) \varphi+a_{j+2, \theta \theta}\left(\varphi_{t}^{2}-|\nabla \varphi|^{2}\right)\right]+\varepsilon^{-1}\left(2 \partial_{\mu} \varphi \partial^{\mu} r_{N, \theta}+\right. \\
\left.r_{N, \theta}\left(\partial_{t t}-\Delta\right) \varphi\right)+\varepsilon^{-2} r_{N, \theta \theta}\left(\varphi_{t}^{2}-|\nabla \varphi|^{2}\right)+\left(\partial_{t t}-\Delta\right) r_{N}, \tag{3.4}
\end{array}
$$

where $a_{j}=0$ if $j \neq 1, \ldots, N$. Now we need to compute $F_{\lambda}\left(u_{\varepsilon}\right)$; to do this we use Taylor's expansion of $F_{\lambda}$ up to first order around $H$

$$
F_{\lambda}\left(u_{\varepsilon}\right)=F_{\lambda}(H)+F_{\lambda}^{\prime}(H)\left(u_{\varepsilon}-H\right)+R_{1}\left(u_{\varepsilon} ; H\right)
$$

In particular we can represent the remainder term $R_{1}$ in the integral form and we obtain

$$
\begin{align*}
F_{\lambda}\left(u_{\varepsilon}\right)= & F_{\lambda}(H)+\sum_{j=1}^{N} \varepsilon^{\sigma+j} F_{\lambda}^{\prime}(H) a_{j}+F_{\lambda}^{\prime}(H) r_{N}+\sum_{j, k=1, j \neq k}^{N} \varepsilon^{2 \sigma+j+k} a_{j} a_{k} A \\
.5) & +\sum_{j=1}^{N} \frac{1}{2} \varepsilon^{2 \sigma+2 j} a_{j}^{2} A+\sum_{j=1}^{N} \varepsilon^{\sigma+j} a_{j} A r_{N}+\frac{1}{2} A r_{N}^{2}, \tag{3.5}
\end{align*}
$$

with

$$
A=\int_{0}^{1}(1-\gamma) F_{\lambda}^{\prime \prime}(H+\gamma a) d \gamma
$$

Therefore $\left(\partial_{t t}-\Delta\right) u_{\varepsilon}=F_{\lambda}\left(u_{\varepsilon}\right)$ iff (3.4) and (3.5) coincide; in such way we obtain an equation in which the coefficients of $\varepsilon^{0}$ and $\varepsilon^{\sigma+j}, j=-1,0,1, \ldots, N-2$, have the following expressions (for $\sigma \geq 0$ integer)

$$
\begin{array}{ll}
(3.6) \quad \varepsilon^{0}: & \left(\partial_{t t}-\Delta\right) H-F_{\lambda}(H) ;  \tag{3.6}\\
(3.7) \varepsilon^{\sigma-1}: & a_{1, \theta \theta}\left(\varphi_{t}^{2}-|\nabla \varphi|^{2}\right)
\end{array}
$$

$$
\text { (3.8) } \quad \varepsilon^{\sigma}: \quad 2 \partial_{\mu} \varphi \partial^{\mu} a_{1, \theta}+a_{1, \theta}\left(\partial_{t t}-\Delta\right) \varphi+a_{2, \theta \theta}\left(\varphi_{t}^{2}-|\nabla \varphi|^{2}\right)
$$

$$
\varepsilon^{\sigma+j}: \quad\left(\partial_{t t}-\Delta\right) a_{j}+2 \partial_{\mu} \varphi \partial^{\mu} a_{j+1, \theta}+a_{j+1, \theta}\left(\partial_{t t}-\Delta\right) \varphi+
$$

$$
\begin{equation*}
+a_{j+2, \theta \theta}\left(\varphi_{t}^{2}-|\nabla \varphi|^{2}\right)-F_{\lambda}^{\prime}(H) a_{j}-\sum_{\substack{h, k=1, h \neq k \\ h+k=j-\sigma}}^{N} a_{h} a_{k} A-\frac{1}{2} a_{m}^{2} A \tag{3.9}
\end{equation*}
$$

If $\sigma \geq 0$ is not integer then there is no term of the form $\sum_{\substack{h, k=1, h \neq k \\ h+k=j-\sigma}}^{N} a_{h} a_{k} A-\frac{1}{2} a_{m}^{2} A$ while the terms of order $\varepsilon^{\mu}$, with $\mu \geq \sigma+N-1$, are given by

$$
\varepsilon^{\sigma+N-1}: \quad \varepsilon^{\sigma+N-1}\left[\left(\partial_{t t}-\Delta\right) a_{N-1}+2 \partial_{\mu} \varphi \partial^{\mu} a_{N, \theta}+a_{N, \theta}\left(\partial_{t t}-\Delta\right) \varphi+\right.
$$

