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# INTERVAL CRITERIA FOR FORCED OSCILLATION OF FUNCTIONAL DIFFERENTIAL EQUATIONS WITH $\gamma$-LAPLACIAN, DAMPING AND MIXED NONLINEARITIES 

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Abstract. We consider a forced second order functional differential equation with $\gamma$-Laplacian, damping, and mixed nonlinearities in the form of

$$
\begin{aligned}
\left(r(t) \phi_{\gamma}\left(x^{\prime}(t)\right)\right)^{\prime} & +p(t) \phi_{\gamma}\left(x^{\prime}(t)\right) \\
& +q_{0}(t) \phi_{\beta}(x(t))+\int_{a}^{b} q(t, s) \phi_{\alpha(s)}(x(g(t, s))) d \zeta(s)=e(t)
\end{aligned}
$$

where $\gamma, \beta \in[0, \infty),-\infty<a<b \leq \infty, \alpha \in C[a, b)$ is strictly increasing is such that $0 \leq \alpha(a)<\mu<\alpha(b-)$ with $\beta>\gamma>\mu>0 ; r, p, q_{0}, e \in$ $C\left(\left[t_{0}, \infty\right), \mathbb{R}\right)$ with $r(t)>0$ on $\left[t_{0}, \infty\right) ; q \in C([0, \infty) \times[a, b))$; and $\zeta:$ $[a, b) \rightarrow \mathbb{R}$ is nondecreasing. The function $g \in C([0, \infty) \times[a, b),[0, \infty))$ is such that $\lim _{t \rightarrow \infty} g(t, s)=\infty$, for $s \in[a, b)$. Interval oscillation criteria of the El-Sayed type and the Kong type are obtained. These criteria are further extended to equations with deviating arguments.

[^0]1. Introduction. We are concerned with the oscillatory behavior of forced second order functional differential equations with $\gamma$-Laplacian, damping and mixed nonlinearities in the form of

$$
\begin{align*}
\left(r(t) \phi_{\gamma}\left(x^{\prime}(t)\right)\right)^{\prime} & +p(t) \phi_{\gamma}\left(x^{\prime}(t)\right)  \tag{1.1}\\
& +q_{0}(t) \phi_{\beta}(x(t))+\int_{a}^{b} q(t, s) \phi_{\alpha(s)}(x(g(t, s))) d \zeta(s)=e(t)
\end{align*}
$$

where $\phi_{\alpha}(u):=|u|^{\alpha} \operatorname{sgn} u, \gamma, \beta \in[0, \infty),-\infty<a<b \leq \infty, \alpha \in C[a, b)$ is strictly increasing such that $0 \leq \alpha(a)<\mu<\alpha(b-)$ with $\beta>\gamma>\mu>0$; $r, p, q_{0}, e \in C\left(\left[t_{0}, \infty\right), \mathbb{R}\right)$ with $r(t)>0$ on $\left[t_{0}, \infty\right) ; q \in C([0, \infty) \times[a, b))$; and $\zeta:[a, b) \rightarrow \mathbb{R}$ is nondecreasing. The function $g \in C([0, \infty) \times[a, b),[0, \infty))$ is such that $\lim _{t \rightarrow \infty} g(t, s)=\infty$, for $s \in[a, b)$. Our interest is to establish oscillation criteria for Eq. (1.1) without assuming that $p(t), q_{0}(t), q(t, s)$, and $e(t)$ are of definite sign. Here $\int_{a}^{b} f(s) d \zeta(s)$ denotes the Riemann-Stieltjes integral of the function $f$ on $[a, b)$ with respect to $\zeta$.

We note that as special cases, the integral term in the equation becomes a finite sum when $\zeta(s)$ is a step function and a Riemann integral when $\zeta(s)=s$.

As usual, a solution $x(t)$ of Eq. (1.1) is said to be oscillatory if it is defined on some ray $[T, \infty)$ with $T \geq 0$, and has an unbounded set of zeros. Eq. (1.1) is said to be oscillatory if every solution extendible throughout $\left[t_{x}, \infty\right)$ for some $t_{x} \geq 0$ is oscillatory.

In the last 50 years, there has been extensive work on oscillation and nonoscillation of various differential equations, see $[1,3,4,5,6,7,8,10,19,20$, $21,22,31,26]$ and the references cited therein. Special cases of the equation

$$
\begin{equation*}
\left(r(t)\left(x^{\prime}(t)\right)^{\gamma}\right)^{\prime}+q_{0}(t) x^{\gamma}(t)+\sum_{j=1}^{N} q_{j}(t) \phi_{\alpha j}(x(t))=e(t) \tag{1.2}
\end{equation*}
$$

where $\phi_{\alpha}(u):=|u|^{\alpha} \operatorname{sgn} u, \gamma$ is a quotient of odd positive integers and $\alpha_{j}>0$, $j=1,2, \ldots, N$, such that

$$
\alpha_{1}>\alpha_{2}>\cdots>\alpha_{m}>\gamma>\alpha_{m+1}>\cdots>\alpha_{n}>0
$$

has been studied by many authors. When $\gamma=N=1, r(t)=1, p(t)=q_{0}(t)=0$, and $q_{1}(t) \geq 0$, Kartsatos [19, 20] initiated an approach for oscillation under the assmption that $e(t)$ is the second derivative of an oscillatory function. This method was further developed by different authors, See Keener [21], Kong and Wong [24], Kong and Zhang [25], Rankin [30], Skidmore and Leighton [32], Skid-
more and Bowers [31], Teufel [39], and Wong [40].
Results were also obtained for oscillation of special cases of Eq. (1.2) without imposing the assumption that $e(t)$ is the second derivative of an oscillatory function. Most of them were for the case when $\gamma=1, r(t)=1$, and $p(t)=0$. For instance, see Nasr [27] for $N=1$ and $\alpha_{1}>1$, Sun and Wong [36] for $\alpha_{j}<1$, and Sun and Wong [37] and Sun and Meng [35] for mixed nonlinearities. Among them, there were interval oscillation criteria which can be regarded as generalizations of the one by El-Sayed [9] for second order forced linear differential equations, and other interval oscillation criteria can be regarded as generalizations of the one by Kong [22] established initially for the second order homogeneous linear equations, see also [23]. Hassan, Erbe and Peterson [15] discussed the oscillation of an equation with $p$-Lapacian, more specifically, they established oscillation criteria of El-Sayed-type for the equation (1.2)

Hassan and Kong [16] considered the forced second order differential equations with $\gamma$-Laplacian and damping in the form of

$$
\begin{equation*}
\left(r(t) \phi_{\gamma}\left(x^{\prime}(t)\right)\right)^{\prime}+p(t) \phi_{\gamma}\left(x^{\prime}(t)\right)+\sum_{j=0}^{N} q_{j}(t) \phi_{\alpha j}(x(t))=e(t) \tag{1.3}
\end{equation*}
$$

where $\alpha_{j}>0, j=0,1,2, \ldots, N$, such that

$$
\begin{equation*}
\alpha_{j}>\gamma, j=1,2, \ldots, m ; \quad \text { and } \quad \alpha_{j}<\gamma, j=m+1, l+2, \ldots, N \tag{1.4}
\end{equation*}
$$

and $r, p, q_{j}, e \in C([0, \infty), \mathbb{R})$ with $r(t)>0$ on $[0, \infty)$. They established oscillation criteria of El-Sayed-type and Kong-type for Eq. (1.3). Sun and Kong [34] considered the equation

$$
\left(r(t) x^{\prime}(t)\right)^{\prime}+q_{0}(t) x(t)+\int_{0}^{b} q(t, s) \phi_{\alpha(s)}(x(t)) d \zeta(s)=e(t)
$$

Recently, Hassan and Kong [17] established interval oscillation criteria of both the El-Sayed-type and the Kong-type for the more general equation

$$
\left(r(t) \phi_{\gamma}\left(x^{\prime}(t)\right)\right)^{\prime}+q_{0}(t) \phi_{\gamma}(x(t))+\int_{0}^{b} q(t, s) \phi_{\alpha(s)}(x(g(t, s))) d \zeta(s)=e(t)
$$

Motivated by above, in this paper, we will establish interval oscillation criteria of both the El-Sayed-type and the Kong-type for the more general equation (1.1).

