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Quasidiagonal Operators in Tridiagonal Algebras

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Presented by M. Putinar

1. Introduction

A given subset \mathcal{R} of the algebra $\mathcal{L}(\mathcal{H})$ of all (bounded linear) operators acting on a complex, separable, infinite dimensional Hilbert space \mathcal{H} , the question —

What kinds of operators do we have in \mathcal{R} ? —

admits several possible answers. The most obvious one is the description of the unitary orbit of \mathcal{R} ,

$$\mathcal{U}(\mathcal{R}) = \{UTU^* : T \in \mathcal{R}, U \text{ is unitary}\}.$$

But this can be too restrictive. A slightly weaker version is a description of the approximate unitary orbit, $\mathcal{U}(\mathcal{R})^-$ (= the norm-closure of $\mathcal{U}(\mathcal{R})$ in $\mathcal{L}(\mathcal{H})$).

Another possible answer is the description of $\mathcal{U}(\mathcal{R})$ modulo compact operators, that is

$$\hat{\mathcal{R}} = \mathcal{U}(\mathcal{R}) + \mathcal{K}(\mathcal{H}),$$

where $\mathcal{K}(\mathcal{H})$ denotes the ideal of all compact operators. Finally, in a combination of the last two, we can also consider the set

$$\hat{\mathcal{R}}_0 = \{A \in \mathcal{L}(\mathcal{H}) : \text{given } \varepsilon > 0 \text{ there exists } K_\varepsilon \in \mathcal{K}(\mathcal{H}),$$

$$\text{with } \|K_\varepsilon\| < \varepsilon, \text{ such that } A - K_\varepsilon \in \mathcal{U}(\mathcal{R})\}$$

(Clearly, $\hat{\mathcal{R}}_0 \subset \hat{\mathcal{R}} \cap \mathcal{U}(\mathcal{R})^-$.)

In [13] and [14], D. A. Herrero analyzed these sets for the case when \mathcal{R} is the nest algebra $\text{alg } \mathcal{N}$ associated with a nest of subspaces \mathcal{N} of \mathcal{H} . (The reader is referred to [3] for definition and properties of nests and nest algebras). In this particular case, $\hat{\mathcal{N}}$ and $\hat{\mathcal{N}}_0$ are always closed subsets of $\mathcal{L}(\mathcal{H})$, and therefore $\hat{\mathcal{N}}_0 = \mathcal{U}(\text{alg } \mathcal{N})^-$; moreover, in “most cases” $\hat{\mathcal{N}} = \hat{\mathcal{N}}_0 = \mathcal{L}(\mathcal{H})$. In [18], D. A. Herrero and D. R. Larson obtained spectral characterizations of $\hat{\mathcal{R}}^\infty(\mathcal{N})$ and

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of natural numbers tending to infinity fast enough, then $\mathcal{F}(\{m_k\})_0^\wedge$ and $\mathcal{U}(\mathcal{F}(\{m_k\}))^-$ should contain every biquasitriangular operator. But this is definitely FALSE.

Let

$$(\text{BD})_{\text{nor}} = \{B = \Sigma \oplus_{n=1}^\infty B_n : B_n \text{ acts on a space of finite dimension } d_n, \text{ and } \sup_n d_n < \infty\}$$

(= the set of all “ n -normal” block-diagonal operators; this set plays a very interesting role in quasidiagonal approximation [5]).

It will be shown that if $(\text{BD})_{\text{nor}} \subset \mathcal{F}(\{m_k\})$, then

$$(*) \quad m_k + m_{k+1} + m_{k+2} = \infty \text{ for all } k \geq 0.$$

(Here $m_0 = 0$).

On the other hand, if $\{m_k\}$ satisfies (*), then

$$\mathcal{U}(\mathcal{F}(\{m_k\}))^- = \mathcal{F}(\{m_k\})_0^\wedge = \mathcal{L}(\mathcal{H}).$$

For $\mathcal{F}(\{m_k\})^\wedge$ we only have weaker results: If $(\text{BD})_{\text{nor}} \subset \mathcal{F}(\{m_k\})^\wedge$, then

$$\lim_{k \rightarrow \infty} (m_k + m_{k+1} + m_{k+2}) = \infty.$$

If $\lim_{k \rightarrow \infty} m_k = \infty$, then $(\text{BD})_{\text{nor}} \subset \mathcal{F}(\{m_k\})^\wedge$.