$$
\begin{gather*}
\left.-F_{\lambda}^{\prime}(H) a_{N-1}\right]+\varepsilon^{-2} r_{N, \theta \theta}\left(\varphi_{t}^{2}-|\nabla \varphi|^{2}\right)+ \\
 \tag{3.10}\\
\varepsilon^{\sigma+N}: \sum_{\substack{h, k=1, h \neq k \\
h+k=N-1-\sigma}}^{N} \varepsilon^{2 \sigma+h+k} a_{h} a_{k} A-\frac{1}{2} \varepsilon^{2 \sigma+2 m} a_{m}^{2} A \\
\varepsilon^{\sigma+N}\left(\partial_{t t}-\Delta\right) a_{N}+\varepsilon^{-1}\left[2 \partial_{\mu} \varphi \partial^{\mu} r_{N, \theta}+r_{N, \theta}\left(\partial_{t t}-\Delta\right) \varphi\right]+  \tag{3.11}\\
\\
 \tag{3.12}\\
-\varepsilon^{\sigma+N} F_{\lambda}^{\prime}(H) a_{N}-\theta \sum_{\substack{h, k=1, h \neq k \\
h+k=N-\sigma}}^{N} \varepsilon^{2 \sigma+h+k} a_{h} a_{k} A-\frac{1}{2} \varepsilon^{2 \sigma+2 m} a_{m}^{2} A, \\
\varepsilon^{\mu}: \quad\left(\partial_{t t}-\Delta\right) r_{N}-F_{\lambda}^{\prime}(H) r_{N}-\sum_{\substack{j, k=1, j \neq k \\
h+k \geq N-1-\sigma}}^{N} \varepsilon^{2 \sigma+h+k} a_{h} a_{k} A+ \\
\\
\\
\\
\\
\\
\\
\\
\\
\end{gather*}
$$

we remark that in (3.9), (3.10) and (3.11), $m$ is given respectiveli by $\frac{j-\sigma}{2}$, $\frac{N-1-\sigma}{2}, \frac{N-\sigma}{2}$ for $j \in\{1, \ldots, N\}$ and $a_{m}=0$ if $m \neq 1, \ldots, N$.

We impose that all the coefficients of different powers of $\varepsilon$ vanish. To determine $H(t, x)$ we use the following nonlinear Cauchy problem

$$
\left\{\begin{array}{l}
\left(\partial_{t t}-\Delta\right) H=F_{\lambda}(H)  \tag{3.13}\\
H(0, x)=h(x) \\
\partial_{t} H(0, x)=0
\end{array}\right.
$$

This particular choice of the initial data in (3.13) is motivated by (3.1) and (3.2) and for the existence of local solution to (3.13) see results in [17]. In this way we reduce the initial data (3.1), (3.2) to the case $h=0$.

The term (3.7) is zero provided $\varphi(t, x)$ satisfies the eikonal equation

$$
\begin{equation*}
\varphi_{t}^{2}-|\nabla \varphi|^{2}=0 \tag{3.14}
\end{equation*}
$$

The initial data (3.1) hints that we have to impose the following initial condition

$$
\begin{equation*}
\varphi(0, x)=l(x) \tag{3.15}
\end{equation*}
$$

To solve this Cauchy problem for $\varphi$ we use the classical results for the existence of solution to first order nonlinear PDE's (see for istance [20], sec. 15, Chap. I). More precisely, these results guarantee that there is a $T>0$ and a neighborhood $U$ of $K$ so that (3.14) and (3.15) has a unique pair of solutions
$\varphi^{ \pm}(t, x) \in C^{\infty}((0, T) \times U)$, satisfying

$$
\varphi^{ \pm}(0, x)=l(x), \quad \partial_{t} \varphi^{ \pm}(0, x)= \pm|\nabla l(x)|
$$

and $\varphi^{ \pm}(t, x) \neq 0$ for $t$ small enough. We shall choose one of them, for example $\varphi(t, x)=\varphi_{+}(t, x)$; in such way the terms (3.8), (3.9), (3.10) and (3.10) simplify; the first one will be zero if $a_{1, \theta}$ satisfies the first transport equation
(3.16) $2 \partial_{\mu} \varphi \partial^{\mu} a_{1, \theta}(t, x, \theta)+a_{1, \theta}(t, x, \theta)\left(\partial_{t t}-\Delta\right) \varphi=0, \quad$ for all $\theta \in[0,2 \pi]$.

The initial data for (3.16) can be deduced from (3.1) and (3.2); more precisely we have that $u_{\varepsilon}(0, x)=h(x)+\varepsilon^{\sigma+1} e^{i l(x) / \varepsilon} b_{0}(\varepsilon, x)$ and $\partial_{t} u_{\varepsilon}(0, x)=\varepsilon^{\sigma} e^{i l(x) / \varepsilon} b_{1}(\varepsilon, x)$ if and only if

$$
\begin{align*}
& H(0, x)+\sum_{j=1}^{N} \varepsilon^{\sigma+j} a_{j}(0, x, l(x) / \varepsilon)+r_{N}(0, x, l(x) / \varepsilon ; \varepsilon)= \\
& =h(x)+\varepsilon^{\sigma+1} b_{0,0}(x) e^{i l(x) / \varepsilon}+\varepsilon^{\sigma+2} b_{0,1}(x) e^{i l(x) / \varepsilon}+\cdots \tag{3.17}
\end{align*}
$$

and

$$
\begin{array}{r}
\partial_{t} H(0, x)+\varepsilon^{\sigma} a_{1, \theta}(0, x, l(x) / \varepsilon) \partial_{t} \varphi(0, x)+\sum_{j=1}^{N-1} \varepsilon^{\sigma+j}\left(a_{j, t}(0, x, l(x) / \varepsilon)+\right. \\
\left.+a_{j+1, \theta}(0, x, l(x) / \varepsilon) \partial_{t} \varphi(0, x)\right)+\varepsilon^{\sigma+N} a_{N, t}(0, x, l(x) / \varepsilon)+\partial_{t} r_{N}(0, x, l(x) / \varepsilon ; \varepsilon)+ \\
(3.18) \varepsilon^{-1} r_{N, \theta}(0, x, l(x) / \varepsilon ; \varepsilon) \varphi_{t}(0, x)=\varepsilon^{\sigma} b_{1,0}(x) e^{i l(x) / \varepsilon}+\varepsilon^{\sigma+1} b_{1,1}(x) e^{i l(x) / \varepsilon}+\cdots \tag{3.18}
\end{array}
$$

respectively. If we require that in the previous expressions the coefficients of the same powers of $\varepsilon$ of both sides of (3.17) and (3.18) coincide, then we obtain for $a_{1, \theta}$ the following initial data

$$
\begin{equation*}
a_{1, \theta}(0, x, l(x) / \varepsilon) \varphi_{t}(0, x)=b_{1,0}(x) e^{i l(x) / \varepsilon} \tag{3.19}
\end{equation*}
$$