This paper is organized as follows: after this introduction, we state lemmas, in Section 2, we state oscillation criteria for (1.1) with $g(t, s) \equiv t$, in Section 3 , we establish oscillation criteria for (1.1) with $g(t, s) \not \equiv t$.
2. Lemmas. We denote by $L_{\zeta}(a, b)$ the set of Riemann-Stieltjes integrables functions on $[a, b)$ with respect to $\zeta$. Let $c \in(a, b)$ such that $\alpha(c)=\mu$. We further assume that

$$
\alpha^{-1} \in L_{\zeta}(a, b) \quad \text { such that } \int_{a}^{c} d \zeta(s)>0 \text { and } \int_{c}^{b} d \zeta(s)>0
$$

To state our main results, we begin with the following lemmas which we will need in the proof of our main results. The following lemma generalizes [17, Lemma 2.1].

Lemma 2.1. Let

$$
m:=\mu\left(\int_{c}^{b} d \zeta(s)\right)^{-1} \int_{c}^{b} \alpha^{-1}(s) d \zeta(s)
$$

and

$$
n:=\mu\left(\int_{a}^{c} d \zeta(s)\right)^{-1} \int_{a}^{c} \alpha^{-1}(s) d \zeta(s)
$$

Then for any $\delta \in(m, n)$, there exists $\eta \in L_{\zeta}(a, b)$ such that $\eta(s)>0$ on $[a, b)$,

$$
\begin{equation*}
\int_{a}^{b} \alpha(s) \eta(s) d \zeta(s)=\mu \quad \text { and } \quad \int_{a}^{b} \eta(s) d \zeta(s)=\delta \tag{2.1}
\end{equation*}
$$

Proof. Let

$$
\eta_{1}(s):= \begin{cases}0, & s \in(a, c) \\ \mu \alpha^{-1}(s)\left(\int_{c}^{b} d \zeta(s)\right)^{-1}, & s \in[c, b)\end{cases}
$$

and

$$
\eta_{2}(s):= \begin{cases}\mu \alpha^{-1}(s)\left(\int_{a}^{c} d \zeta(s)\right)^{-1}, & s \in(a, c) \\ 0, & s \in[c, b)\end{cases}
$$

Clearly for $i=1,2, \eta_{i} \in L_{\zeta}(a, b)$ and

$$
\int_{a}^{b} \alpha(s) \eta_{i}(s) d \zeta(s)=\mu
$$

Moreover,

$$
\int_{a}^{b} \eta_{1}(s) d \zeta(s)=m \quad \text { and } \quad \int_{a}^{b} \eta_{2}(s) d \zeta(s)=n
$$

For $k \in[0,1]$ let

$$
\eta(s, k):=(1-k) \eta_{1}(s)+k \eta_{2}(s), \quad s \in[a, b) .
$$

Then it is easy to see that

$$
\int_{a}^{b} \alpha(s) \eta(s, k) d \zeta(s)=\mu
$$

Furthermore, since $\eta(s, 0)=\eta_{1}(s)$ and $\eta(s, 1)=\eta_{2}(s)$, we have

$$
\int_{a}^{b} \eta(s, 0) d \zeta(s)=m \quad \text { and } \quad \int_{a}^{b} \eta(s, 1) d \zeta(s)=n
$$

By the continuous dependence of $\eta(s, k)$ on $k$ there exists $k^{*} \in(0,1)$ such that $\eta(s):=\eta\left(s, k^{*}\right)$ satisfies

$$
\int_{a}^{b} \eta(s) d \zeta(s)=\delta
$$

Note that $\eta(s)>0$ for $s \in[a, b)$ and $\int_{a}^{b} \alpha(s) \eta(s) d \zeta(s)=\mu$ and the definitions of $m$ and $n$ gives $0<m<1<n$.

The next Lemma is a generalized Arithmetic-Geometric mean inequality established in [34].

Lemma 2.2. Let $u \in C[a, b)$ and $\eta \in L_{\zeta}(a, b)$ satisfying $u \geq 0, \eta>0$ on $[a, b)$ and $\int_{a}^{b} \eta(s) d \zeta(s)=1$. Then

$$
\int_{a}^{b} \eta(s) u(s) d \zeta(s) \geq \exp \left(\int_{a}^{b} \eta(s) \ln [u(s)] d \zeta(s)\right)
$$

where we use the convention that $\ln 0=-\infty$ and $e^{-\infty}=0$.
3. Oscillation Criteria for (1.1) with $g(t, s) \equiv t$. In this section, we establish oscillation criteria for equation (1.1) with $g(t, s) \equiv t$, namely,

$$
\begin{align*}
\left(r(t) \phi_{\gamma}\left(x^{\prime}(t)\right)\right)^{\prime}+p(t) \phi_{\gamma}\left(x^{\prime}(t)\right) & +q_{0}(t) \phi_{\beta}(x(t))  \tag{3.1}\\
& +\int_{a}^{b} q(t, s) \phi_{\alpha(s)}(x(t)) d \zeta(s)=e(t)
\end{align*}
$$

The first result provides an oscillation criterion of the El-Sayed-type.

Theorem 3.1. Suppose that for any $T \geq 0$ and for $i=1,2$, there exist constants $a_{i}$ and $b_{i}$ with $T \leq a_{i}<b_{i}$ such that, for $i=1,2$

$$
\begin{equation*}
q(t, s) \geq 0, \quad \text { for }(t, s) \in\left[a_{i}, b_{i}\right] \times[a, b) \tag{3.3}
\end{equation*}
$$

and

$$
\begin{equation*}
(-1)^{i} e(t) \geq 0, \text { for } t \in\left[a_{i}, b_{i}\right] \tag{3.4}
\end{equation*}
$$

Assume further that for $i=1,2$, there exist $u_{i} \in C^{1}\left[a_{i}, b_{i}\right]$ satisfying $u_{i}\left(a_{i}\right)=$ $u_{i}\left(b_{i}\right)=0, u_{i}(t) \not \equiv 0$ on $\left[a_{i}, b_{i}\right]$ and a continuous positive function $\rho(t)$ such that

$$
\begin{array}{r}
\sup _{\delta \in(m, 1]} \int_{a_{i}}^{b_{i}}\left[Q(t)\left|u_{i}(t)\right|^{\gamma+1}-\frac{\rho(t) r(t)}{(\gamma+1)^{\gamma+1}}\left[(\gamma+1)\left|u_{i}^{\prime}(t)\right|+\left|u_{i}(t)\right||P(t)|\right]^{\gamma+1}\right] d t  \tag{3.5}\\
>0
\end{array}
$$

where

$$
\begin{equation*}
P(t):=\frac{\rho^{\prime}(t)}{\rho(t)}-\frac{p(t)}{r(t)} \tag{3.6}
\end{equation*}
$$

and

$$
\begin{equation*}
Q(t):=\hat{\delta} \rho(t)\left(q_{0}(t)\right)^{(\gamma-\mu) /(\beta-\mu)}(\hat{q}(t))^{(\beta-\gamma) /(\beta-\mu)}, \tag{3.7}
\end{equation*}
$$

with

$$
\hat{\delta}:=(\beta-\mu)(\beta-\gamma)^{(\gamma-\beta) /(\beta-\mu)}(\gamma-\mu)^{(\mu-\gamma) /(\beta-\mu)}
$$

and

$$
\hat{q}(t):=\left[\frac{|e(t)|}{1-\delta}\right]^{1-\delta} \exp \left(\int_{a}^{b} \eta(s) \ln \left[\frac{q(t, s)}{\eta(s)}\right] d \zeta(s)\right)
$$

with $\eta(s)$ is defined as in Lemma 2.1 based on $\delta$. Here we use the convention that $\ln 0=-\infty, e^{-\infty}=0$, and $0^{1-\delta}=1$ and $(1-\delta)^{1-\delta}=1$ for $\delta=1$. Then Eq. (3.1) is oscillatory.