However, it is known that $(\text{BD})_{\text{nor}}$ is not dense in the class (QD) of all quasidiagonal operators [21], [23], [24]. Indeed, $(\text{QD})_{\text{nor}} := [(\text{BD})_{\text{nor}}]^-$ is a nowhere dense subset of (QD) [5] (and (QD) is well-known to be a nowhere dense subset of the class (BQT) of all biquasitriangular operators [11]).

Open problem. Does $(\text{QD}) \subset \mathcal{F}(\{m_k\})^\wedge$ imply that $m_{k-1} + m_k + m_{k+1} = \infty$ for all k large enough?

2. When is $(\text{BD})_{\text{nor}} \subset \mathcal{U}(\mathcal{F}(\{m_k\}))^-$?

Theorem 2.1. *The following are equivalent*

- (i) $\mathcal{U}(\mathcal{F}(\{m_k\}))^- \supset (\text{BD})_{\text{nor}}$;
- (ii) $m_k + m_{k+1} + m_{k+2} = \infty$ for all $k \geq 0$ ($m_0 = 0$);
- (iii) $\mathcal{F}(\{m_k\})_0^\wedge = \mathcal{L}(\mathcal{H})$.

Let
$$A_n = \begin{vmatrix} 1 & 1 & 1 & \dots & 1 \\ & 2 & 1 & \dots & 1 \\ & & 3 & \dots & 1 \\ & & & \dots & \dots \\ & 0 & & \dots & \dots \\ & & & & n \end{vmatrix}$$

with respect to the orthogonal direct sum decomposition $\mathcal{H} = \Sigma \oplus_{k=1}^n \mathcal{H}_k$ ($\mathcal{H}_k \simeq \mathcal{H}$, $k=1, 2, \dots, n$). It is obvious that $A_n \in (\text{BD})_{\text{nor}}$, A_n is unitarily equivalent to the direct sum of infinitely many copies of the $n \times n$ complex matrix (with the same entries with respect to the decomposition $\mathbb{C}^n = \mathbb{C} \oplus \mathbb{C} \oplus \dots \oplus \mathbb{C}$), and the spectrum of A_n is equal to $\sigma(A_n) = \{1, 2, \dots, n\}$.

Let $\mathcal{G}_k = \ker(A_n - k)$ and $\mathcal{G}_k^* = \ker(A_n - k)^*$ ($k=1, 2, \dots, n$). Clearly, $\mathcal{G}_k = \mathcal{H}(A_n; k)$, where $\mathcal{H}(T; \sigma)$ denotes the Riesz spectral invariant subspace of the operator T associated with the clopen subset σ of $\sigma(T)$ (if $\sigma = \{\lambda\}$ is a singleton, we simply write $\mathcal{H}(T; \lambda)$).

By Gauss-Jordan elimination [1], we obtain

$$\mathcal{G}_k = \{x \oplus x \oplus \dots \oplus x (k\text{-copies}) \oplus 0 \oplus 0 \oplus \dots \oplus 0 : x \in \mathcal{H}\}$$

($k=1, 2, \dots, n$),

$$\mathcal{G}_k^* = \{0 \oplus \dots \oplus 0 (k-1 \text{ copies}) \oplus x \oplus (-x) \oplus 0 \oplus \dots \oplus 0 : x \in \mathcal{H}\}$$

($k=1, 2, \dots, n-1$), and $\mathcal{G}_n^* = \{0 \oplus 0 \oplus \dots \oplus 0 \oplus x : x \in \mathcal{H}\}$.

We have $\mathcal{H} = \Sigma \dot{+}_{k=1}^n \mathcal{G}_k = \Sigma \dot{+}_{k=1}^n \mathcal{G}_k^*$, where $\dot{+}$ denotes algebraic (but not necessarily orthogonal) direct sum.

Lemma 2.2. *Let \mathcal{X} be the direct sum of r ($0 < r < n$) subspaces of the family $\{\mathcal{G}_1, \mathcal{G}_2, \dots, \mathcal{G}_n\}$, and let \mathcal{X}^* be the direct sum of $n-r$ subspaces of the family $\{\mathcal{G}_1^*, \mathcal{G}_2^*, \dots, \mathcal{G}_n^*\}$. Then*

$$\mathcal{H} = \mathcal{X} \dot{+} \mathcal{X}^*,$$

that is, $\mathcal{X} \cap \mathcal{X}^* = \{0\}$, $\mathcal{H} = \mathcal{X} + \mathcal{X}^*$ and

$$\inf \{ \|x - x^*\| : x \in \mathcal{X}, x^* \in \mathcal{X}^*, \|x\| = \|x^*\| = y \} \geq \delta$$

for some positive constant δ depending only n .