Note that by (3.17) we obtain $\left.a_{1}(t, x, \theta)\right|_{t=0}=b_{0,0}(x) e^{i \theta}$; therefore $a_{1, \theta}(0, x, l(x) / \varepsilon)$ $=i b_{0,0}(x) e^{i l(x) / \varepsilon}$. Moreover, by (3.19) we have the following relation between for $b_{0,0}(x)$ and $b_{1,0}(x)$

$$
i b_{0,0}(x) \varphi_{t}(0, x)=b_{1,0}(x)
$$

From Cauchy problem $(3.16)$, (3.19) for first transport equation we can recover $a_{1, \theta}$; the existence of local solutions to this problem is a well known result (see [11]). Then it remains to determine $a_{1}(t, x, \theta)$ from $a_{1, \theta}$; denote by $\partial_{\theta}^{-1}$ the operator of the primitive of $a_{1, \theta}$ that has mean zero (see [13]); namely $a_{1}=\partial_{\theta}^{-1} a_{1, \theta}$
such that

$$
\begin{equation*}
\int_{0}^{2 \pi} a_{1}(t, x, \theta) d \theta=0 \tag{3.20}
\end{equation*}
$$

We obtain

$$
a_{1}(t, x, \theta)=C+\int_{0}^{\theta} a_{1, \eta}(t, x, \eta) d \eta
$$

therefore (3.20) gives

$$
C=-\frac{1}{2 \pi} \int_{0}^{2 \pi}\left(\int_{0}^{\theta} a_{1, \eta}(t, x, \eta) d \eta\right) d \theta
$$

In such way, we get for $a_{1}$ the following expression

$$
\begin{equation*}
a_{1}(t, x, \theta)=-\frac{1}{2 \pi} \int_{0}^{2 \pi}\left(\int_{0}^{\theta} a_{1, \eta}(t, x, \eta) d \eta\right) d \theta+\int_{0}^{\theta} a_{1, \eta}(t, x, \eta) d \eta \tag{3.21}
\end{equation*}
$$

In general, the term (3.9) vanishes provided $a_{j+1, \theta}$ is solution to the following $(j+1)-$ th transport equation

$$
\begin{align*}
2 \partial_{\mu} \varphi \partial^{\mu} a_{j+1, \theta}+a_{j+1, \theta}\left(\partial_{t t}-\Delta\right) \varphi= & -\left(\partial_{t t}-\Delta\right) a_{j}+F_{\lambda}^{\prime}(H) a_{j}- \\
& -\sum_{\substack{h, k=1, h \neq k \\
h+k=j-\sigma}} a_{h} a_{k} A-\frac{1}{2} a_{m}^{2} A \tag{3.22}
\end{align*}
$$

for $m=\frac{j-\sigma}{2}, j=1, \ldots, N-1$; note that the last two terms in the above equation disappear if the conditions $h+k=j-\sigma, m=\frac{j-\sigma}{2} \in\{1, \ldots, j+1\}$ are not satisfied for any $j, k=1, \ldots, N$. Having in mind (3.18) we impose to this equation the following initial data

$$
\begin{equation*}
a_{j+1, \theta}(0, x, l(x) / \varepsilon) \varphi_{t}(0, x)=b_{1, j}(x) e^{i l(x) / \varepsilon}-a_{j, t}(0, x, l(x) / \varepsilon) \tag{3.23}
\end{equation*}
$$

Again, for the existence of local solution $a_{j+1, \theta}$ for these Cauchy problems for higher order transport equations we recall results in [11]; with the same argument discussed for $a_{1}$ we determine $a_{j+1}$ from $a_{j+1, \theta}$. Moreover, by (3.17) we obtain $a_{j+1}(0, x, l(x) / \varepsilon)=b_{0, j}(x) e^{i l(x) / \varepsilon}$. Therefore, if we combine this identity with (3.23), we deduce to the following compatibility condition for $b_{0, j}(x)$ and $b_{1, j}(x)$

$$
i b_{0, j}(x) e^{i l(x) / \varepsilon} \varphi_{t}(0, x)=b_{1, j}(x) e^{i l(x) / \varepsilon}-a_{j, t}(0, x, l(x) / \varepsilon)
$$

4. Justification of the oscillatory expansion. Using results in Section 2 we want to justify the asymptotic expansion in the previous Section 3.