Proof. Assume Eq. (1.1) has an extendible solution $x(t)$ which is eventually positive or negative. Then, without loss of generality, assume $x(t)>0$ for all $t \geq T \geq 0$, where $T$ depends on the solution $x(t)$. When $x(t)$ is eventually
negative, the proof follows the same way except that the interval $\left[a_{2}, b_{2}\right]$, instead of $\left[a_{1}, b_{1}\right]$, is used. Define

$$
\begin{equation*}
z(t):=\rho(t) \frac{r(t) \phi_{\gamma}\left(x^{\prime}(t)\right)}{\phi_{\gamma}(x(t))}, t \geq T \tag{3.8}
\end{equation*}
$$

Then

$$
\begin{aligned}
z^{\prime}(t) & =\rho(t)\left[\frac{\left(r(t) \phi_{\gamma}\left(x^{\prime}(t)\right)\right)^{\prime}}{\phi_{\gamma}(x(t))}-\frac{r(t) \phi_{\gamma}\left(x^{\prime}(t)\right)\left(\phi_{\gamma}(x(t))^{\prime}\right.}{\left(\phi_{\gamma}(x(t))\right)^{2}}\right]+\rho^{\prime}(t) \frac{r(t) \phi_{\gamma}\left(x^{\prime}(t)\right)}{\phi_{\gamma}(x(t))} \\
(3.9) & =\rho(t)\left[\frac{\left(r(t) \phi_{\gamma}\left(x^{\prime}(t)\right)\right)^{\prime}}{\phi_{\gamma}(x(t))}-\frac{r(t) \phi_{\gamma}\left(x^{\prime}(t)\right)}{\phi_{\gamma}(x(t))} \frac{\gamma x^{\prime}(t)}{x(t)}\right]+\rho^{\prime}(t) \frac{r(t) \phi_{\gamma}\left(x^{\prime}(t)\right)}{\phi_{\gamma}(x(t))} .
\end{aligned}
$$

It follows from (1.1), (3.6) and (3.8) that for $t \geq T$,
$z^{\prime}(t)=-\rho(t) q_{0}(t) x^{\beta-\gamma}(t)-\rho(t) \int_{a}^{b} q(t, s)[x(t)]^{\alpha(s)-\gamma} d \zeta(s)+\rho(t) e(t) x^{-\gamma}(t)$
$(3.10)+P(t) z(t)-\frac{\gamma|z(t)|^{\frac{\gamma+1}{\gamma}}}{(\rho(t) r(t))^{\frac{1}{\gamma}}}$.
From the assumption, there exists a nontrivial interval $\left[a_{1}, b_{1}\right] \subset[T, \infty)$ such that (3.3) and (3.4) hold with $i=1$.
(I) We first consider the case where the supremum in (3.5) is assumed at $\delta=1$. From (3.4) and (3.10), we have that for $t \in\left[a_{1}, b_{1}\right]$

$$
\begin{gather*}
z^{\prime}(t) \leq-\rho(t) q_{0}(t) x^{\beta-\gamma}(t)-\rho(t) x^{\mu-\gamma}(t) \int_{q}^{b} q(t, s)[x(t)]^{\alpha(s)-\mu} d \zeta(s)  \tag{3.11}\\
+P(t) z(t)-\frac{\gamma|z(t)|^{\frac{\gamma q_{1}}{\gamma}}}{(\rho(t) r(t))^{\frac{1}{\gamma}}}
\end{gather*}
$$

Let $\eta \in L_{\zeta}(a, b)$ be defined as in Lemma 2.1 with $\delta=1$. Then $\eta$ satisfies (2.1) with $\delta=1$. This implies that

$$
\int_{a}^{b} \eta(s)[\alpha(s)-\mu] d \zeta=0
$$

Then, from Lemma 2.2, we get, for $t \in\left[a_{1}, b_{1}\right]$

$$
\begin{aligned}
& \int_{a}^{b} q(t, s)[x(t)]^{\alpha(s)-\mu} d \zeta(s) \\
= & \int_{a}^{b} \eta(s) \frac{q(t, s)}{\eta(s)}[x(t)]^{\alpha(s)-\mu} d \zeta(s)
\end{aligned}
$$

$$
\begin{aligned}
& \geq \exp \left(\int_{a}^{b} \eta(s) \ln \left(\frac{q(t, s)}{\eta(s)}[x(t)]^{\alpha(s)-\mu}\right) d \zeta(s)\right) \\
& =\exp \left(\int_{a}^{b} \eta(s) \ln \left[\frac{q(t, s)}{\eta(s)}\right] d \zeta(s)+\ln (x(t)) \int_{a}^{b} \eta(s)[\alpha(s)-\mu] d \zeta(s)\right) \\
& =\exp \left(\int_{a}^{b} \eta(s) \ln \left[\frac{q(t, s)}{\eta(s)}\right] d \zeta(s)\right)=\hat{q}(t)
\end{aligned}
$$

This together with (3.11) shows that
(3.12) $z^{\prime}(t) \leq-\rho(t) q_{0}(t) x^{\beta-\gamma}(t)-\rho(t) \hat{q}(t) x^{\mu-\gamma}(t)+P(t) z(t)-\frac{\gamma|z(t)|^{\frac{\gamma+1}{\gamma}}}{(\rho(t) r(t))^{\frac{1}{\gamma}}}$. Define

$$
X:=q_{0}^{1 /(\beta-\gamma)} x \quad \text { and } \quad Y:=\hat{q} q_{0}^{(\gamma-\mu) /(\beta-\gamma)}
$$

and using the inequality in [11, Lemma 2.1]

$$
X^{\beta-\gamma}+Y X^{\mu-\gamma} \geq \hat{\delta} Y^{(\beta-\gamma) /(\beta-\mu)} \quad \text { for all } \beta>\gamma>\mu>0
$$

where

$$
\hat{\delta}:=(\beta-\mu)(\beta-\gamma)^{(\gamma-\beta) /(\beta-\mu)}(\gamma-\mu)^{(\mu-\gamma) /(\beta-\mu)}
$$

we have

$$
\begin{equation*}
q_{0} x^{\beta-\gamma}+\hat{q} x^{\mu-\gamma} \geq \hat{\delta} \hat{q}^{(\beta-\gamma) /(\beta-\mu)} q_{0}^{(\gamma-\mu) /(\beta-\mu)} \tag{3.13}
\end{equation*}
$$

