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# Commutants of the Euler operator and corresponding mean-periodic functions 

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#### Abstract

The Euler operator $\delta=t(\mathrm{~d} / \mathrm{d} t)$ is considered in the space $C=C\left(\mathbb{R}_{+}\right), \mathbb{R}_{+}=(0, \infty)$, and the operators $M: C \rightarrow C$ such that $M \delta=\delta M$ in $C^{1}\left(\mathbb{R}_{+}\right)$are characterized. Next, for a non-zero linear functional $\Phi: C\left(\mathbb{R}_{+}\right) \rightarrow \mathbb{C}$ the continuous linear operators $M$ with the invariant hyperplane $\Phi\{f\}=0$ and commuting with $\delta$ in it are also characterized. Further, mean-periodic functions for $\delta$ with respect to the functional $\Phi$ are introduced and it is proved that they form an ideal in a corresponding convolutional algebra $\left(C\left(\mathbb{R}_{+}\right), *\right)$. As an application, unique mean-periodic solutions of Euler differential equations are characterized.


Keywords: Commutant; Riesz-Markov theorem; Invariant hyperplane; Convolutional algebra; Multiplier; Cyclic element; Mean-periodic function

Mathematics Subject Classification: 47B38; 47B37

## 1. Introduction

Compared with the case of differentiation operator $D=\mathrm{d} / \mathrm{d} t$ in a space $C$ of continuous functions, the problem of characterizing the continuous linear operators $M: C \rightarrow C$ commuting with the Euler operator $\delta=t(\mathrm{~d} / \mathrm{d} t)$, i.e. such that

$$
M \delta=\delta M
$$

in $C^{1}$, had not been so intensively treated as the corresponding problem for $D$. Here we can mention only the classical book of Levin [1, Ch. 8 and 9, Theorem 20, pp. 379-380], where $\delta$ is considered in spaces of entire functions.

In the operational calculus developed in Elizarraraz and Verde-Star [2] in fact some operators commuting with the Euler operator are found.

Due to the analogy of the considerations for $\delta$ and $D$, a short survey of the results for differentiation operator will be made.

[^0]Bourbaki [3, Chapter 6] seems to be the first to characterize the linear continuous operators $M: C(\mathbb{R}) \rightarrow C(\mathbb{R})$ with $M D=D M$ in $C^{1}(\mathbb{R})$. These are the operators of the form

$$
M f(t)=\Phi_{\tau}\{f(t+\tau)\}
$$

where $\Phi$ is a linear functional on $C(\mathbb{R})$. According to Riesz-Markov theorem ([4, Theorem 4.10.1]) $\Phi$ has the form

$$
\Phi(f)=\int_{\alpha}^{\beta} f(\tau) \mathrm{d} \sigma(\tau)
$$

where $-\infty<\alpha<\beta<\infty$ and $\sigma(\tau)$ is a Radon measure.
Delsarte [5] introduced the space of the mean-periodic functions determined by the functional $\Phi$ as the kernel space of $M$. For details see also Schwartz [6].

One of the authors (Dimovski [7]) had found the linear continuous operators $M: C(\mathbb{R}) \rightarrow C(\mathbb{R})$, such that the subspace $C_{\Phi}=\{f \in C(\mathbb{R}), \Phi(f)=0\}$ is an invariant subspace of $M$ and $M$ commutes with $D$ in $C_{\Phi}^{1}$. It happened that these are the operators of the form

$$
M f=\mu f(t)+m * f
$$

where $\mu=$ const, $m \in C(\mathbb{R})$, and $*$ is the operation

$$
(f * g)(t)=\Phi_{\tau}\left\{\int_{\tau}^{t} f(t+\tau-\sigma) g(\sigma) \mathrm{d} \sigma\right\}
$$

Quite natural is the question about the relationship between the two types of commutants. A partial answer is given by the following theorem (Dimovski and Skórnik $[8,9]$ ):

The space of the mean-periodic functions determined by the functional $\Phi$ forms an ideal in the convolutional algebra $(C(\mathbb{R}), *)$.

Similar results for the Pommiez operator $\Delta f(z)=[f(z)-f(0)] / z$ are presented by Dimovski and Hristov [10].

An interesting historical survey about commutants of differentiation operator and related operators like the Euler one can be found in the book of Korobeinik [11].