By Theorem 2.1, in the assumption $\|h\|_{H^{\frac{1}{2}\left(\mathbb{R}^{n}\right)}} \leq C$, we derive for $H$ the
following estimate

$$
\begin{equation*}
\|H\|_{L^{q}\left(\mathbb{R}_{+}^{1+n}\right)} \leq C_{H}, \tag{4.1}
\end{equation*}
$$

with $q=2 \frac{n+1}{n-1}$; moreover note that $a(t, x, \theta ; \varepsilon)$ solves the following problem

$$
\left\{\begin{array}{l}
\left(\partial_{t t}-\Delta\right) a=F_{\lambda}(H+a)-F_{\lambda}(H)  \tag{4.2}\\
a(0, x, \theta ; \varepsilon)=\varepsilon^{\sigma+1} e^{i l(x) / \varepsilon} b_{0}(\varepsilon, x) \\
\partial_{t} a(0, x, \theta ; \varepsilon)=\varepsilon^{\sigma} e^{i l(x) / \varepsilon} b_{1}(\varepsilon, x)
\end{array}\right.
$$

and the initial data for $a(t, x, \theta ; \varepsilon)$ satisfy the assumptions of Theorem 2.1. Therefore the same argument of this theorem leads to the proof of the following

Corollary 4.1. Let $a(t, x, \theta ; \varepsilon)$ be the solution to problem (4.2). Then there exists a constant $C>0$ independent of $\varepsilon$ such that

$$
\|a(\cdot, \cdot, \theta ; \varepsilon)\|_{L^{q}\left(\mathbb{R}_{+}^{1+n}\right)} \leq C \varepsilon^{\sigma}
$$

for $q=2 \frac{n+1}{n-1}$.
Proof. In this proof we denote $\|a(\cdot, \cdot, \theta ; \varepsilon)\|_{L^{q}\left(\mathbb{R}_{+}^{1+n}\right)}$ simply by $\|a\|_{L^{q}\left(\mathbb{R}_{+}^{1+n}\right)}$. We observe that

$$
\left|F_{\lambda}(H+a)-F_{\lambda}(H)\right| \leq C|a|\left(|a|^{\lambda-1}+|H|^{\lambda-1}\right)
$$

then

$$
\begin{align*}
& \left\|F_{\lambda}(H+a)-F_{\lambda}(H)\right\|_{L^{p}\left(\mathbb{R}_{+}^{1+n}\right)} \leq \\
& \leq C\|a\|_{L^{p}\left(\mathbb{R}_{+}^{1+n}\right)}\left(\left\||a|^{\lambda-1}\right\|_{L^{p}\left(\mathbb{R}_{+}^{1+n}\right)}+\left\||H|^{\lambda-1}\right\|_{L^{p}\left(\mathbb{R}_{+}^{1+n}\right)}\right) \\
& \leq C\left\|a|a|^{\lambda-1}\right\|_{L^{p}\left(\mathbb{R}_{+}^{1+n}\right)}+C\|a\|_{L^{p}\left(\mathbb{R}_{+}^{1+n}\right)}\left\|\left.H\right|^{\lambda-1}\right\|_{L^{p}\left(\mathbb{R}_{+}^{1+n}\right)} \\
& \leq C\|a\|_{L^{q}\left(\mathbb{R}_{+}^{1+n}\right)}^{\lambda}+C\|a\|_{L^{q}\left(\mathbb{R}_{+}^{1+n}\right)}\left\||H|^{\lambda-1}\right\|_{L^{r}\left(\mathbb{R}_{+}^{1+n}\right)} \tag{4.3}
\end{align*}
$$

here we used the fact that $\lambda p=q$ and we applied Hölder inequality with $\frac{1}{r}+\frac{1}{q}=$ $\frac{1}{p}$. Moreover by (4.1) we have

$$
\left\||H|^{\lambda-1}\right\|_{L^{r}\left(\mathbb{R}_{+}^{1+n}\right)}=\|H\|_{L^{r(\lambda-1)}\left(\mathbb{R}_{+}^{1+n}\right)}^{\lambda-1}=\|H\|_{L^{q}\left(\mathbb{R}_{+}^{1+n}\right)}^{\lambda-1} \leq C_{H}^{\lambda-1}
$$

now we can use Young inequality to estimate the term $\|a\|_{L^{q}\left(\mathbb{R}_{+}^{1+n}\right)} C_{H}^{\lambda-1}$; we obtain
that

$$
\|a\|_{L^{q}\left(\mathbb{R}_{+}^{1+n}\right)}^{\frac{1}{\lambda}}\left(C_{H}\right)^{\frac{\lambda-1}{\lambda}} \leq C\left(\|a\|_{L^{q}\left(\mathbb{R}_{+}^{1+n}\right)}+C_{H}\right)
$$

and this implies that

$$
\begin{equation*}
\|a\|_{L^{q}\left(\mathbb{R}_{+}^{1+n}\right)}\left(C_{H}\right)^{\lambda-1} \leq C\|a\|_{L^{q}\left(\mathbb{R}_{+}^{1+n}\right)}^{\lambda}+C C_{H}^{\lambda} \tag{4.4}
\end{equation*}
$$

Then by (4.3) and (4.4) we conclude that

$$
\left\|F_{\lambda}(H+a)-F_{\lambda}(H)\right\|_{L^{p}\left(\mathbb{R}_{+}^{1+n}\right)} \leq C\|a\|_{L^{q}\left(\mathbb{R}_{+}^{1+n}\right)}^{\lambda}+C
$$

Finally we observe that

$$
\|a(0, \cdot, l(x) / \varepsilon ; \varepsilon)\|_{H^{\frac{1}{2}\left(\mathbb{R}^{n}\right)}}+\left\|\partial_{t} a(0, \cdot, l(x) / \varepsilon ; \varepsilon)\right\|_{L^{2}\left(\mathbb{R}^{n}\right)} \leq C \varepsilon^{\sigma}
$$

then with the same argument of Theorem 2.1 we conclude the proof.
At this point we must estimate the remainder $r_{N}(t, x, \theta ; \varepsilon)$ in the above approximation (3.3). We start with the simplest case $N=1$, then we shall generalize the result for $N \geq 1$.