Substituting (3.13) into (3.12) and using the definition of $Q$, we obtain

$$
\begin{equation*}
z^{\prime}(t) \leq-Q(t)+P(t) z(t)-\frac{\gamma|z(t)|^{\frac{\gamma+1}{\gamma}}}{(\rho(t) r(t))^{\frac{1}{\gamma}}}, \quad \text { for } t \in\left[a_{1}, b_{1}\right] \tag{3.14}
\end{equation*}
$$

where $Q(t)$ is defined by (3.7) with $\delta=1$. Multiplying both sides of (3.14) by $\left|u_{1}(t)\right|^{\gamma+1}$, integrating from $a_{1}$ to $b_{1}$, and using integration by parts, we find that

$$
\begin{aligned}
& \int_{a_{1}}^{b_{1}} Q(t)\left|u_{1}(t)\right|^{\gamma+1} d t \\
\leq & \int_{a_{1}}^{b_{1}}\left\{(\gamma+1) \phi_{\gamma}\left(u_{1}(t)\right) u_{1}^{\prime}(t) z(t)+\left|u_{1}(t)\right|^{\gamma+1} P(t) z(t)\right. \\
& \left.-\frac{\gamma\left|u_{1}(t)\right|^{\gamma+1}}{(\rho(t) r(t))^{\frac{1}{\gamma}}}|z(t)|^{\frac{\gamma+1}{\gamma}}\right\} d t
\end{aligned}
$$

$$
\begin{align*}
\leq & \int_{a_{1}}^{b_{1}}\left\{\left|u_{1}(t)\right|^{\gamma}\left[(\gamma+1)\left|u_{1}^{\prime}(t)\right|+\left|u_{1}(t)\right||P(t)|\right]|z(t)|\right. \\
& \left.-\frac{\gamma\left|u_{1}(t)\right|^{\gamma+1}}{(\rho(t) r(t))^{\frac{1}{\gamma}}}|z(t)|^{\frac{\gamma+1}{\gamma}}\right\} d t . \tag{3.15}
\end{align*}
$$

Let $\lambda:=\frac{\gamma+1}{\gamma}$. Define $A$ and $B$ by

$$
A^{\lambda}:=\frac{\gamma\left|u_{1}(t)\right|^{\gamma+1}}{(\rho(t) r(t))^{\frac{1}{\gamma}}}|z(t)|^{\lambda},
$$

and

$$
B^{\lambda-1}:=\frac{\left(\gamma \rho(t) r(t) \frac{1}{\gamma+1}\right.}{\gamma+1}\left[(\gamma+1)\left|u_{1}^{\prime}(t)\right|+\left|u_{1}(t)\right||P(t)|\right] .
$$

Using the inequality in [13] we have

$$
\begin{equation*}
\lambda A B^{\lambda-1}-A^{\lambda} \leq(\lambda-1) B^{\lambda}, \tag{3.16}
\end{equation*}
$$

i.e.,

$$
\begin{gathered}
\left|u_{1}(t)\right|^{\gamma}\left[(\gamma+1)\left|u_{1}^{\prime}(t)\right|+\left|u_{1}(t)\right||P(t)|\right]|z(t)|-\frac{\gamma\left|u_{1}(t)\right|^{\gamma+1}}{(\rho(t) r(t))^{\frac{1}{\gamma}}}|z(t)|^{\lambda} \\
\leq \frac{\rho(t) r(t)}{(\gamma+1)^{\gamma+1}}\left[(\gamma+1)\left|u_{1}^{\prime}(t)\right|+\left|u_{1}(t)\right||P(t)|\right]^{\gamma+1},
\end{gathered}
$$

which together with (3.15) implies that

$$
\int_{a_{1}}^{b_{1}} Q(t)\left|u_{1}(t)\right|^{\gamma+1} d t \leq \int_{a_{1}}^{b_{1}} \frac{\rho(t) r(t)}{(\gamma+1)^{\gamma+1}}\left[(\gamma+1)\left|u_{1}^{\prime}(t)\right|+\left|u_{1}(t)\right||P(t)|\right]^{\gamma+1} d t .
$$

This leads to a contradiction to (3.5).
(II) Now, we consider the case where the supremum in (3.5) is assumed at $\delta \in(m, 1)$. Then from (3.4), we see that, for $t \in\left[a_{1}, b_{1}\right]$,

$$
\begin{align*}
z^{\prime}(t)= & -\rho(t) q_{0}(t) x^{\beta-\gamma}(t) \\
& -\rho(t) x^{\mu-\gamma}(t)\left(\int_{a}^{b} q(t, s)[x(t)]^{\alpha(s)-\mu} d \zeta(s)-\rho(t)|e(t)| x^{-\mu}(t)\right) \\
& +P(t) z(t)-\frac{\gamma|z(t)|^{\frac{\gamma+1}{\gamma}}}{(\rho(t) r(t))^{\frac{1}{\gamma}}} . \tag{3.17}
\end{align*}
$$

Let $\widetilde{\eta}(s):=\delta^{-1} \eta(s)$. Then, from (2.1), we have

$$
\begin{equation*}
\int_{a}^{b} \widetilde{\eta}(s) d \zeta(s)=1 \quad \text { and } \quad \int_{a}^{b} \widetilde{\eta}(s)[\delta \alpha(s)-\mu] d \zeta=0 \tag{3.18}
\end{equation*}
$$

Hence, for $t \in\left[a_{1}, b_{1}\right]$

$$
\begin{align*}
& \int_{a}^{b} q(t, s)[x(t)]^{\alpha(s)-\mu} d \zeta(s)+|e(t)| x^{-\mu}(t) \\
= & \int_{a}^{b} \widetilde{\eta}(s)\left(\delta \eta^{-1}(s) q(t, s)[x(t)]^{\alpha(s)-\mu}+|e(t)| x^{-\mu}(t)\right) d \zeta(s) \tag{3.19}
\end{align*}
$$

Using the Arithmetic-geometric mean inequality, see [2, Page 17],

$$
c h+d k \geq c^{h} d^{k}, \quad \text { where } c, d \geq 0, h, k>0 \text { and } h+k=1
$$

with

$$
c=\eta^{-1}(s) q(t, s)[x(t)]^{\alpha(s)-\mu}, d=\frac{1}{1-\delta}|e(t)| x^{-\mu}(t), h=\delta \text { and } k=1-\delta
$$

we have that for $t \in\left[a_{1}, b_{1}\right]$ and $s \in[a, b)$

$$
\begin{aligned}
\delta \eta^{-1}(s) q(t, s)[x(t)]^{\alpha(s)-\mu}+(1-\delta) & \frac{|e(t)|}{1-\delta} x^{-\mu}(t) \\
& \geq\left[\frac{q(t, s)}{\eta(s)}\right]^{\delta}\left[\frac{|e(t)|}{1-\delta}\right]^{1-\delta}[x(t)]^{\delta \alpha(s)-\mu}
\end{aligned}
$$

Substituting this into (3.19) and using Lemma 2.2 and (3.18), we see that,for $t \in\left[a_{1}, b_{1}\right]$,

$$
\begin{aligned}
& \int_{a}^{b} q(t, s)[x(t)]^{\alpha(s)-\mu} d \zeta(s)+|e(t)| x^{-\mu}(t) \\
& \geq \exp \left(\int_{a}^{b} \widetilde{\eta}(s) \ln \left(\left[\frac{q(t, s)}{\eta(s)}\right]^{\delta}\left[\frac{|e(t)|}{1-\delta}\right]^{1-\delta}[x(t)]^{\delta \alpha(s)-\mu}\right) d \zeta(s)\right) \\
&= \exp \left(\int_{a}^{b} \widetilde{\eta}(s)\left(\ln \left[\frac{q(t, s)}{\eta(s)}\right]^{\delta}+\ln \left[\frac{|e(t)|}{1-\delta}\right]^{1-\delta}+[\delta \alpha(s)-\mu] \ln x(t)\right) d \zeta(s)\right) \\
&\left(\neq 20\left[\frac{|e(t)|}{1-\delta}\right]^{1-\delta} \exp \left(\int_{a}^{b} \eta(s) \ln \frac{q(t, s)}{\eta(s)} d \zeta(s)\right)=\hat{q}(t)\right.
\end{aligned}
$$

It follows from (3.17) and (3.20), that we get, for $t \in\left[a_{1}, b_{1}\right]$,

$$
z^{\prime}(t) \leq-\rho(t) q_{0}(t) x^{\beta-\gamma}(t)-\rho(t) \hat{q}(t) x^{\mu-\gamma}(t)+P(t) z(t)-\frac{\gamma|z(t)|^{\frac{\gamma+1}{\gamma}}}{(\rho(t) r(t))^{\frac{1}{\gamma}}}
$$

$$
\begin{equation*}
\stackrel{(3.13)}{\leq}-Q(t)+P(t) z(t)-\frac{\gamma|z(t)|^{\frac{\gamma+1}{\gamma}}}{(\rho(t) r(t))^{\frac{1}{\gamma}}} \tag{3.21}
\end{equation*}
$$

where $Q$ is defined by (3.7) with $\delta \in(m, 1)$. The rest of the proof is similar to Part (I) and hence is omitted.