Proof. As mentioned above, $A_n = B_n^{(\infty)}$, where B_n is the operator defined by the obvious $n \times n$ matrix with respect to the canonical orthogonal basis of \mathbb{C}^n . Given \mathcal{X} and \mathcal{X}^* as above, let \mathcal{Y} and \mathcal{Y}^* be the intersection of \mathcal{X} and, respectively, \mathcal{X}^* with the "first copy" of \mathbb{C}^n .

It is straightforward to check that $\mathcal{Y} \cap \mathcal{Y}^* = \{0\}$. Since $\dim \mathcal{Y} + \dim \mathcal{Y}^* = r + (n-r) = n = \dim \mathbb{C}^n$, we infer that $\mathbb{C}^n = \mathcal{Y} \dot{+} \mathcal{Y}^*$, and therefore

$$\min \{ \|y - y^*\| : y \in \mathcal{Y}, y^* \in \mathcal{Y}^*, \|y\| = \|y^*\| = 1 \} = \delta(\mathcal{Y}, \mathcal{Y}^*)$$

for some $\delta(\mathcal{Y}, \mathcal{Y}^*) > 0$.

Since there are only finitely many possible choices for \mathcal{Y} and \mathcal{Y}^* , we see that

$$\delta := \min_{y, y^*} \delta(\mathcal{Y}, \mathcal{Y}^*) > 0.$$

Now the result follows by observing that $\mathcal{H} = \Sigma \oplus_{k=1}^n \mathcal{H}_k \simeq \mathcal{H} \otimes \mathbb{C}^n \simeq \mathbb{C}^n \oplus \mathbb{C}^n \oplus \dots$ ■

The following is the key result of this article.

Theorem 2.3. *Let \mathcal{R} be a subset of $\mathcal{L}(\mathcal{H})$ such that $\mathcal{U}(\mathcal{R})^- \supset (\text{BD})_{\text{nor}}$. Let \mathcal{M} and \mathcal{N} be two subspaces of \mathcal{H} such that \mathcal{M} is invariant under \mathcal{R} and \mathcal{N} is invariant under $\mathcal{R}^* (= \{T^* : T \in \mathcal{R}\})$.*

- (i) If $\mathcal{N} \supset \mathcal{M} \neq \{0\}$, then \mathcal{N} is infinite dimensional;
- (ii) If $\mathcal{M} \supset \mathcal{N} \neq \{0\}$, then \mathcal{M} is infinite dimensional.

Proof. Let A_n be as above. For each ε , $0 < \varepsilon \ll 1$, there exist R_n in \mathcal{R} and U unitary such that $\|A_n - UR_nU^*\| < \varepsilon$.

By replacing, if necessary, \mathcal{M} and \mathcal{N} by $U\mathcal{M}$ and, respectively, $U\mathcal{N}$, we can directly assume that $U = 1$, that is, $\|A_n - R_n\| < \varepsilon$. If ε is small enough, then $\sigma(R_n)$ is the disjoint union of n compact subsets $\sigma_1, \sigma_2, \dots, \sigma_n$, with σ_k included in the interior of the circle γ_k of radius $1/4$ centered at k ($k = 1, 2, \dots, n$).

Let \mathcal{J}_k be the range of the Riesz idempotent

$$\frac{1}{2\pi i} \int_{\gamma_k} (\lambda - R_n)^{-1} d\lambda,$$

and let \mathcal{J}_k^* be the analogously defined subspace corresponding to R_n^* . If $P_{\mathcal{L}}$ denotes the orthogonal projection of \mathcal{H} onto the subspace \mathcal{L} , we have

$$\|P_{\mathcal{L}_k} - P_{\mathcal{J}_k}\| = O(\varepsilon) \text{ and } \|P_{\mathcal{J}_k^*} - P_{\mathcal{J}_k^*}\| = O(\varepsilon)$$

($k = 1, 2, \dots, n$).