For $N=1$ the approximation (3.3) takes the form

$$
u_{\varepsilon}(t, x)=H(t, x)+\varepsilon^{\sigma+1} a_{1}(t, x, \theta)+r_{1}(t, x, \theta ; \varepsilon) ;
$$

from (3.4) and (3.5) we obtain

$$
\begin{aligned}
& \left(\partial_{t t}-\Delta\right) H+\varepsilon^{\sigma-1} a_{1, \theta \theta}\left(\varphi_{t}^{2}-|\nabla \varphi|^{2}\right)+\varepsilon^{\sigma}\left[2 \partial_{\mu} \varphi \partial^{\mu} a_{1, \theta}+\right. \\
& \left.+a_{1, \theta}\left(\partial_{t t}-\Delta\right) \varphi\right]+\varepsilon^{\sigma+1}\left(\partial_{t t}-\Delta\right) a_{1}+\varepsilon^{-2} r_{1, \theta \theta}\left(\varphi_{t}^{2}-|\nabla \varphi|^{2}\right)+ \\
& \varepsilon^{-1}\left[2 \partial_{\mu} \varphi \partial^{\mu} r_{1, \theta}+r_{1, \theta}\left(\partial_{t t}-\Delta\right) \varphi\right]+\left(\partial_{t t}-\Delta\right) r_{1}= \\
(4.5) & =F(H)+\varepsilon^{\sigma+1} F^{\prime}(H) a_{1}+F^{\prime}(H) r_{1}+\frac{1}{2} \varepsilon^{2 \sigma+2} a_{1}^{2} A+2 \varepsilon^{\sigma+1} a_{1} A r_{1}+\frac{1}{2} A r_{1}^{2},
\end{aligned}
$$

where

$$
A=\int_{0}^{1}(1-\gamma) F^{\prime \prime}(H+\gamma a) d \gamma
$$

note that in the previous expression the term $r_{1}$ is of order $\varepsilon^{\sigma+2}$. If we require that in (4.5) the terms of order $\varepsilon^{\sigma+2}$ are zero, then, having in mind (3.13), (3.14) and (3.16), we obtain for $r_{1, \theta}$ the following equation

$$
\begin{equation*}
\partial_{t} r_{1, \theta}-\sum_{j=1}^{n} \mu_{j} \partial_{x_{j}} r_{1, \theta}+\nu r_{1, \theta}=f \tag{4.6}
\end{equation*}
$$

with $\mu_{j}=\frac{\partial_{x_{j}} \varphi}{2 \partial_{t} \varphi}, \quad \nu=\frac{\left(\partial_{t t}-\Delta\right) \varphi}{2 \partial_{t} \varphi}$ and $f=-\varepsilon^{\sigma+2}\left(\partial_{t t}-\Delta\right) a_{1}+\varepsilon^{\sigma+2} F^{\prime}(H) a_{1}$.

Moreover, if we impose that in (3.18) the terms of order $\varepsilon^{\sigma+1}$ must be equal, we get for $r_{1, \theta}$ the following initial condition

$$
\begin{equation*}
r_{1, \theta}\left(0, x, \frac{l(x)}{\varepsilon} ; \varepsilon\right) \varphi_{t}(0, x)=\varepsilon^{\sigma+2} b_{1,1}(x) e^{i l(x) / \varepsilon} \tag{4.7}
\end{equation*}
$$

The existence of local solution to problem (4.6), (4.7) is well known (see [11]); to determine $r_{1}$ from $r_{1, \theta}$ we use the same argument discussed above for $a_{1}$.

At this point we note that if we set $B=\sum_{j=1}^{n} \mu_{j} \partial_{x_{j}}$, then (4.6) can be written as follows

$$
\begin{equation*}
\partial_{t} r_{1, \theta}=B r_{1, \theta}-\nu r_{1, \theta}+f \tag{4.8}
\end{equation*}
$$

By differentiating with respect to $t$ both sides of (4.8) we obtain

$$
\begin{equation*}
\partial_{t t} r_{1, \theta}-B^{2} r_{1, \theta}=\left(\nu^{2}-B \nu-\nu B+\partial_{t} B-\partial_{t} \nu\right) r_{1, \theta}+\left(B-\nu+\partial_{t}\right) f \tag{4.9}
\end{equation*}
$$

note that $B^{2}=\sum_{j, k=1}^{n} \mu_{j} \mu_{k} \partial_{x_{j}} \partial_{x_{k}}$ and for $\mu=\left(\mu_{1}, \ldots, \mu_{n}\right)$ by eikonal equation we have $\|\mu\|=\left|\frac{\nabla \varphi}{2 \partial_{t} \varphi}\right|=\frac{1}{2}$.