Example 3.1. Consider the second order differential equation

$$
\begin{align*}
\left((2+\cos 4 t)\left(x^{\prime}(t)\right)^{2}\right)^{\prime}-\sin t\left(x^{\prime}(t)\right)^{2} & +\cos t(x(t))^{3}  \tag{3.22}\\
& +\int_{0}^{1} \cos t \phi_{5 s}(x(t)) d s=-e^{t} \cos 2 t
\end{align*}
$$

Here we have
(i) $\alpha(s)=5 s, \xi(s)=s, \gamma=2, \beta=3, \mu=1 a=0$ and $b=1$;
(ii) $r(t)=2+\cos 4 t, p(t)=-\sin t, q_{0}(t)=q(t, s)=\cot s$, and $e(t)=$ $-e^{t} \cos 2 t$.

Note that

$$
m=\left(\int_{\frac{1}{5}}^{1} d s\right)^{-1}\left(\int_{\frac{1}{5}}^{1} \frac{1}{5 s} d s\right)=\ln \sqrt[4]{5}
$$

For any $\delta \in(\ln \sqrt[4]{5}, 1]$, we set

$$
\eta(s):=\frac{\delta}{5 \delta-1} s^{\frac{2-5 s}{5 \delta-1}}
$$

then (2.1) is satisfied. For any $T \in \mathbb{R}$, we choose $n \in \mathbb{N}$ so large that $2 n \pi \geq T$ and let

$$
a_{1}=2 n \pi, a_{2}=b_{1}=2 n \pi+\frac{\pi}{4}, b_{2}=2 n \pi+\frac{\pi}{2}
$$

Let $\rho(t)=2+\cos 4 t$, and for $i=1,2$ let $u_{i}(t)=\sin 4 t$.Then

$$
\begin{aligned}
\int_{0}^{\frac{\pi}{4}}\left(\frac { \rho ( t ) r ( t ) } { ( \gamma + 1 ) ^ { \gamma + 1 } } \left[(\gamma+1)\left|u_{i}^{\prime}(t)\right|+\left|u_{i}(t)\right|\right.\right. & \left.|P(t)|]^{\gamma+1}\right) d t \\
& =4 \int_{0}^{\frac{\pi}{4}}(2+\cos 4 t)^{2} \cos ^{3} 4 t d t=\frac{3}{2} \pi
\end{aligned}
$$

Therefore, it is easy to see that (3.5) is satisfied and hence Eq. (3.22) is oscillatory if

$$
\sup _{\delta \in(\ln \sqrt[4]{5}, 1]} \int_{0}^{\frac{\pi}{4}} 2(2+\cos 4 t) \sqrt{\cos t \hat{q}(t)} \sin ^{3} 4 t d t>\frac{3}{2} \pi
$$

where

$$
\hat{q}(t)=\left[\frac{\left|e^{t} \cos 2 t\right|}{1-\delta}\right]^{1-\delta} \exp \left(\int_{a}^{b} \eta(s) \ln \left[\frac{\cos t}{\eta(s)}\right] d s\right)
$$

Following Philos [27], Kong [22], and Kong [23], we say that for any $a, b \in$ $\mathbb{R}$ such that $a<b$, a function $H_{i}(t, s), i=1,2$, belongs to a function class $\mathcal{H}(a, b)$, denoted by $H_{i} \in \mathcal{H}(a, b)$, if $H_{i} \in C(\mathbb{D}, \mathbb{R})$, where $\mathbb{D}:=\{(t, s): b \geq t \geq s \geq a\}$, which satisfies

$$
\begin{equation*}
H_{i}(t, t)=0, \quad H_{i}(b, s)>0 \quad \text { and } \quad H_{i}(s, a)>0 \quad \text { for } b>s>a \tag{3.23}
\end{equation*}
$$

and $H_{i}(t, s)$ has continuous partial derivatives $\partial H_{i}(t, s) / \partial t$ and $\partial H_{i}(t, s) / \partial s$ on $[a, b] \times[a, b]$ such that for $i=1,2$,

$$
\begin{equation*}
\frac{\partial H_{i}(t, s)}{\partial t}+P(s) H_{i}(t, s)=(\gamma+1) h_{i 1}(t, s) H^{\frac{\gamma}{\gamma+1}}(t, s) \tag{3.24}
\end{equation*}
$$

and

$$
\begin{equation*}
\frac{\partial H_{i}(t, s)}{\partial s}+P(s) H_{i}(t, s)=(\gamma+1) h_{i 2}(t, s) H^{\frac{\gamma}{\gamma+1}}(t, s), \tag{3.25}
\end{equation*}
$$

where $h_{i 1}, h_{i 2} \in L_{\text {loc }}(\mathbb{D}, \mathbb{R})$. Next, we use the function class $\mathcal{H}(a, b)$ to establish an oscillation criterion for Eq. (1.1) of the Kong-type.

Theorem 3.2. Suppose that for any $T \geq 0$ and for $i=1,2$, there exist constants $a_{i}$ and $b_{i}$ with $T \leq a_{i}<b_{i}$ such that (3.3) and (3.4) hold. Assume further that for $i=1,2$, there exist $c_{i} \in\left(a_{i}, b_{i}\right)$ and $H_{i} \in \mathcal{H}\left(a_{i}, b_{i}\right)$ and a continuous positive function $\rho(t)$ such that

$$
\sup _{\delta \in(m, 1]}\left\{\frac{1}{H_{i}\left(c_{i}, a_{i}\right)} \int_{a_{i}}^{c_{i}}\left[Q(s) H_{i}\left(s, a_{i}\right)-\rho(s) r(s)\left|h_{i 1}\left(s, a_{i}\right)\right|^{\gamma+1}\right] d s\right.
$$

$$
\begin{equation*}
\left.+\frac{1}{H_{i}\left(b_{i}, c_{i}\right)} \int_{c_{i}}^{b_{i}}\left[Q(s) H_{i}\left(b_{i}, s\right)-\rho(s) r(s)\left|h_{i 2}\left(b_{i}, s\right)\right|^{\gamma+1}\right] d s\right\}>0 \tag{3.26}
\end{equation*}
$$

where $P(t)$ and $Q(t)$ are defined by (3.6) and (3.7), respectively. Then Eq. (3.1) is oscillatory.