Since $\mathcal{M} \in \text{Lat } R_n$, \mathcal{M} "splits" as $\mathcal{M} = \sum_{k=1}^n \mathcal{M}_k$, where $\mathcal{M}_k = \mathcal{M} \cap \mathcal{J}_k$ ($k = 1, 2, \dots, n$; see [2]). Let $\mathcal{Q}_k = [P_{\mathcal{J}_k} \mathcal{M}_k]^-$, and let $\mathcal{S}(\mathcal{L})$ denote the unit sphere of the subspace \mathcal{L} ; then

$$\begin{aligned} \delta(\mathcal{M}_k, \mathcal{Q}_k) &:= \sup_{x \in \mathcal{S}(\mathcal{M}_k)} \text{dist}[x, \mathcal{Q}_k] = \sup_{x \in \mathcal{S}(\mathcal{M}_k)} \text{dist}[x, \mathcal{J}_k] \\ &\leq \sup_{x \in \mathcal{S}(\mathcal{J}_k)} \text{dist}[x, \mathcal{J}_k] = \delta(\mathcal{J}_k, \mathcal{J}_k) \\ &\leq \|P_{\mathcal{J}_k} - P_{\mathcal{Q}_k}\| = O(\varepsilon). \end{aligned}$$

Thus, $\dim \mathcal{M}_k \leq \dim \mathcal{Q}_k$ provided ε is small [19]. On the other hand, it is obvious from the definition of \mathcal{Q}_k that the dimension of this subspace cannot exceed that of \mathcal{M}_k ; therefore

$$\dim \mathcal{M}_k = \dim \mathcal{Q}_k \quad (k = 1, 2, \dots, n).$$

Define $\mathcal{Q} = \sum_{k=1}^n \mathcal{Q}_k$. Clearly, $\dim \mathcal{Q} = \dim \mathcal{M}$.

Similarly, $\mathcal{N} = \sum_{k=1}^n \mathcal{N}_k$ ($\mathcal{N}_k = \mathcal{N} \cap \mathcal{J}_k^*$) and, if we define $\mathcal{Q}_k^* = [P_{\mathcal{J}_k^*} \mathcal{N}_k]^-$ ($k = 1, 2, \dots, n$) and $\mathcal{Q}^* = \sum_{k=1}^n \mathcal{Q}_k^*$, then $\dim \mathcal{Q}^* = \dim \mathcal{N}$.

Moreover, we actually have $\mathcal{Q}_k = P_{\mathcal{J}_k} \mathcal{M}_k$, $\mathcal{Q}_k^* = P_{\mathcal{J}_k^*} \mathcal{N}_k$, $\|P_{\mathcal{M}_k} - P_{\mathcal{Q}_k}\| = O(\varepsilon)$ and $\|P_{\mathcal{N}_k} - P_{\mathcal{Q}_k^*}\| = O(\varepsilon)$ ($k = 1, 2, \dots, n$; see [19]).

(i) Assume that $\mathcal{N} \supset \mathcal{M} \neq \{0\}$; then $\mathcal{Q}_h \neq \{0\}$ for some h , $1 \leq h \leq n$. Pick $x \in \mathcal{S}(\mathcal{Q}_h) (\subset \mathcal{S}(\mathcal{Q}_h))$ and $y \in \mathcal{M}_h$ such that $x = P_{\mathcal{J}_h} y$, and let $x' = \sum_{k=1}^n P_{\mathcal{J}_k^*} P_{\mathcal{J}_k} y (\in \mathcal{Q}^*)$.

Since $y = P_{\mathcal{J}_h} y = \sum_{k=1}^n P_{\mathcal{J}_k^*} y$, we have

$$\begin{aligned} \|x - x'\| &= \|P_{\mathcal{J}_h} y - \sum_{k=1}^n P_{\mathcal{J}_k^*} P_{\mathcal{J}_k} y\| \\ &\leq \|(P_{\mathcal{J}_h} - P_{\mathcal{J}_h})y\| + \left\| \left(\sum_{k=1}^n [P_{\mathcal{J}_k^*} - P_{\mathcal{J}_k}] \right) P_{\mathcal{J}_k} y \right\| = O(\varepsilon) \|y\| = O(\varepsilon). \end{aligned}$$

Observe that $x \in \mathcal{G}_h$ and x' belongs to the subspace spanned by some subset of $\{\mathcal{G}_1^*, \mathcal{G}_2^*, \dots, \mathcal{G}_n^*\}$. If ε is sufficiently small, it follows from Lemma 2.2 that x' does not belong to the direct sum of any proper subset of the \mathcal{G}_k^* 's, and therefore $P_{\mathcal{G}_h^*} x' \neq 0$ for all $k=1, 2, \dots, n$. Since $0 \neq P_{\mathcal{G}_h^*} x' \in \mathcal{Q}_k^*$, we conclude that

$$\dim \mathcal{N} = \dim \mathcal{Q}^* \geq n.$$

Since n can be chosen arbitrarily large, \mathcal{N} must be an infinite dimensional subspace.