For the initial data we impose in addition to (4.9) the condition (4.7) and by (4.8) we require that

$$
\begin{equation*}
\left.\left(\partial_{t} r_{1, \theta}\right)\right|_{t=0}=\left.\left(B r_{1, \theta}-\nu r_{1, \theta}+f\right)\right|_{t=0} . \tag{4.10}
\end{equation*}
$$

Since the operator $\nu^{2}-2 B \nu+\partial_{t} B-\partial_{t} \nu$ is bounded, by local estimates of Strichartz type in the case of variable coefficients (cf. [2]) we obtain for $r_{1, \theta}$ the following inequality

$$
\begin{gathered}
\left\|r_{1, \theta}(\cdot, \cdot, \theta ; \varepsilon)\right\|_{L^{q}([0, T] \times\{|x| \leq R+t\})} \leq C(R, T)\left\|\left(B-\nu+\partial_{t}\right) f\right\|_{L^{p}([0, T] \times\{|x| \leq R+t\})}+ \\
\quad+\left\|r_{1, \theta}(0, \cdot, l(x) / \varepsilon ; \varepsilon)\right\|_{\perp^{\frac{1}{2}}\left(\mathbb{R}^{n}\right)}+\left\|\partial_{t} r_{1, \theta}(0, \cdot, l(x) / \varepsilon ; \varepsilon)\right\|_{H^{-\frac{1}{2}}\left(\mathbb{R}^{n}\right)} .
\end{gathered}
$$

Note that for any $x \in K$ and for any $\theta \in[0,2 \pi]$ there exists $\varepsilon=\varepsilon(x)>0$ such that $r_{1, \theta}(0, x, \theta ; \varepsilon)=r_{1, \theta}(0, x, l(x) / \varepsilon ; \varepsilon)$; then by our assumptions on $b_{1}$ and $\varphi$ we deduce from (4.7) that

$$
\begin{equation*}
\left\|r_{1, \theta}(0, \cdot, l(x) / \varepsilon ; \varepsilon)\right\|_{H^{\frac{1}{2}\left(\mathbb{R}^{n}\right)}}\left\|r_{1, \theta}(0, \cdot, l(x) / \varepsilon ; \varepsilon)\right\|_{H^{\frac{1}{2}\left(\mathbb{R}^{n}\right)}} \leq C \varepsilon^{\sigma+2} \tag{4.11}
\end{equation*}
$$

Similarly, from (4.10) and (4.11) we obtain

$$
\left.\left\|\partial_{t} r_{1, \theta}(0, \cdot, l(x) / \varepsilon ; \varepsilon)\right\|_{H^{\frac{1}{2}\left(\mathbb{R}^{n}\right)}} \| \partial_{t} r_{1, \theta} 0, \cdot, l(x) / \varepsilon ; \varepsilon\right) \|_{L^{2}}\left(\mathbb{R}^{n}\right) \leq C \varepsilon^{\sigma+2}
$$

Therefore our next step is to estimate the local $L^{p}$-norm of $\left(B-\nu+\partial_{t}\right) f$; for simplicity, here below we write $L_{l o c}^{p}$ instead of $L^{p}([0, T] \times\{|x| \leq R+t\})$. Note
that

$$
\left.\|B f\|_{L_{l o c}^{p}} \leq C \varepsilon^{\sigma+2}\left\|\nabla_{x}\left(F^{\prime}(H) a_{1}\right)\right\|_{L_{l o c}^{p}}+C \varepsilon^{\sigma+2} \| \nabla_{x}\left(\partial_{t t}-\Delta\right) a_{1}\right) \|_{L_{l o c}^{p}}
$$

in particular

$$
\begin{gathered}
\left\|\nabla_{x}\left(F^{\prime}(H) a_{1}\right)\right\|_{L_{l o c}^{p}}=C\left\|\nabla_{x}\left(|H|^{\lambda-2} H a_{1}\right)\right\|_{L_{l o c}^{p}} \leq \\
\leq C\left\|\nabla_{x} H|H|^{\lambda-2}\right\|_{L_{l o c}^{r}}\left\|a_{1}\right\|_{L_{l o c}^{q}}+C\left\|H|H|^{\lambda-2}\right\|_{L_{l o c}^{r}}\left\|\nabla_{x} a_{1}\right\|_{L_{l o c}^{q}},
\end{gathered}
$$

with $\frac{1}{r}+\frac{1}{q}=\frac{1}{p}$. Applying again Hölder inequality, we get

$$
\left\|\nabla_{x} H|H|^{\lambda-2}\right\|_{L_{l o c}^{r}} \leq\left\|\nabla_{x} H\right\|_{L_{l o c}^{q}}\|H\|_{L_{l o c}^{L^{2}(\lambda-2)}}^{\lambda-2}
$$

where $\frac{1}{r_{2}}+\frac{1}{q}=\frac{1}{r}$; this gives $r_{2}(\lambda-2)=q$, since $\lambda p=q$. Similarly,

$$
\left\|H|H|^{\lambda-2}\right\|_{L_{l o c}^{r}} \leq\|H\|_{L_{l o c}^{q}}\|H\|_{L_{l o c}^{r_{2}(\lambda-2)}}^{\lambda-2}=\|H\|_{L_{l o c}^{q}}^{\lambda-1},
$$

therefore we have

$$
\begin{aligned}
\left\|\nabla_{x}\left(F^{\prime}(H) a_{1}\right)\right\|_{L_{l o c}^{p}} & \leq C\left\|\nabla_{x} H\right\|_{L_{l o c}^{q}}\|H\|_{L_{l o c}^{q}}^{\lambda-2}\left\|a_{1}\right\|_{L_{l o c}^{q}}+C\|H\|_{L_{l o c}^{q}}^{\lambda-2}\left\|\nabla_{x} a_{1}\right\|_{L_{l o c}^{q}} \leq \\
& \leq C\left\|\nabla_{x} H\right\|_{L_{l o c}^{q}}\left\|a_{1}\right\|_{L_{l o c}^{q}}+C\left\|\nabla_{x} a_{1}\right\|_{L_{l o c}^{q}} .
\end{aligned}
$$