Proof. Assume Eq. (3.1) has an extendible solution $x(t)$ which is eventually positive or negative. Then, without loss of generality, assume $x(t)>0$ for all $t \geq T \geq 0$, where $T$ depends on the solution $x(t)$. Define $z(t)$ by (3.8). From (3.14) and (3.21), we get that

$$
\begin{equation*}
z^{\prime}(t) \leq-Q(t)+P(t) z(t)-\frac{\gamma|z(t)|^{\frac{\gamma+1}{\gamma}}}{(\rho(t) r(t))^{\frac{1}{\gamma}}} \tag{3.27}
\end{equation*}
$$

Multiplying both sides of (3.27), with $t$ replaced by $s$, by $H_{1}\left(b_{1}, s\right)$ and integrating with respect to $s$ from $c_{1}$ to $b_{1}$, we find that

$$
\begin{aligned}
& \int_{c_{1}}^{b_{1}} Q(s) H_{1}\left(b_{1}, s\right) d s \\
\leq & -\int_{c_{1}}^{b_{1}} z^{\prime}(s) H_{1}\left(b_{1}, s\right) d s+\int_{c_{1}}^{b_{1}} P(s) z(s) H_{1}\left(b_{1}, s\right) d s \\
& -\int_{c_{1}}^{b_{1}} \frac{\gamma|z(t)|^{\frac{\gamma+1}{\gamma}}}{(\rho(t) r(t))^{\frac{1}{\gamma}}} H_{1}\left(b_{1}, s\right) d s
\end{aligned}
$$

Using integration by parts and from (3.23) and (3.25), we obtain

$$
\begin{aligned}
& \int_{c_{1}}^{b_{1}} Q(s) H_{1}\left(b_{1}, s\right) d s \\
\leq & z\left(c_{1}\right) H_{1}\left(b_{1}, c_{1}\right)+\int_{c_{1}}^{b_{1}}\left[(\gamma+1) h_{12}\left(b_{1}, s\right) H_{1}^{\frac{\gamma}{\gamma+1}}\left(b_{1}, s\right) z(s)\right. \\
& \left.-\frac{\gamma|z(s)|^{\frac{\gamma+1}{\gamma}} H_{1}\left(b_{1}, s\right)}{(\rho(s) r(s))^{\frac{1}{\gamma}}}\right] d s \\
\leq & z\left(c_{1}\right) H_{1}\left(b_{1}, c_{1}\right)+\int_{c_{1}}^{b_{1}}\left[(\gamma+1)\left|h_{12}\left(b_{1}, s\right)\right| H_{1}^{\frac{\gamma}{\gamma+1}}\left(b_{1}, s\right)|z(s)|\right.
\end{aligned}
$$

$$
\begin{equation*}
\left.-\frac{\gamma|z(s)|^{\frac{\gamma+1}{\gamma}} H_{1}\left(b_{1}, s\right)}{(\rho(s) r(s))^{\frac{1}{\gamma}}}\right] d s \tag{3.28}
\end{equation*}
$$

Let $\lambda=\frac{\gamma+1}{\gamma}$. Define $A$ and $B$ by

$$
A^{\lambda}:=\frac{\gamma|z(s)|^{\lambda} H_{1}\left(b_{1}, s\right)}{(\rho(s) r(s))^{\frac{1}{\gamma}}} \text { and } B^{\lambda-1}:=(\gamma \rho(s) r(s))^{\frac{1}{\gamma+1}}\left|h_{12}\left(b_{1}, s\right)\right|
$$

Then, using the inequality (3.16), we get that

$$
\begin{aligned}
&(\gamma+1)\left|h_{12}\left(b_{1}, s\right)\right| H_{1}^{\frac{\gamma}{\gamma+1}}\left(b_{1}, s\right)|z(s)| \\
&-\frac{\gamma|z(s)|^{\frac{\gamma+1}{\gamma}} H_{1}\left(b_{1}, s\right)}{(\rho(s) r(s))^{\frac{1}{\gamma}}} \leq \rho(s) r(s)\left|h_{12}\left(b_{1}, s\right)\right|^{\gamma+1} .
\end{aligned}
$$

This together with (3.28) shows that

$$
\begin{equation*}
\frac{1}{H_{1}\left(b_{1}, c_{1}\right)} \int_{c_{1}}^{b_{1}}\left[Q(s) H_{1}\left(b_{1}, s\right)-\rho(s) r(s)\left|h_{12}\left(b_{1}, s\right)\right|^{\gamma+1}\right] d s \leq z\left(c_{1}\right) \tag{3.29}
\end{equation*}
$$

Similarly, multiplying both sides of (3.27), with $t$ replaced by $s$, by $H_{1}\left(s, a_{1}\right)$ and integrating by parts from $a_{1}$ to $c_{1}$, we see that

$$
\begin{equation*}
\frac{1}{H_{1}\left(c_{1}, a_{1}\right)} \int_{a_{1}}^{c_{1}}\left[Q(s) H_{1}\left(s, a_{1}\right)-\rho(s) r(s)\left|h_{11}\left(s, a_{1}\right)\right|^{\gamma+1}\right] d s \leq-z\left(c_{1}\right) \tag{3.30}
\end{equation*}
$$

Combining (3.29) and (3.30) we get that

$$
\begin{aligned}
& \frac{1}{H_{1}\left(c_{1}, a_{1}\right)} \int_{a_{1}}^{c_{1}}\left[Q(s) H_{1}\left(s, a_{1}\right)-\rho(s) r(s) h_{11}^{\gamma+1}\left(s, a_{1}\right)\right] d s \\
+ & \frac{1}{H_{1}\left(b_{1}, c_{1}\right)} \int_{c_{1}}^{b_{1}}\left[Q(s) H_{1}\left(b_{1}, s\right)-\rho(s) r(s) h_{12}^{\gamma+1}\left(b_{1}, s\right)\right] d s \leq 0 .
\end{aligned}
$$

This contradicts (3.26) with $i=1$. This completes the proof.
4. Oscillation Criteria for (1.1) with $g(t, s) \not \equiv t$. In this section we prove oscillation criteria for Eq. (1.1) with both cases of delay and advanced types. In the follwoing, we will use the notations:

$$
\begin{gathered}
g_{*}(t)=\inf _{s \in[a, b)}\{t, g(t, s)\} \text { and } g^{*}(t)=\sup _{s \in[a, b)}\{t, g(t, s)\} ; \\
\psi_{i}(t, s):= \begin{cases}\delta_{i}(t, s), & g(t, s)<t, \\
\zeta_{i}(t, s), & g(t, s)>t ;\end{cases}
\end{gathered}
$$

with

$$
\delta_{i}(t, s):=\frac{R\left(g(t, s), g\left(a_{i}, s\right)\right)}{R\left(t, g\left(a_{i}, s\right)\right)}
$$

and

$$
\begin{aligned}
\zeta_{i}(t, s) & :=\frac{R\left(g\left(b_{i}, s\right), g(t, s)\right)}{R\left(g\left(b_{i}, s\right), t\right)}, \\
R\left(t, t_{0}\right) & :=\int_{t_{0}}^{t} \tilde{r}^{-\frac{1}{\gamma}}(u) d u, \tilde{r}(t) \\
& :=r(t)\left[\exp \int_{0}^{t} \frac{p(v)}{r(v)} d v\right] \text { and } \hat{q}(t, s):=q(t, s)\left[\psi_{1}(t, s)\right]^{\alpha(s)} .
\end{aligned}
$$

Theorem 4.1. Suppose that for any $T \geq 0$ and for $i=1,2$, there exist constants $a_{i}, b_{i} \in[T, \infty)$ with $a_{i}<b_{i}$, such that

$$
\begin{gather*}
q_{0}(t) \geq 0 \quad \text { for } t \in\left[g_{*}\left(a_{i}\right), g^{*}\left(b_{i}\right)\right]  \tag{4.1}\\
q(t, s) \geq 0 \quad \text { for }(t, s) \in\left[g_{*}\left(a_{i}\right), g^{*}\left(b_{i}\right)\right] \times[a, b) \tag{4.2}
\end{gather*}
$$

and

$$
\begin{equation*}
(-1)^{i} e(t) \geq 0, \text { for } t \in\left[g_{*}\left(a_{i}\right), g^{*}\left(b_{i}\right)\right] \tag{4.3}
\end{equation*}
$$

