

Provided for non-commercial research and educational use.
Not for reproduction, distribution or commercial use.

Mathematica Balkanica

Mathematical Society of South-Eastern Europe
A quarterly published by
the Bulgarian Academy of Sciences – National Committee for Mathematics

The attached copy is furnished for non-commercial research and education use only. Authors are permitted to post this version of the article to their personal websites or institutional repositories and to share with other researchers in the form of electronic reprints.

Other uses, including reproduction and distribution, or selling or licensing copies, or posting to third party websites are prohibited.

For further information on Mathematica Balkanica visit the website of the journal
<http://www.mathbalkanica.info>

or contact:

Mathematica Balkanica - Editorial Office;
Acad. G. Bonchev str., Bl. 25A, 1113 Sofia, Bulgaria
Phone: +359-2-979-6311, Fax: +359-2-870-7273,
E-mail: balmat@bas.bg

Applications of the Algebraic Derivatives to Solving Some Differential Equations of Fractional Order

V. M. Almeida, J. Rodríguez

Presented by V. Kiryakova

The differential equation of fractional order, $tD^{\delta+1}x(t) + (1-t)D^{\delta}x(t) - aD^{\delta-1}x(t) = 0$ ($a \in C$, $\delta > 1$, $\delta \in R$), where D^{δ} is the Riemann-Liouville differential operator, and for $\delta = 1$ is the Laguerre differential equation, is solved using the Mikusinski's operational calculus. The obtained solutions are represented by

$$x_{a,\delta}(t) = \sum_{k=0}^{\infty} \binom{-a}{k} (-1)^k \frac{t^{k+\delta-1}}{\Gamma(k+\delta)} = \frac{t^{\delta-1}}{\Gamma(\delta)} {}_1F_1(a, \delta, t)$$

and satisfy

$$D^{\delta}[x_{a,\delta} * x_{b,\delta}](t) = x_{a+b,\delta}(t),$$

where $*$ is the convolution

$$(f * g)(t) = \int_0^t f(t-\xi)g(\xi)d\xi$$

and ${}_1F_1$ is the Kummer function, called also a confluent hypergeometric function.

Similar results are obtained also for the functions $x_{a,\delta,\alpha} = e^{\alpha t}x_{a,\delta}(t)$.

AMS Subj. Classification: 44A40, 26A33

Key Words: Mikusinski's operational calculus, algebraic derivatives, differential equations of fractional order, Laguerre differential equation, Riemann-Liouville operator

1. Introduction

W. Kierat and K. Skornik [3], using the Mikusinski's operational calculus, have solved the differential equation

$$t \frac{d^2x}{dt^2} + (c-t) \frac{dx}{dt} - ax = 0 \quad (c, a \in C)$$

which for $c = 1$ reduces to the Laguerre differential equation and has as one of its solutions,

$$x_a(t) = \sum_{k=0}^{\infty} \binom{-a}{k} (-1)^k \frac{t^k}{\Gamma(k+1)}.$$

We introduce the functions $x_{a,\alpha}(t) = e^{\alpha t}x_a(t)$, closely related to $x_a(t)$ and prove the following properties:

$$\frac{d}{dt}[x_a * x_b](t) = x_{a+b}(t)$$

$$\left(\frac{d}{dt} - \alpha\right)[x_{a,\alpha} * x_{b,\alpha}](t) = x_{a+b,\alpha}(t).$$

Obviously, the functions $x_a(t)$ and $x_{a,\alpha}(t)$ are generalizations of the Laguerre polynomials and functions respectively.

In this paper we generalize the preceding results, using a similar technique, to a differential equation containing the Riemann-Liouville fractional operators.