Since $H$ is the solution to (3.13), we conclude that $\nabla_{x} H$ satisfies the following problem

$$
\left\{\begin{array}{c}
\left(\partial_{t t}-\Delta\right)\left(\nabla_{x} H\right)=C|H|^{\lambda-2} \nabla_{x} H \\
\nabla_{x} H(0, x)=\nabla_{x} h(x) \\
\partial_{t}\left(\nabla_{x} H\right)(0, x)=0
\end{array}\right.
$$

therefore we derive from Theorem 2.1 the following estimate

$$
\left\|\nabla_{x} H\right\|_{L_{l o c}^{q}} \leq C
$$

Now it remains to estimate $L_{l o c}^{q}$-norm of $a_{1}$ and $\nabla_{x} a_{1}$. First, recall that we can recover $a_{1}$ using (3.21); therefore we have Poincaré inequality for the periodic in $\theta$ function $a_{1}(\cdot, \cdot, \theta)$

$$
\begin{equation*}
\left\|a_{1}\right\|_{L_{l o c}^{q}} \leq \sup _{0 \leq \theta \leq 2 \pi}\left\|a_{1, \theta}(\cdot, \cdot, \theta)\right\|_{L_{l o c}^{q}} \tag{4.12}
\end{equation*}
$$

With the same notations and the same argument discussed above for $r_{1, \theta}$, differentiating with respect to $t$ (3.16), we obtain for $a_{1, \theta}$ the following second order

Cauchy problem

$$
\left\{\begin{array}{l}
\left(\partial_{t t}-B\right) a_{1, \theta}=\left(\nu^{2}-\nu B-B \nu-\partial_{t} \nu\right) a_{1, \theta}  \tag{4.13}\\
a_{1, \theta}(0, x, l(x) / \varepsilon) \varphi_{t}(0, x)=b_{1,0}(x) e^{i l(x) / \varepsilon} \\
\left(\partial_{t} a_{1, \theta}\right)(0, x, l(x) / \varepsilon)=\left.\left(B a_{1, \theta}-\nu a_{1, \theta}\right)\right|_{t=0}
\end{array}\right.
$$

therefore as for $r_{1, \theta}$ we have the following estimate

$$
\left\|a_{1, \theta}\right\|_{L_{l o c}^{q}} \leq C\left\|a_{1, \theta}(0, \cdot, l(x) / \varepsilon)\right\|_{H^{\frac{1}{2}\left(\mathbb{R}^{n}\right)}}+C\left\|\partial_{t} a_{1, \theta}(0, \cdot, l(x) / \varepsilon)\right\|_{L^{2}} \leq C
$$

Recall that also for $a_{1, \theta}$, for any $x \in K$ and for any $\theta \in[0,2 \pi]$ we have $a_{1, \theta}(0, x, \theta)=$ $a_{1, \theta}(0, x, l(x) / \varepsilon)$ for some $\varepsilon=\varepsilon(x)>0$; therefore (4.12) in combination with the last inequality leads to the following estimate for $a_{1}$

$$
\left\|a_{1}(\cdot, \cdot, \theta)\right\|_{L_{l o c}^{q}} \leq C
$$

From (4.13) we compute that $\nabla_{x} a_{1, \theta}$ satisfies the following Cauchy problem

$$
\left\{\begin{array}{c}
\left(\partial_{t t}-\Delta\right)\left(\nabla_{x} a_{1, \theta}\right)=\left(\partial_{t} B-B \nu-\nu B-\partial_{t} \nu+\nu^{2}\right)\left(\nabla_{x} a_{1, \theta}\right)+  \tag{4.14}\\
\quad+\left(\nabla_{x}\left(B^{2}+\partial_{t} B-B \nu-\nu B-\partial_{t} \nu+\nu^{2}\right)\right) a_{1, \theta} \\
\nabla_{x} a_{1, \theta}(0, x, l(x) / \varepsilon) \varphi_{t}(0, x)=\nabla_{x}\left(b_{1,0}(x) e^{i l(x) / \varepsilon}\right) \\
\quad-\nabla_{x} \varphi_{t}(0, x) \frac{b_{1,0}(x) e^{i l(x) / \varepsilon}}{\varphi_{t}(0, x)}
\end{array}\right\}
$$

Again, by results in [2] we derive for $\nabla_{x} a_{1, \theta}$ the following estimate

$$
\begin{aligned}
\left\|\nabla_{x} a_{1, \theta}(\cdot, \cdot, \theta)\right\|_{L_{l o c}^{q}} & \leq C\left\|\nabla_{x} a_{1, \theta}(0, \cdot, l(x) / \varepsilon)\right\|_{H^{\frac{1}{2}\left(\mathbb{R}^{n}\right)}}+ \\
& +C\left\|\partial_{t} \nabla_{x} a_{1, \theta}(0, \cdot, l(x) / \varepsilon)\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}
\end{aligned}
$$

then by initial data in (4.14) and by our assumptions on $b_{1}, \varphi$ and $l$ we have

$$
\left\|\nabla_{x} a_{1, \theta}(\cdot, \cdot, \theta)\right\|_{L_{l o c}^{q}} \leq C
$$

As for $r_{1}$ and $a_{1}$, from this last inequality we derive the following estimate for $\nabla_{x} a_{1}$,

$$
\left\|\nabla_{x} a_{1,}(\cdot, \cdot, \theta)\right\|_{L_{l o c}^{q}} \leq C
$$