(ii) follows by the same argument. ■

Now we are in a position to prove the main result.

Proof of Theorem 2.1. (i) \Rightarrow (ii). This follows immediately from Theorem 2.4. Observe that if $R \in \mathcal{F}(\{m_k\})$ then for each $k \geq 0$

$$\mathcal{M}_{2k+1} \in \text{Lat } R, \mathcal{M}_{2k+1} \subset \mathcal{M}_{2k} \oplus \mathcal{M}_{2k+1} \oplus \mathcal{M}_{2k+2} \in \text{Lat } R^*$$

and

$$\mathcal{M}_{2k} \in \text{Lat } R^*, \mathcal{M}_{2k} \subset \mathcal{M}_{2k-1} \oplus \mathcal{M}_{2k} \oplus \mathcal{M}_{2k+1} \in \text{Lat } R$$

($\mathcal{M}_0 = \{0\}$). By theorem 2.4,

$$m_{2k} + m_{2k+1} + m_{2k+2} = \infty \text{ and } m_{2k-1} + m_{2k} + m_{2k+1} = \infty.$$

Thus,

$$m_k + m_{k+1} + m_{k+2} = \infty \text{ for all } k=0, 1, 2, \dots$$

(ii) \Rightarrow (iii). Let $T \in \mathcal{L}(\mathcal{H})$ and let $\varepsilon > 0$ be given. By Voiculescu's theorem [22] there exists $K_0 \in \mathcal{K}(\mathcal{H})$, with $\|K_0\| < \varepsilon/2$, such that $T - K_0 \simeq T \oplus A^{(\infty)}$ for a suitable A in $\mathcal{L}(\mathcal{H})$.

Assume $\mathcal{M}_2, \mathcal{M}_5, \mathcal{M}_8, \mathcal{M}_{11}, \dots$ are infinite dimensional; then we can write $\mathcal{M}_{3k-1} = \mathcal{R}_k \oplus \mathcal{S}_k$, where \mathcal{R}_k and \mathcal{S}_k are infinite dimensional ($k=1, 2, \dots$). We can find compact perturbations F_0 and F_1 such that $\max\{\|F_0\|, \|F_1\|\} < \varepsilon/2$, and $T - F_0$ is unitarily equivalent to an operator of the form

$$\begin{pmatrix} A_1 & B_1 \\ 0 & C_1 \end{pmatrix}$$

(with respect to the decomposition $\mathcal{M}_1 \oplus \mathcal{R}_1$, where A_1 is a normal diagonal operator), and $A - F_1$ is unitarily equivalent to an operator of the form

$$\begin{pmatrix} C_1'' & 0 \\ D_1' & A_2 \end{pmatrix}$$

(with respect to the decomposition $\mathcal{S}_1 \oplus \mathcal{M}_3$), where C_1'' is a normal diagonal operator (see [12, Chapter 3] for details). Thus $T \oplus A - F_0 \oplus F_1$ is unitarily equivalent to

$$\begin{pmatrix} A_1 & B_1 & 0 \\ 0 & C_1 & 0 \\ 0 & D_1 & A_2 \end{pmatrix}$$

(with respect to the decomposition $\mathcal{M}_1 \oplus \mathcal{M}_2 \oplus \mathcal{M}_3$), where $B_1 = (B_1' \ 0)$, $C_1 = C_1' \oplus C_1''$ and $D_1 = (0 \ D_1')$. Define $B_2 = 0$.