2. A generalization of the Laguerre differential equation and its solutions

Following J. Mikusinski [4], we consider the ring of functions

$$C^n = \{f(t) : f(t) \in C^n([0, \infty)), [D^k f(t)]_{t=0} = 0, k = 0, 1, \dots, n-2\}$$

and the differential equation of fractional order

$$(2.1) \quad tD^{\delta+1}x(t) + (1-t)D^\delta x(t) - aD^{\delta-1}x(t) = 0 \quad (a \in C, \delta > 1, \delta \in R),$$

where

$$(2.2) \quad D^\delta = D^n I^{n-\delta} \quad (n-1 < \delta \leq n)$$

and

$$(2.3) \quad \left. \begin{aligned} I^\nu f(t) &= \frac{1}{\Gamma(\nu)} \int_0^t (t-\xi)^{\nu-1} f(\xi) d\xi \quad (\nu > 0) \\ I^0 f(t) &= f(t) \end{aligned} \right\},$$

I^ν being the Riemann-Liouville fractional integration operator of order ν .

Using (2.2) and (2.3), and substituting $y(t) = I^{n-\delta}x(t)$, the equation (2.1) is transformed into

$$(2.4) \quad tD^{n+1}y(t) + (1-t)D^n y(t) - aD^{n-1}y(t) = 0.$$

In order to solve (2.4) we take in account the following propositions.

Proposition 1. *Let $y(t)$ be the function $y(t) = I^{n-\delta}x(t)$, then*

$$[D^k y(t)]_{t=0} = \left[\frac{d^k y(t)}{dt^k}\right]_{t=0} = 0, \quad k = 0, 1, \dots, n-1.$$

Proof. The function $D^k y(t)$ can be expressed ([5], p.62, Th. 3) by

$$D^k y(t) = D^k I^{n-\delta} x(t) = I^{n-\delta} D^k x(t) + \sum_{r=0}^{k-1} \frac{t^{n-\delta-k+r}}{\Gamma(n-\delta-k+r+1)} [D^r x(t)]_{t=0},$$

and since $x(t) \in C^n$ and $k = 0, 1, \dots, n-1$, it can be easily shown that

$$[D^k y(t)]_{t=0} = [I^{n-\delta} D^k x(t)]_{t=0} = 0.$$

From Proposition 1 and using the notion of algebraic derivative given in [4], $\mathcal{D}f(t) = -tf(t)$, we obtain

Proposition 2. One of the solutions of the equation (2.4) can be written as

$$y_{a,n}(t) = \sum_{k=0}^{\infty} \binom{-a}{k} (-1)^k \frac{t^{k+n-1}}{\Gamma(k+n)}$$

Proof. The equation (2.4) is transformed into

$$\mathcal{D}[s^{n+1}y(t) - y^{(n)}(0)] + s^n y(t) + \mathcal{D}[s^n y(t)] - as^{n-1}y(t) = 0,$$

by using the operational calculus' rule [4],

$$D^n f(t) = s^n f(t) - s^{n-1}[f'(t)]_{t=0} - s^{n-2}[f^{(2)}(t)]_{t=0} - \dots - [f^{(n-1)}(t)]_{t=0}$$

and Proposition 1. Then it can be rewritten as

$$(s^n - s^{n-1})\mathcal{D}y(t) + s^{n-1}(1 - a - ns)y(t) = 0,$$

so one can get the solution

$$y_{a,n}(t) = s^{a-n}(s-1)^{-a} = l^n(1-l)^{-a} = \sum_{k=0}^{\infty} \binom{-a}{k} (-1)^k \frac{t^{k+n-1}}{\Gamma(k+n)},$$

where $l = s^{-1}$, $l^\delta = t^{\delta-1}/\Gamma(\delta)$.

Remark. It is very easy to get $\frac{d^n}{dt^n}[y_{a,n} * y_{b,n}](t) = y_{a+b,n}(t)$.

Next we are going to prove similar properties for the functions $x_{a,\delta}(t) = D^{n-\delta} y_{a,n}(t)$.