## 2. General commutant

Theorem 2.1 A linear continuous operator $M: C\left(\mathbb{R}_{+}\right) \rightarrow C\left(\mathbb{R}_{+}\right)$with $M: C^{1}\left(\mathbb{R}_{+}\right) \rightarrow$ $C^{1}\left(\mathbb{R}_{+}\right)$commutes with $\delta=t(\mathrm{~d} / \mathrm{d} t)$ in $C^{1}\left(\mathbb{R}_{+}\right)$iff it admits a representation of the form

$$
\begin{equation*}
(M f)(t)=\Phi_{\tau}\{f(t \tau)\} \tag{1}
\end{equation*}
$$

with a continuous linear functional $\Phi: C\left(\mathbb{R}_{+}\right) \rightarrow \mathbb{C}$.
Proof Consider the one-parameter family $T^{\tau}, 0<\tau<\infty$, of the shift operators defined by

$$
\begin{equation*}
\left(T^{\tau} f\right)(t):=f(t \tau), \quad 0<\tau<\infty \tag{2}
\end{equation*}
$$

Each of them commutes with $\delta=t(\mathrm{~d} / \mathrm{d} t)$ in $C^{1}\left(\mathbb{R}_{+}\right)$. Indeed,

$$
\left(\delta T^{\tau} f\right)(t)=t f^{\prime}(t \tau) \tau=t \tau f^{\prime}(t \tau)=(\delta f)(t \tau)=\left(T^{\tau} \delta f\right)(t)
$$

Lemma 2.2 A linear operator $M: C\left(\mathbb{R}_{+}\right) \rightarrow C\left(\mathbb{R}_{+}\right)$with $M: C^{1}\left(\mathbb{R}_{+}\right) \rightarrow C^{1}\left(\mathbb{R}_{+}\right)$commutes with $\delta=t(\mathrm{~d} / \mathrm{d} t)$ in $C^{1}\left(\mathbb{R}_{+}\right)$iff $M$ commutes with $T^{\tau}$ for all $\tau, 0<\tau<\infty$.

Proof First a 'multiplicative' version of the Taylor formula is needed. Let $f$ be a polynomial and $g$ be the function defined by

$$
g(x)=f\left(\mathrm{e}^{x}\right)
$$

Then

$$
f(t \tau)=g(\ln (t \tau))=g(\ln t+\ln \tau)
$$

Denote $x=\ln t$ and $\xi=\ln \tau$, i.e. $t=\mathrm{e}^{x}$ and $\tau=\mathrm{e}^{\xi}$, and apply the usual Taylor formula for $g$ :

$$
\begin{equation*}
f(t \tau)=g(x+\xi)=\sum_{n=0}^{\infty} \frac{g^{(n)}(x)}{n!} \xi^{n} \tag{3}
\end{equation*}
$$

Then

$$
\begin{equation*}
g^{\prime}(x)=\frac{\mathrm{d} g(x)}{\mathrm{d} x}=\frac{\mathrm{d} g(\ln t)}{\mathrm{d} t} \cdot \frac{\mathrm{~d} t}{\mathrm{~d} x}=\frac{\mathrm{d} f(t)}{\mathrm{d} t} \cdot \frac{\mathrm{de}^{x}}{\mathrm{~d} x}=f^{\prime}(t) \mathrm{e}^{x}=t f^{\prime}(t)=(\delta f)(t) \tag{4}
\end{equation*}
$$

Further,

$$
\begin{equation*}
g^{\prime \prime}(x)=\left(\delta^{2} f\right)(t), \ldots, g^{(n)}(x)=\left(\delta^{n} f\right)(t), \ldots \tag{5}
\end{equation*}
$$

Substituting (4) and (5) in (3) gives the desired 'multiplicative' Taylor formula:

$$
\begin{equation*}
\left(T^{\tau} f\right)(t)=f(t \tau)=\sum_{n=0}^{\infty}\left(\delta^{n} f\right)(t) \frac{(\ln \tau)^{n}}{n!} \tag{6}
\end{equation*}
$$