Similarly, we can find compact perturbations F_2 and F_3 such that $\max[\|F_2\|, \|F_3\|] < \varepsilon/4$, $A - F_2$ is unitarily equivalent to an operator of the form

$$\begin{pmatrix} C_2 & 0 \\ D'_2 & A'_3 \end{pmatrix}$$

(with respect to the decomposition $\mathcal{M}_4 \oplus \mathcal{R}_2$, where C_2 is a normal diagonal operator), and $A - F_3$ is unitarily equivalent to an operator of the form

$$\begin{pmatrix} A''_3 & B''_3 \\ 0 & C_3 \end{pmatrix}$$

(with respect to the decomposition $\mathcal{S}_2 \oplus \mathcal{M}_6$, where C_3 is a normal diagonal operator). Thus, $A \oplus A - F_2 \oplus F_3$ is unitarily equivalent to

$$\begin{pmatrix} C_2 & 0 & 0 \\ D_2 & A_3 & B_3 \\ 0 & 0 & C_3 \end{pmatrix}$$

(with respect to the decomposition $\mathcal{M}_4 \oplus \mathcal{M}_5 \oplus \mathcal{M}_6$), where

$$D_2 = \begin{pmatrix} D'_2 \\ 0 \end{pmatrix}, \quad A_3 = A'_3 \oplus A''_3 \quad \text{and} \quad B_3 = \begin{pmatrix} 0 \\ B''_3 \end{pmatrix}.$$

Define $D_3 = 0$.

By an obvious inductive argument, we can find compact perturbations F_4, F_5, \dots , so that

$$F = \Sigma \oplus_{k=0}^{\infty} F_k \in \mathcal{K}(\mathcal{H}), \quad \|F\| < \varepsilon/2,$$

and $T - (K_0 + F)$ is unitarily equivalent to a staircase operator in $\mathcal{F}(\{m_k\})$.

Since $K_0 + F$ is compact and $\|K_0 + F\| < \varepsilon$, this proves the result for the particular case when \mathcal{M}_{3k-1} is infinite dimensional for all $k \geq 1$. The general case follows by exactly the same argument, just by interpolating $\{0\}$ -subspaces in the direct sum decomposition $\mathcal{H} = \Sigma \oplus_{k=1}^{\infty} \mathcal{M}_k$. The details are left to the reader.

Since (iii) \Rightarrow (i) is a trivial implication, the proof of Theorem 2.1 is now complete. ■

Corollary 2.5. *If*

$$m_k + m_{k+1} + m_{k+2} = \infty$$

for all k sufficiently large, then

$$(\mathcal{F}(\{m_k\}))^\wedge = \mathcal{L}(\mathcal{H}).$$

3. The analysis of $\mathcal{F}(\{m_k\})^\wedge$

Proposition 3.1. *If $(\text{BD})_{\text{nor}} \subset \mathcal{F}(\{m_k\})^\wedge$, then*

$$m_k + m_{k+1} + m_{k+2} \rightarrow \infty \quad (k \rightarrow \infty).$$

Proof. Let A_n be defined as usual and let K_n be a compact operator such that $R_n = A_n - K_n$ (or some unitarily equivalent operator) belongs to $\mathcal{F}(\{m_k\})$.

Let P_h denote the orthogonal projection of \mathcal{H} onto $\Sigma \oplus_{k=1}^h \mathcal{M}_k$. Given $\varepsilon > 0$, we can find $h(\varepsilon)$ such that the norm of the compact operator

$$K_{n,\varepsilon} = K_n - P_{h(\varepsilon)} K_n P_{h(\varepsilon)}$$

does not exceed ε . Clearly, we can assume that $h(\varepsilon)$ is odd.

It is easily seen that

$$A_n - K_{n,\varepsilon} = \begin{bmatrix} A_0 & B_{h(\varepsilon)} & & & \\ & C_{h(\varepsilon)} & & & \\ & D_{h(\varepsilon)} & A_{h(\varepsilon)+1} & B_{h(\varepsilon)+1} & \\ & & & & \ddots \\ & & & & & \ddots \end{bmatrix}$$

with respect to the decomposition $\mathcal{H} = (\Sigma \oplus_{k=1}^{h(\varepsilon)} \mathcal{M}_k) \oplus \mathcal{M}_{h(\varepsilon)+1} \oplus \mathcal{M}_{h(\varepsilon)+2} \oplus \dots$.

By using the same arguments as in the proofs of Theorems 2.3 and 2.1 (i) \Rightarrow (ii), we deduce that

$$m_k + m_{k+1} + m_{k+2} \geq n$$

for all $k > h(\varepsilon)$. (The details are left to the reader.)