Recalling all these inequalities we conclude that

$$
\left\|\nabla_{x}\left(F^{\prime}(H) a_{1}\right)\right\|_{L_{l o c}^{p}} \leq C
$$

Exactly the same arguments allow us to get analogous results for the $L_{l o c}^{p}$-norm
of $\nabla_{x}\left(\left(\partial_{t t}-\Delta\right) a_{1}\right)$; therefore we obtain that

$$
\|B f\|_{L_{l o c}^{p}} \leq C \varepsilon^{\sigma+2}
$$

for some costant $C$ independent of $\varepsilon$.
The following estimate of the $L_{l o c}^{p}$-norm of the term $\left(\partial_{t}-\nu\right) f$ is proved with the same tools

$$
\left\|\left(\partial_{t}-\nu\right) f\right\|_{L_{l o c}^{p}} \leq C \varepsilon^{\sigma+2}
$$

therefore, if we combine all these results we get for $r_{1, \theta}$ the following estimate

$$
\left\|r_{1, \theta}(\cdot, \cdot, \theta ; \varepsilon)\right\|_{L_{l o c}^{q}} \leq C \varepsilon^{\sigma+2}
$$

Since as for $a_{1}$, we can recover $r_{1}$ from $r_{1, \theta}$ by the formula

$$
r_{1}(t, x, \theta ; \varepsilon)=-\frac{1}{2 \pi} \int_{0}^{2 \pi}\left(\int_{0}^{\theta} r_{1, \eta}(t, x, \eta ; \varepsilon) d \eta\right) d \theta+\int_{0}^{\theta} r_{1, \eta}(t, x, \eta ; \varepsilon) d \eta
$$

we have

$$
\begin{aligned}
\left\|r_{1}(\cdot, \cdot, \theta ; \varepsilon)\right\|_{L^{q}([0, T] \times\{|x| \leq R+t\})} & \leq \sup _{0 \leq \theta \leq 2 \pi}\left\|r_{1, \theta}(\cdot, \cdot, \theta ; \varepsilon)\right\|_{L^{q}([0, T] \times\{|x| \leq R+t\})} \\
& \leq C(R, T) \varepsilon^{\sigma+2}
\end{aligned}
$$

In general, for $N \geq 1$ the remainder $r_{N, \theta}$ satisfies the following Cauchy problem

$$
\left\{\begin{array}{l}
\partial_{t} r_{N, \theta}-\sum_{j=1}^{n} \mu_{j} \partial_{x_{j}} r_{N, \theta}+\nu r_{N, \theta}=g \\
\varepsilon^{-1} r_{N, \theta}(0, x, l(x) / \varepsilon ; \varepsilon) \varphi_{t}(0, x)=\varepsilon^{\sigma+N} b_{1, N}(x) e^{i l(x) / \varepsilon}
\end{array}\right.
$$

where $\mu_{j}$ and $\nu$ are as before and

$$
\begin{aligned}
g= & -\varepsilon^{\sigma+N+1} \frac{\left(\partial_{t t}-\Delta\right) a_{N}}{2 \varphi_{t}} \varepsilon^{\sigma+N+1} F^{\prime}(H) \frac{a_{N}}{2 \varphi_{t}}+ \\
& -\sum_{\substack{h, k=1, h \neq k \\
h+k=N-\sigma}}^{N} \varepsilon^{2 \sigma+1+h+k} \frac{a_{h} a_{k}}{2 \varphi_{t}} A-\frac{1}{2} \varepsilon^{2 \sigma+1+2 m} \frac{a_{m}^{2}}{2 \varphi_{t}} A .
\end{aligned}
$$

With the same argument discussed above for $r_{1, \theta}$ we derive for $r_{N, \theta}$ the following second order Cauchy problem

$$
\left\{\begin{array}{l}
\left(\partial_{t t}-B^{2}\right) r_{N, \theta}=\left(\nu^{2}-B \nu-\nu B+\partial_{t} B-\partial_{t} \nu\right) r_{N, \theta}+\left(B-\nu+\partial_{t}\right) g \\
r_{N, \theta}(0, x, l(x) / \varepsilon ; \varepsilon) \varphi_{t}(0, x)=\varepsilon^{\sigma+N+1} b_{1, N}(x) e^{i l(x) / \varepsilon} \\
\partial_{t} r_{N, \theta}(0, x, l(x) / \varepsilon ; \varepsilon)=\left.\left(B r_{N, \theta}-\nu r_{N, \theta}+g\right)\right|_{t=0}
\end{array}\right.
$$

Since again

$$
\left\|\left(B-\nu+\partial_{t}\right) g\right\|_{L_{\text {loc }}^{p}} \leq C \varepsilon^{\sigma+N+1},
$$

we can state in general the following
Theorem 4.2. For any $N \geq 1$ the remainder $r_{N}(t, x ; \varepsilon)$ satisfies the estimate

$$
\left\|r_{N}(\cdot, \cdot, \theta ; \varepsilon)\right\|_{L^{q}([0, T] \times\{|x| \leq R+t\})} \leq C_{N} \varepsilon^{\sigma+N+1}
$$

where the constant $C_{N}>0$ is independent of $\varepsilon$.
Remark 4.3. In the previous corollary we have just local estimate since the Cauchy problems for eikonal equation and for transport equations have only local solutions (see [20]); in order to obtain global estimate on $r_{N}$ it is necessary that $\varphi(t, x)$ and $a_{j}(t, x, \theta)$ should be defined for every $t \geq 0$.

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