It is true for arbitrary polynomial $f(t)$.
Now suppose that $M$ commutes with the Euler operator $\delta$, i.e. $M \delta=\delta M$. Then, for every $\tau, 0<\tau<\infty$, (6) implies

$$
\begin{aligned}
\left(M T^{\tau} f\right)(t) & =M \sum_{n=0}^{\infty}\left(\delta^{n} f\right)(t) \frac{(\ln \tau)^{n}}{n!}=\sum_{n=0}^{\infty}\left(M\left(\delta^{n} f\right)\right)(t) \frac{(\ln \tau)^{n}}{n!} \\
& =\sum_{n=0}^{\infty}\left(\delta^{n}(M f)\right)(t) \frac{(\ln \tau)^{n}}{n!}=\left(T^{\tau} M f\right)(t)
\end{aligned}
$$

In order to prove the opposite implication, suppose $M T^{\tau}=T^{\tau} M$ for every $\tau, 0<\tau<\infty$, and for arbitrary polynomial $f(t)$, and reverse the order in the last chain of equalities as follows:

$$
\sum_{n=0}^{\infty}\left(M\left(\delta^{n} f\right)\right)(t) \frac{(\ln \tau)^{n}}{n!}=\left(M\left(T^{\tau} f\right)\right)(t)=\left(T^{\tau}(M f)\right)(t)=\sum_{n=0}^{\infty}\left(\delta^{n}(M f)\right)(t) \frac{(\ln \tau)^{n}}{n!}
$$

The sums have to coincide for every $\tau$ and hence the coefficients of $(\ln \tau)^{n}$ are equal for arbitrary $n$. For $n=1$, it follows that

$$
\begin{equation*}
(M(\delta f))(t)=(\delta(M f))(t) \tag{7}
\end{equation*}
$$

Assuming that (7) is true for polynomials, it follows that it is true for arbitrary $f \in C^{1}\left(\mathbb{R}_{+}\right)$ since $f$ could be approximated by polynomials. The proof of the lemma is completed.

Proof of Theorem 2.1 It is a matter of a direct check to show that the operators of the form (1) commute with $\delta$ and here only the proof of the necessity is needed.

If $M$ commutes with $\delta$, then by the lemma

$$
\begin{equation*}
M T^{\tau} f(t)=T^{\tau} M f(t), \quad 0<\tau<\infty \tag{8}
\end{equation*}
$$

Applying the symmetry property

$$
\begin{equation*}
\left(T^{\tau} f\right)(t)=f(t \tau)=f(\tau t)=\left(T^{t} f\right)(\tau) \tag{9}
\end{equation*}
$$

to the right hand side of (8) gives

$$
\begin{equation*}
\left(M\left(T^{\tau} f\right)\right)(t)=\left(T^{t}(M f)\right)(\tau) \tag{10}
\end{equation*}
$$

Define the linear functional $\Phi$ as

$$
\Phi\{f\}:=(M f)(1)
$$

Then, substituting 1 for $t$ in (10) and taking into account that $T^{1}$ is the identity operator, one has

$$
\left(M\left(T^{\tau} f\right)\right)(1)=\left(T^{1}(M f)\right)(\tau)=(M f)(\tau)
$$

The left hand side is the value of the functional $\Phi$ for the function $g(t)=\left(T^{\tau} f\right)(t)$, and hence

$$
(M f)(\tau)=\Phi_{\sigma}\left\{\left(T^{\tau} f\right)(\sigma)\right\}=\Phi_{\sigma}\left\{\left(T^{\sigma} f\right)(\tau)\right\}
$$

Using (2) and (9), this is in fact the desired representation (1) of the commutant of $\delta$ with $\tau$ for $t$, and with the dumb variable $\sigma$ instead of $\tau$. This completes the proof.

The abundance of the operators, commuting with $\delta$ in $C\left(\mathbb{R}_{+}\right)$given by Theorem 2.1, is in sharp contrast to the set of linear operators commuting with $\delta$ in $C(\Delta)$, where $\Delta$ is a segment $[a, b] \subset \mathbb{R}_{+}$. Then the only such operators are the trivial ones:

$$
M f(t)=c f(t), \quad c=\text { const. }
$$

Such a result for differentiation operator $\mathrm{d} / \mathrm{d} x$ is shown by Kahane [12]. The corresponding result for the Euler operator $\delta$ will be stated in the following theorem.

Theorem 2.3 Let $[a, b] \subset \mathbb{R}_{+}$. Then a continuous linear operator $M: C[a, b] \rightarrow C[a, b]$, such that $M: C^{1}[a, b] \rightarrow C^{1}[a, b]$, commutes with the Euler operator $\delta$ in $C^{1}[a, b]$ if and only if it is an operator of the form

$$
M f(t)=c f(t)
$$

with a constant $c$.