Proposition 3. The solution $x_{a,\delta}(t)$ of equation (2.1) satisfies the following relations:

$$\text{a) } x_{a,\delta}(t) = \sum_{k=0}^{\infty} \binom{-a}{k} (-1)^k \frac{t^{k+\delta-1}}{\Gamma(k+\delta)} = t^\delta (1-t)^{-a},$$

$$\text{b) } D^\delta [x_{a,\delta} * x_{b,\delta}](t) = x_{a+b,\delta}(t),$$

$$\text{c) } x_{a,\delta}(t) = \frac{t^{\delta-1}}{\Gamma(\delta)} {}_1F_1(a, \delta, t).$$

Proof.

It is easy to prove a), using the next three equalities:

$$\bullet D^\alpha t^k = \frac{\Gamma(k+1)}{\Gamma(k-\alpha+1)} t^{k-\alpha} \quad ([1]),$$

$$\bullet t^\delta = \frac{t^{\delta-1}}{\Gamma(\delta)} \quad ([4]),$$

$$\bullet x_{a,\delta}(t) = D^{n-\delta} y_{a,n}(t).$$

b) is a straightforward corollary.

c) We can represent the function $x_{a,\delta}(t)$ by

$$x_{a,\delta}(t) = \frac{t^{\delta-1}}{\Gamma(\delta)} \sum_{k=0}^{\infty} \frac{(a)_k}{(\delta)_k} \frac{t^k}{\Gamma(k+1)} = \frac{t^{\delta-1}}{\Gamma(\delta)} {}_1F_1(a, \delta, t),$$

where from [6],

$$\bullet \binom{-a}{k} = \frac{(-1)^k (a)_k}{\Gamma(k+1)}$$

$$\bullet \Gamma(k+\delta) = (\delta)_k \Gamma(\delta)$$

$$\bullet (a)_0 = 1 ; (a)_n = a(a+1)(a+2)\dots(a+n-1) \quad n = 1, 2, 3, \dots$$

3. The functions $x_{a,\delta,\alpha}(t)$

Following a similar process to that in Section 2, we can obtain similar results for the functions $x_{a,\delta,\alpha}(t) = e^{\alpha t} x_{a,\delta}(t)$.

Proposition 4. *The function $y_{a,n,\alpha}(t) = e^{\alpha t} y_{a,n}(t)$, where $y_{a,n}(t)$ is a solution of equation (2.4), satisfies:*

$$\left(\frac{d}{dt} - \alpha\right)^n [y_{a,n,\alpha} * y_{b,n,\alpha}](t) = y_{a+b,n,\alpha}(t).$$

Proof. We use that $e^{\alpha t} \frac{t^{n-1}}{\Gamma(n)} = \frac{1}{(s-\alpha)^n}$ (see [4]) and

$$\begin{aligned} \left(\frac{d}{dt} - \alpha\right)^n [t^n(1-\alpha t)^{-n}] &= \sum_{k=0}^n \binom{n}{k} (-1)^k D^k \alpha^{n-k} t^n (1-\alpha t)^{-n} \\ &= (1-\alpha t)^{-n} \sum_{k=0}^n \binom{n}{k} (-1)^k (\alpha t)^{n-k} = 1. \end{aligned}$$

Now we prove the same properties for the functions $x_{a,\delta,\alpha}(t) = e^{\alpha t} x_{a,\delta}(t)$, where $x_{a,\delta}(t)$ is a solution of equation (2.1). First we introduce the following definition.

Definition 1. Let $D = \frac{d}{dt}$ be the differentiation operator and $\delta > 1$ be a real number. Then we define the operator

$$(3.1) \quad (D - \alpha)^\delta f(t) = \begin{cases} D^\delta f(t) & \text{if } \alpha = 0, \\ \sum_{k=0}^{\infty} \binom{\delta}{k} (-1)^k \alpha^{\delta-k} D^k f(t) & \text{if } \alpha \neq 0. \end{cases}$$

Obviously this definition can be only applied only to the set of functions $f(t)$ for which the series $\sum_{k=0}^{\infty} \binom{\delta}{k} (-1)^k \alpha^{\delta-k} D^k f(t)$ is convergent. Let us observe that this set is not empty since, at least the polynomials belong to it.