Assume further that for $i=1,2$, there exist $u_{i} \in C^{1}\left[a_{i}, b_{i}\right]$ satisfying $u_{i}\left(a_{i}\right)=$ $u_{i}\left(b_{i}\right)=0, u_{i}(t) \not \equiv 0$ on $\left[a_{i}, b_{i}\right]$ and a continuous positive function $\rho(t)$ such that

$$
\sup _{\delta \in(m, 1]} \int_{a_{i}}^{b_{i}}\left[\hat{Q}(t)\left|u_{i}(t)\right|^{\gamma+1}-\frac{\rho(t) r(t)}{(\gamma+1)^{\gamma+1}}\left[(\gamma+1)\left|u_{1}^{\prime}(t)\right|+\left|u_{1}(t)\right||P(t)|\right]^{\gamma+1}\right] d t>0
$$

where $P(t)$ is defined by (3.6) and

$$
\begin{equation*}
\hat{Q}(t):=\hat{\delta} \rho(t)\left(q_{0}(t)\right)^{(\gamma-\mu) /(\beta-\mu)}(\bar{q}(t))^{(\beta-\gamma) /(\beta-\mu)} \tag{4.4}
\end{equation*}
$$

with

$$
\hat{\delta}:=(\beta-\mu)(\beta-\gamma)^{(\gamma-\beta) /(\beta-\mu)}(\gamma-\mu)^{(\mu-\gamma) /(\beta-\mu)}
$$

and

$$
\bar{q}(t):=\left[\frac{|e(t)|}{1-\delta}\right]^{1-\delta} \exp \left(\int_{a}^{b} \eta(s) \ln \left[\frac{\hat{q}(t, s)}{\eta(s)}\right] d \zeta(s)\right)
$$

with $\eta(s)$ is defined as in Lemma 2.1 based on $\delta$. Here we use the convention that $\ln 0=-\infty, e^{-\infty}=0$, and $0^{1-\delta}=1$ and $(1-\delta)^{1-\delta}=1$ for $\delta=1$. Then Eq. (1.1) is oscillatory.

Proof. Assume Eq. (1.1) has an extendible solution $x(t)$ which is eventually positive or negative. Then, without loss of generality, we may assume $x(t)$, $x(g(t, s))>0$, for $t \in[T, \infty)$ and $s \in[a, b]$. Define $z(t)$ by (3.8). From (1.1) and (3.9), we have for $t \geq T$,

$$
\begin{align*}
z^{\prime}(t)= & -\rho(t) q_{0}(t) x^{\beta-\gamma}(t) \\
& -\rho(t) \int_{a}^{b} q(t, s) \frac{[x(g(t, s))]^{\alpha(s)}}{[x(t)]^{\gamma}} d \zeta(s)+\rho(t) e(t) x^{-\gamma}(t) \\
& +P(t) z(t)-\frac{\gamma|z(t)|^{\frac{\gamma+1}{\gamma}}}{(\rho(t) r(t))^{\frac{1}{\gamma}}} \tag{4.5}
\end{align*}
$$

From the assumption, there exist constants $a_{1}$ and $b_{1}$ with $a_{1}<b_{1}$ and $\left[g_{*}\left(a_{1}\right), g^{*}\left(b_{1}\right)\right] \subset\left[t_{0}, \infty\right)$ such that (4.1), (4.2) and (4.3) hold with $i=1$. From (1.1), we get, for $t \in\left[g_{*}\left(a_{1}\right), g^{*}\left(b_{1}\right)\right]$,

$$
\begin{aligned}
& \left(\tilde{r}(t) \phi_{\gamma}\left(x^{\prime}(t)\right)\right)^{\prime} \\
= & {\left[\exp \int_{0}^{t} \frac{p(v)}{r(v)} d v\right]\left(r(t) \phi_{\gamma}\left(x^{\prime}(t)\right)\right)^{\prime}+\left[\exp \int_{0}^{t} \frac{p(v)}{r(v)} d v\right] p(t) \phi_{\gamma}\left(x^{\prime}(t)\right) } \\
= & {\left[\exp \int_{0}^{t} \frac{p(v)}{r(v)} d v\right]\left[-q_{0}(t) \phi_{\beta}(x(t))-\int_{a}^{b} q(t, s) \phi_{\alpha(s)}(x(g(t, s))) d \zeta(s)+e(t)\right] } \\
\leq & 0
\end{aligned}
$$

Then $\tilde{r}(t) \phi_{\gamma}\left(x^{\prime}(t)\right)$ is nonincreasing on $\left[g_{*}\left(a_{1}\right), g^{*}\left(b_{1}\right)\right]$. Now we consider the following two cases:
Case (a): Delay type, i.e. $g(t, s) \leq t$, for $t \in[a, b]$ and $s \in[a, b]$. Since $\tilde{r}(t) \phi_{\gamma}\left(x^{\prime}(t)\right)$ is nonincreasing on $\left[g_{*}\left(a_{1}\right), g^{*}\left(b_{1}\right)\right]$. Then

$$
\begin{aligned}
x(t)-x(g(t, s)) & =\int_{g(t, s)}^{t} \phi_{\gamma}^{-1}\left(\tilde{r}(u) \phi_{\gamma}\left(x^{\prime}(u)\right)\right) \tilde{r}^{-\frac{1}{\gamma}}(u) d u \\
& \leq \phi_{\gamma}^{-1}\left[\tilde{r} \phi_{\gamma}\left(x^{\prime}\right)(g(t, s))\right] \int_{g(t, s)}^{t} \tilde{r}^{-\frac{1}{\gamma}}(u) d u \\
& =\phi_{\gamma}^{-1}\left[\tilde{r} \phi_{\gamma}\left(x^{\prime}\right)(g(t, s))\right] R(t, g(t, s))
\end{aligned}
$$

where $\phi_{\gamma}^{-1}$ is the inverse function of $\phi_{\gamma}$, and so

$$
\begin{equation*}
\frac{x(t)}{x(g(t, s))} \leq 1+\frac{\phi_{\gamma}^{-1}\left[\tilde{r} \phi_{\gamma}\left(x^{\prime}\right)(g(t, s))\right]}{x(g(t, s))} R(t, g(t, s)) \tag{4.6}
\end{equation*}
$$

We also see that for $t \in\left[a_{1}, g^{*}\left(b_{1}\right)\right]$

$$
\begin{aligned}
x(g(t, s)) & >x(g(t, s))-x\left(g\left(a_{1}, s\right)\right)=\int_{g\left(a_{1}, s\right)}^{g(t, s)} \phi_{\gamma}^{-1}\left(\tilde{r}(u) \phi_{\gamma}\left(x^{\prime}(u)\right)\right) \tilde{r}^{-\frac{1}{\gamma}}(u) d u \\
& \geq \phi_{\gamma}^{-1}\left[\tilde{r} \phi_{\gamma}\left(x^{\prime}\right)(g(t, s))\right] \int_{g\left(a_{1}, s\right)}^{g(t, s)} \tilde{r}^{-\frac{1}{\gamma}}(u) d u \\
& =\phi_{\gamma}^{-1}\left[\tilde{r} \phi_{\gamma}\left(x^{\prime}\right)(g(t, s))\right] R\left(g(t, s), g\left(a_{1}, s\right)\right)
\end{aligned}
$$

which implies that for $t \in\left(a_{1}, g^{*}\left(b_{1}\right)\right]$

$$
\begin{equation*}
\frac{\left.\phi_{\gamma}^{-1}\left[\tilde{r} \phi_{\gamma}\left(x^{\prime}\right)(g(t, s))\right]\right)}{x(g(t, s))}<\frac{1}{R\left(g(t, s), g\left(a_{1}, s\right)\right)} \tag{4.7}
\end{equation*}
$$