Proof Let $[a, b]$ be an arbitrary segment of $\mathbb{R}_{+}$and let $M \delta=\delta M$ in $C^{1}[a, b]$. Consider the substitution $t=\mathrm{e}^{x}$ as the transformation

$$
\begin{equation*}
S f(t)=f\left(\mathrm{e}^{x}\right)=: \tilde{f}(x) \tag{11}
\end{equation*}
$$

Obviously $S: C[a, b] \rightarrow C[\ln a, \ln b]$ and $S: C^{1}[a, b] \rightarrow C^{1}[\ln a, \ln b]$. Then, denoting $D:=\mathrm{d} / \mathrm{d} t$, one has as in (4)

$$
\begin{equation*}
S \delta f(t)=f^{\prime}\left(\mathrm{e}^{x}\right)=D S f(t) \tag{12}
\end{equation*}
$$

It is supposed that

$$
M \delta f(t)=\delta M f(t)
$$

Applying $S$ on the left hand side and using (12) yields

$$
\begin{equation*}
S M \delta f(t)=\operatorname{S\delta Mf(t)=\operatorname {DSM}f(t)......} \tag{13}
\end{equation*}
$$

Denoting by $\tilde{M}$ the operator

$$
\begin{equation*}
\tilde{M}=S M S^{-1} \tag{14}
\end{equation*}
$$

It is easily seen from (13) and (12) that

$$
\begin{equation*}
\tilde{M} D \tilde{f}(x)=D \tilde{M} \tilde{f}(x) \tag{15}
\end{equation*}
$$

This means that the conditions of Kahane's theorem [12] are fulfilled for the operator $\tilde{M}$ in $C[\ln a, \ln b]$ and the result is that

$$
\tilde{M} \tilde{f}(x)=c \tilde{f}(x), \quad c=\text { const }
$$

which in view of (11) and (14) gives also the desired

$$
M f(t)=c f(t), \quad c=\text { const. }
$$

## 3. A general convolution related to the Euler operator

Basic for the theory of differentiation operator $\mathrm{d} / \mathrm{d} t$ considered in a space $C(\Delta)$ of continuous functions on an interval $\Delta$ is the operation

$$
\begin{equation*}
(f * g)(t)=\Phi_{\tau}\left\{\int_{\tau}^{t} f(t+\tau-\sigma) g(\sigma) \mathrm{d} \sigma\right\}, \tag{16}
\end{equation*}
$$

where $\Phi$ is a linear functional on $C(\Delta)$. Its properties are studied in detail in [13]. The operation (16) is bilinear, commutative, and associative in $C(\Delta)$. It generalizes the classical Duhamel convolution

$$
\begin{equation*}
(f * g)(t)=\int_{0}^{t} f(t-\tau) g(\tau) \mathrm{d} \tau \tag{17}
\end{equation*}
$$

when the functional $\Phi$ in (16) is $\Phi(f)=f(0)$.
In ref. [7] it is shown that any operator of the commutant of $\mathrm{d} / \mathrm{d} t$ in $C(\Delta)$ with an invariant hyperplane $C_{\Phi}(\Delta)=\{f \in C(\Delta), \Phi(f)=0\}$ has the form $M f(t)=\mu f(t)+(m * f)(t)$ with $\mu=$ const and $m \in C(\Delta)$.

In order to extend this result to the Euler operator an analogue of the operation (16) is needed. In the literature only the analogue

$$
(f * g)(t)=\int_{1}^{t} f\left(\frac{t}{\tau}\right) g(\tau) \frac{\mathrm{d} \tau}{\tau}
$$

of the Duhamel convolution (17) is known (see [2]).

## Definition 3.1 The analytic function

$$
\begin{equation*}
E(\lambda)=\Phi_{\tau}\left(\tau^{\lambda}\right) \tag{18}
\end{equation*}
$$

is said to be the Euler indicatrix of the functional $\Phi$.
It is also convenient to denote for the rest of this article

$$
\begin{equation*}
\varphi_{\lambda}(t)=\frac{t^{\lambda}}{E(\lambda)}=\frac{t^{\lambda}}{\Phi_{\tau}\left(\tau^{\lambda}\right)} \tag{19}
\end{equation*}
$$