In order to know if the operator $(D - \alpha)^\delta$ can be applied to the function $x_{a,\delta,\alpha}(t)$, it is necessary to work in the Mikusinski's quotient field [4], and so we can state the following proposition.

Proposition 5.

$$x_{a,\delta,\alpha}(t) = (s - \alpha)^{-\delta} \left(1 - \frac{1}{s - \alpha}\right)^{-a} = t^\delta (1 - \alpha t)^{-\delta} \left[\frac{1 - (\alpha + 1)t}{1 - \alpha t}\right]^{-a}$$

Proof. It is a simple exercise taking into account that

$$x_{a,\delta}(t) = \sum_{k=0}^{\infty} \binom{-a}{k} (-1)^k \frac{t^{k+\delta-1}}{\Gamma(k+\delta)}$$

and

$$\frac{1}{(s - \alpha)^\delta} = t^\delta \sum_{k=0}^{\infty} \binom{-\delta}{k} (-1)^k (\alpha t)^k = \frac{t^{\delta-1}}{\Gamma(\delta)} \sum_{k=0}^{\infty} \frac{(\alpha t)^k}{\Gamma(k+1)} = \frac{t^{\delta-1}}{\Gamma(\delta)} e^{\alpha t}.$$

Definition 1 was given for any function, but it can be generalized for the elements of the Mikusinski's quotient field.

Now we can state

Proposition 6. *Let $m_{a,\delta,\alpha} = (s - \alpha)^{-\delta}(1 - \frac{1}{s-\alpha})^{-a}$ be a Mikusinski operator, then*

$$(D - \alpha)^\delta [m_{a,\delta,\alpha} \cdot m_{a,\delta,\alpha}] = m_{a+b,\delta,\alpha}.$$

Proof. It can be proved from

$$\begin{aligned} (D - \alpha)^\delta [l^\delta(1 - \alpha l)^{-\delta}] &= \sum_{k=0}^\infty \binom{\delta}{k} (-1)^k \alpha^{\delta-k} l^{\delta-k} (1 - \alpha l)^{-\delta} \\ &= (1 - \alpha l)^{-\delta} \sum_{k=0}^\infty \binom{\delta}{k} (-1)^k (\alpha l)^{\delta-k} = 1. \end{aligned}$$

■

Proposition 7. *For the functions $x_{a,\delta,\alpha}(t)$ and $x_{b,\delta,\alpha}(t)$,*

$$(3.2) \quad (D - \alpha)^\delta [x_{a,\delta,\alpha} * x_{b,\delta,\alpha}](t) = x_{a+b,\delta,\alpha}(t).$$

Proof. The functions $x_{a,\delta,\alpha}(t)$ and $x_{b,\delta,\alpha}(t)$ are continuous and so, they belong to \mathcal{C} , the generating ring of the Mikusinski's quotient field. Thus they can be identified with the operators $m_{a,\delta,\alpha}$ and $m_{b,\delta,\alpha}$, respectively. Therefore, making use of Proposition 6, we can obtain (3.2).

4. More general differential equations

In [7], it is shown that the differential equation

$$(4.1) \quad 4.1a_2ty^{(2)}(t) + (a_1t + b_1)y'(t) + (a_0t + b_0)y(t) = 0$$

is convertible into

$$\frac{\mathcal{D}y}{y} = \frac{q(s)}{p(s)} = \frac{(-2a_2 + b_1)s - a_1 + b_0}{a_2s^2 + a_1s + a_0}$$

and if the algebraic equation $p(z) = a_2z^2 + a_1z + a_0$, has two distinct roots z_1 and z_2 , then