Therefore, the combination of (4.6) and (4.7) shows that for $t \in\left(a_{1}, g^{*}\left(b_{1}\right)\right]$

$$
\frac{x(t)}{x(g(t, s))}<1+\frac{R(t, g(t, s))}{R\left(g(t, s), g\left(a_{1}, s\right)\right)}=\frac{R\left(t, g\left(a_{1}, s\right)\right)}{R\left(g(t, s), g\left(a_{1}, s\right)\right)}=\frac{1}{\delta_{1}(t, s)} .
$$

Hence

$$
\begin{equation*}
x(g(t, s))>\delta_{1}(t, s) x(t), \quad \text { for } t \in\left[a_{1}, g^{*}\left(b_{1}\right)\right] . \tag{4.8}
\end{equation*}
$$

Case (b): advanced type, i.e. $g(t, s)>t$, for $t \in[a, b]$ and $s \in[a, b]$. Since $\tilde{r}(t) \phi_{\gamma}\left(x^{\prime}(t)\right)$ is nonincreasing on $\left[g_{*}\left(a_{1}\right), g^{*}\left(b_{1}\right)\right]$, we have, for $t \in\left[g_{*}\left(a_{1}\right), b_{1}\right]$

$$
\begin{aligned}
x(g(t, s))-x(t) & =\int_{t}^{g(t, s)} \phi_{\gamma}^{-1}\left(\tilde{r}(u) \phi_{\gamma}\left(x^{\prime}(u)\right)\right) \tilde{r}^{-\frac{1}{\gamma}}(u) d u \\
& \geq \phi_{\gamma}^{-1}\left[\tilde{r} \phi_{\gamma}\left(x^{\prime}\right)(g(t, s))\right] \int_{t}^{g(t, s)} \tilde{r}^{-\frac{1}{\gamma}}(u) d u \\
& =\phi_{\gamma}^{-1}\left[\tilde{r} \phi_{\gamma}\left(x^{\prime}\right)(g(t, s))\right] R(g(t, s), t)
\end{aligned}
$$

and so

$$
\begin{equation*}
\frac{x(t)}{x(g(t, s))} \leq 1-\frac{\phi_{\gamma}^{-1}\left[\tilde{r} \phi_{\gamma}\left(x^{\prime}\right)(g(t, s))\right]}{x(g(t, s))} R(g(t, s), t) . \tag{4.9}
\end{equation*}
$$

Also, we see that, for $t \in\left[g_{*}\left(a_{1}\right), b_{1}\right]$

$$
-x(g(t, s))<x\left(g\left(b_{1}, s\right)\right)-x(g(t, s))=\int_{g(t, s)}^{g\left(b_{1}, s\right)} \phi_{\gamma}^{-1}\left(\tilde{r}(u) \phi_{\gamma}\left(x^{\prime}(u)\right)\right) \tilde{r}^{-\frac{1}{\gamma}}(u) d u
$$

$$
\begin{aligned}
& \leq \phi_{\gamma}^{-1}\left[\tilde{r} \phi_{\gamma}\left(x^{\prime}\right)(g(t, s))\right] \int_{g(t, s)}^{g\left(b_{1}, s\right)} \tilde{r}^{-\frac{1}{\gamma}}(u) d u \\
& =\phi_{\gamma}^{-1}\left[\tilde{r} \phi_{\gamma}\left(x^{\prime}\right)(g(t, s))\right] R\left(g\left(b_{1}, s\right), g(t, s)\right)
\end{aligned}
$$

which implies for $t \in\left[g_{*}\left(a_{1}\right), b_{1}\right)$, that

$$
\begin{equation*}
-\frac{\phi_{\gamma}^{-1}\left[\tilde{r} \phi_{\gamma}\left(x^{\prime}\right)(g(t, s))\right]}{x(g(t, s))}<\frac{1}{R\left(g\left(b_{1}, s\right), g(t, s)\right)} \tag{4.10}
\end{equation*}
$$

Thus, (4.9) and (4.10) imply, for $t \in\left[g_{*}\left(a_{1}\right), b_{1}\right)$

$$
\frac{x(t)}{x(g(t, s))}<1-\frac{R(g(t, s), t)}{R\left(g\left(b_{1}, s\right), g(t, s)\right)}=\frac{R\left(g\left(b_{1}, s\right), t\right)}{R\left(g\left(b_{1}, s\right), g(t, s)\right)}=\frac{1}{\zeta_{1}(t, s)} .
$$

Hence

$$
\begin{equation*}
x(g(t, s))>\zeta_{1}(t, s) x(t), \quad \text { for } t \in\left[g_{*}\left(a_{1}\right), b_{1}\right] . \tag{4.11}
\end{equation*}
$$

From (4.8) and (4.11), we get

$$
x(g(t, s)) \geq \psi_{1}(t, s) x(t), \quad \text { for } t \in\left[a_{1}, b_{1}\right] \text { and } s \in[a, b)
$$

Then (4.5) becomes, for two caes (a) and (b),

$$
\begin{aligned}
z^{\prime}(t) \leq & -\rho(t) q_{0}(t) x^{\beta-\gamma}(t)-\rho(t) \int_{a}^{b} \hat{q}(t, s)[x(t)]^{\alpha(s)-\gamma} d \zeta(s)+\rho(t) e(t) x^{-\gamma}(t) \\
& +P(t) z(t)-\frac{\gamma|z(t)|^{\frac{\gamma+1}{\gamma}}}{(\rho(t) r(t))^{\frac{1}{\gamma}}}
\end{aligned}
$$

where $\hat{q}(t, s)=q(t, s)\left[\psi_{1}(t, s)\right]^{\alpha(s)}$. The rest of the proof is similar to that of Theorem 3.1 after (3.11) and hence is omitted.

Theorem 4.2. Suppose that for any $T \geq 0$ and for $i=1,2$, there exist constants $a_{i}$ and $b_{i}$ with $T \leq a_{i}<b_{i}$ such that (4.1), (4.2) and (4.3) hold. Assume further that for $i=1,2$, there exist $c_{i} \in\left(a_{i}, b_{i}\right)$ and $H_{i} \in \mathcal{H}\left(a_{i}, b_{i}\right)$ and a continuous positive function $\rho(t)$ such that

$$
\begin{aligned}
& \sup _{\delta \in(m, 1]}\left\{\frac{1}{H_{i}\left(c_{i}, a_{i}\right)} \int_{a_{i}}^{c_{i}}\left[\hat{Q}(s) H_{i}\left(s, a_{i}\right)-\rho(s) r(s)\left|h_{i 1}\left(s, a_{i}\right)\right|^{\gamma+1}\right] d s\right. \\
& \left.+\frac{1}{H_{i}\left(b_{i}, c_{i}\right)} \int_{c_{i}}^{b_{i}}\left[\hat{Q}(s) H_{i}\left(b_{i}, s\right)-\rho(s) r(s)\left|h_{i 2}\left(b_{i}, s\right)\right|^{\gamma+1}\right] d s\right\}>0,
\end{aligned}
$$

where $P(t)$ and $\hat{Q}(t)$ are defined by (3.6) and (4.4), respectively. Then Eq. (3.1) is oscillatory.

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