Here a 'multiplicative variant' of (16) is proposed.
THEOREM3.2 Let $\Phi$ be a continuous non-zero linear functional on $C\left(\mathbb{R}_{+}\right)$. Then the operation

$$
\begin{equation*}
(f * g)(t)=\Phi_{\tau}\left\{\int_{\tau}^{t} f\left(\frac{t \tau}{\sigma}\right) g(\sigma) \frac{\mathrm{d} \sigma}{\sigma}\right\} \tag{20}
\end{equation*}
$$

is a separately continuous, bilinear, commutative, and associative operation in $C\left(\mathbb{R}_{+}\right)$ such that

$$
\begin{equation*}
\Phi(f * g)=0 . \tag{21}
\end{equation*}
$$

Proof According to Riesz-Markov theorem ([4, Theorem 4.10.1])

$$
\Phi\{f\}=\int_{\alpha}^{\beta} f(\tau) \mathrm{d} \sigma(\tau)
$$

with $\Delta=[\alpha, \beta] \subset \mathbb{R}_{+}$and a Radon measure $\sigma(t)$. Hence, (20) is a separately continuous operation in $C(\Delta)$.

The bilinearity and the commutativity of the operation (20) are almost evident, whereas the associativity of (20) is by no means obvious and needs a proof.

Let $f(t)=t^{\mu}$ and $g(t)=t^{\nu}$. Then

$$
\begin{aligned}
\left\{t^{\mu}\right\} *\left\{t^{\nu}\right\} & =\Phi_{\tau}\left\{\int_{\tau}^{t} \frac{(t \tau)^{\mu}}{\sigma^{\mu}} \sigma^{\nu} \frac{\mathrm{d} \sigma}{\sigma}\right\}=t^{\mu} \Phi_{\tau}\left\{\tau^{\mu} \int_{\tau}^{t} \sigma^{\nu-\mu-1} \mathrm{~d} \sigma\right\} \\
& =t^{\mu} \Phi_{\tau}\left\{\tau^{\mu} \frac{t^{\nu-\mu}-\tau^{\nu-\mu}}{\nu-\mu}\right\}=\frac{E(\mu) t^{\nu}-E(\nu) t^{\mu}}{\nu-\mu}
\end{aligned}
$$

Using this expression, it follows that

$$
\begin{equation*}
\left(\left\{t^{\mu}\right\} *\left\{t^{\nu}\right\}\right) *\left\{t^{\varkappa}\right\}=\left\{t^{\mu}\right\} *\left(\left\{t^{\nu}\right\} *\left\{t^{\varkappa}\right\}\right) \tag{22}
\end{equation*}
$$

because both sides of (22) have one and the same symmetric form

$$
t^{\mu} \frac{E(v) E(\varkappa)}{(\mu-v)(\mu-\varkappa)}+t^{\nu} \frac{E(\varkappa) E(\mu)}{(v-\varkappa)(v-\mu)}+t^{\varkappa} \frac{E(\mu) E(v)}{(\varkappa-\mu)(\varkappa-v)}
$$

with respect to $\mu, \nu$, and $\varkappa$. Then, (22) differentiated $m, n$, and $k$ times with respect to $\mu, \nu$, and $\varkappa$ correspondingly, gives

$$
\left(\left\{t^{\mu}(\ln t)^{m}\right\} *\left\{t^{\nu}(\ln t)^{n}\right\}\right) *\left\{t^{\varkappa}(\ln t)^{k}\right\}=\left\{t^{\mu}(\ln t)^{m}\right\} *\left(\left\{t^{\nu}(\ln t)^{n}\right\} *\left\{t^{\varkappa}(\ln t)^{k}\right\}\right)
$$

Next, passing to the limits $\mu \rightarrow+0, v \rightarrow+0$, and $\varkappa \rightarrow+0$, one gets

$$
\left(\left\{(\ln t)^{m}\right\} *\left\{(\ln t)^{n}\right\}\right) *\left\{(\ln t)^{k}\right\}=\left\{(\ln t)^{m}\right\} *\left(\left\{(\ln t)^{n}\right\} *\left\{(\ln t)^{k}\right\}\right) .
$$

But the bilinearity of (20) implies for arbitrary polynomials $P, Q$, and $R$

$$
(\{P(\ln t)\} *\{Q(\ln t)\}) *\{R(\ln t)\}=\{P(\ln t)\} *(\{Q(\ln t)\} *\{R(\ln t)\})
$$