$y = C(s - z_1)^{\gamma_1}(s - z_2)^{\gamma_2}$ satisfies equation (4.1), where C is a non-zero constant and γ_1, γ_2 are complex numbers satisfying

$$\frac{q(z)}{p(z)} = \frac{\gamma_1}{z - z_1} + \frac{\gamma_2}{z - z_2}.$$

Making use of Yosida's paper [7], W. Kierat [2] has determined particular solutions of the differential equations with linear coefficients

$$(4.2) \quad a_n t x^{(n)}(t) + (a_{n-1}t + b_{n-1})x^{(n-1)}(t) + \dots + (a_0t + b_0)x(t) = 0,$$

transforming them into

$$\frac{Dx}{x} = \frac{Q(s)}{P(s)}.$$

He concludes that the element of Mikusinski's quotient field

$$(4.3) \quad v = C \prod_{i=1}^r (s - \alpha_i)^{\gamma_{i1}} \prod_{j=2}^{k_i} \exp\left[\frac{\gamma_{ij}}{-j+1}(s - \alpha_i)^{-j+1}\right]$$

satisfies equation (4.2), where $C \in C$, the complex numbers α_i are the roots of the polynomial $P(z) = a_n z^n + a_{n-1} z^{n-1} + \dots + a_0$ ($k_i \in N$, $k_1 + \dots + k_r = \deg P$) and $\gamma_{ij} \in C$ satisfying

$$\frac{Q(s)}{P(s)} = \sum_{i=1}^r \sum_{j=1}^{k_i} \frac{\gamma_{ij}}{(s - \alpha_i)^j}.$$

The purpose of this section is to show that the method from the previous sections may be used to determine particular solutions of the differential equations of fractional order $\delta > 1$ (n is integer so that $n - 1 < \delta \leq n$):

$$(4.4) \quad a_n t D^\delta x(t) + (a_{n-1}t + b_{n-1})D^{\delta-1}x(t) + \dots + (a_0t + b_0)D^{\delta-n}x(t) = 0.$$

Let $y(t) = I^{n-\delta}x(t)$. The equation (4.4) can be written as

$$a_n t D^n y(t) + (a_{n-1}t + b_{n-1})D^{n-1}y(t) + \dots + (a_0t + b_0)y(t) = 0$$

and then, making use of (4.3) and $x(t) = D^{n-\delta}y(t)$, we can conclude

Proposition 8. *The element*

$$w = C s^{n-\delta} \prod_{i=1}^r (s - \alpha_i)^{\gamma_{i1}} \prod_{j=2}^{k_i} \exp\left[\frac{\gamma_{ij}}{-j+1}(s - \alpha_i)^{-j+1}\right]$$

satisfies equation (4.4).

References

- [1] J.A. Alamo, J. Rodríguez. Cálculo operacional de Mikusinski para el operador de Riemann-Liouville y su generalizado. *Revista de la Academia Canaria de las Ciencias* 1, 1993, 31-40.

- [2] W. Kierat. A note on applications of the algebraic derivative to solving of some differential equations. *Acta Univ. Palack. Olomuc. Fac. Rerum Natur. Math.* **110**, 1993, 63-68.
- [3] W. Kierat, K. Skornik. A remark on solutions of the Laguerre differential equation. *Integral Transforms and Special Functions* **1(4)**, 1993, 315-316.
- [4] J. Mikusinski. *Operational Calculus*. Pergamon Press, 1959.
- [5] K. S. Miller, B. Ross. *An Introduction to the Fractional Calculus and Fractional Differential Equations*. John Wiley, 1993.
- [6] H. M. Srivastava, H.L. Manocha. *A Treatise on Generating Functions*. Ellis Horwood, 1984.
- [7] K. Yosida. The algebraic derivative and Laplace's differential equation. *Proc. Japan Acad., Ser. A* **59**, 1983, 1-4.

*Departamento de Análisis Matemático
Universidad de La Laguna, La Laguna (Tenerife)
Canary Islands, SPAIN*

Received 11.04.1997

e-mails: valmeida@ull.es, jorodriguez@ull.es