Therefore,

$$m_k + m_{k+1} + m_{k+2} \rightarrow \infty \quad (k \rightarrow \infty). \quad \blacksquare$$

Proposition 3.2. *If $m_k \rightarrow \infty$ ($k \rightarrow \infty$), then $(BD)_{\text{nor}} \subset \mathcal{F}\{(m_k)\}^\wedge$.*

Proof. Assume that all the m_k 's are finite and let $M = \Sigma \oplus_{j=1}^\infty M_j$, where M_j acts on a space of dimension d_j , and $d_j \leq d$ for some d .

Define $j_0 \geq 1$ and $k_0 = 2j_0 + 1 \geq 1$ so that $m_k > d$ for all $k > k_0$ and

$$\sum_{k=1}^{k_0} m_k \leq \sum_{j=1}^{j_0} d_j < \sum_{k=1}^{k_0+1} m_k.$$

Now we define j_1, j_2, \dots , so that

$$\sum_{k=1}^{k_0+p} m_k \leq \sum_{j=1}^{j_p} d_j < \sum_{k=1}^{k_0+p+1} m_k.$$

After a finite rank perturbation, we can directly assume that $M_j = 0$ for $1 \leq j \leq j_0$.

If $p = 2m - 1$ ($p = 2m$) and M_{j_p} is written as a lower (upper, resp.) triangular matrix with respect to a suitable orthogonal basis of the corresponding d_{j_p} -dimensional space, and the space is decomposed as $\mathcal{R}_p \oplus \mathcal{S}_p$, where \mathcal{R}_p is the span of the first

$$\sum_{j=1}^{j_p} d_j - \sum_{k=1}^{k_0+p} m_k$$

vectors, then

$$M_{j_p} = \begin{pmatrix} C'_{h_0+m-1} & 0 \\ D'_{h_0+m-1} & A'_{h_0+m} \end{pmatrix}$$

$$\left(M_{j_p} = \begin{pmatrix} A''_{h_0+m} & B''_{h_0+m} \\ 0 & C''_{h_0+m} \end{pmatrix}, \text{ resp.} \right).$$

Define $A_1, B_1, C_1, D_1, A_2, \dots, A_{h_0}, B_{h_0}$ equal to 0,

$$C_{h_0} = 0 \oplus M_{j_0+1} \oplus M_{j_0+2} \oplus \dots \oplus M_{j_1-1} \oplus C'_{h_0}$$

(where 0 acts on a space of dimension $\sum_{j=1}^{j_0} d_j - \sum_{k=1}^{k_0} m_k$),

$$C_{h_0+m} = C''_{h_0+m} \oplus M_{j_p+1} \oplus M_{j_p+2} \oplus \dots \oplus M_{j_{p+1}-1} \oplus C'_{h_0+m} \quad (p=2m),$$

$$A_{h_0+m} = A'_{h_0+m} \oplus M_{j_p+1} \oplus M_{j_p+2} \oplus \dots \oplus M_{j_{p+1}-1} \oplus A''_{h_0+m} \quad (p=2m-1),$$

$B_{h_0+m} = (B''_{h_0+m} \ 0 \ 0 \dots 0)$ and D_{h_0+m} is the column of operators $(D'_{h_0+m-1} \ 0 \ 0 \dots 0)$ ($m=1, 2, \dots$).

Now it is a straightforward exercise to check that M (or M minus some finite rank perturbation) has a staircase representation associated with the sequence $A_1, B_1, C_1, D_1, \dots, A_r, B_r, C_r, D_r, \dots$, and this operator belongs to $\mathcal{U}(\mathcal{F}(\{m_k\}))$. Hence, $M \in \mathcal{F}(\{m_k\})^\wedge$.

If $m_k = \infty$ for some k , the result follows by similar arguments. The details are left to the reader. ■

Let $\mathcal{F}(\{m_k\})$ be a given tridiagonal algebra. For each infinite m_k , drop m_{k-1}, m_k and m_{k+1} from the sequence, and let $\{n_r\}$ be the (finite or infinite) sequence formed by the remaining terms. If $\{n_r\}$ is finite, then we still have $\mathcal{F}(\{m_k\})^\wedge \supset (\text{BD})_{\text{nor}}$. (Indeed, $\mathcal{F}(\{m_k\})^\wedge = \mathcal{L}(\mathcal{H})$.)

The authors conjecture that if m_k is finite for all k , then $(\text{BD})_{\text{nor}} \subset \mathcal{F}(\{m_k\})^\wedge$ if and only if $m_k \rightarrow \infty$ ($k \rightarrow \infty$).

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