To finish this proof, note that if $t \in \mathbb{R}_{+}$then $\ln t$ covers the whole real line $\mathbb{R}$. Then Weierstrass' theorem allows any function in $C\left(\mathbb{R}_{+}\right)$to be approximated almost uniformly by polynomials of $\ln t, t>0$, i.e. by a sequence uniformly convergent to the function on each segment $[a, b] \subset \mathbb{R}_{+}$. Due to the continuity of the functional $\Phi$, the desired equality holds for every $f, g, h \in C\left(\mathbb{R}_{+}\right)$

$$
(f * g) * h=f *(g * h)
$$

The second statement (21) of the theorem can be checked as follows: The function

$$
h(t, \tau)=\int_{\tau}^{t} f\left(\frac{t \tau}{\sigma}\right) g(\sigma) \frac{\mathrm{d} \sigma}{\sigma}
$$

is antisymmetric with respect to $t$ and $\tau$, i.e. $h(t, \tau)=-h(\tau, t)$, and, hence

$$
\begin{align*}
\Phi\{f * g\} & =\Phi_{t}\{(f * g)(t)\}=\Phi_{t} \Phi_{\tau}\{h(t, \tau)\} \\
& =\Phi_{t} \Phi_{\tau}\{-h(\tau, t)\}=-\Phi_{t} \Phi_{\tau}\{h(\tau, t)\} \\
& =-\Phi_{\tau} \Phi_{t}\{h(\tau, t)\}=-\Phi_{t} \Phi_{\tau}\{h(t, \tau)\}=-\Phi\{f * g\} . \tag{23}
\end{align*}
$$

Here, the Fubini property of the functional $\Phi$ is used, i.e. the possibility of interchanging of $\Phi_{t}$ and $\Phi_{\tau}$. At the end, $t$ and $\tau$ are also interchanged, since they are 'dumb' variables in the expression. Thus, the last chain of equalities gives $2 \Phi\{f * g\}=0$ and $\Phi\{f * g\}=0$ holds.

## 4. The commutant of $\delta$ in an invariant hyperplane

In this section, another commutant of $\delta$ will be described. Here, it is supposed that the operators $M: C\left(\mathbb{R}_{+}\right) \rightarrow C\left(\mathbb{R}_{+}\right)$preserve $C^{1}\left(\mathbb{R}_{+}\right)$, i.e. $M: C^{1}\left(\mathbb{R}_{+}\right) \rightarrow C^{1}\left(\mathbb{R}_{+}\right)$, and additionally they preserve invariant also a hyperplane

$$
\begin{equation*}
C_{\Phi}:=\left\{f \in C\left(\mathbb{R}_{+}\right): \Phi\{f\}=0\right\} \tag{24}
\end{equation*}
$$

i.e. $M: C_{\Phi} \rightarrow C_{\Phi}$, where $\Phi: C\left(\mathbb{R}_{+}\right) \rightarrow \mathbb{C}$ is an arbitrary non-zero linear functional.

The main result of this section is the explicit representation $M f=\mu f+m * f$ of any linear continuous operator $M: C\left(\mathbb{R}_{+}\right) \rightarrow C\left(\mathbb{R}_{+}\right)$with $M: C_{\Phi} \rightarrow C_{\Phi}$ and commuting with $\delta=t(\mathrm{~d} / \mathrm{d} t)$ in $C_{\Phi}^{1}:=C_{\Phi} \cap C^{1}\left(\mathbb{R}_{+}\right)$.

To this end some auxilliary results will be considered.

Lemma 4.1 A linear operator $M: C\left(\mathbb{R}_{+}\right) \rightarrow C\left(\mathbb{R}_{+}\right)$with $M: C^{1}\left(\mathbb{R}_{+}\right) \rightarrow C^{1}\left(\mathbb{R}_{+}\right)$and $M: C_{\Phi}\left(\mathbb{R}_{+}\right) \rightarrow C_{\Phi}\left(\mathbb{R}_{+}\right)$commutes with the Euler operator $\delta$ in $C_{\Phi}^{1}\left(\mathbb{R}_{+}\right)$iff $M$ commutes with $L_{\lambda}$ in $C\left(\mathbb{R}_{+}\right)$, where $L_{\lambda}$ is the right inverse in $C\left(\mathbb{R}_{+}\right)$of the perturbed Euler operator $\delta_{\lambda}=\delta-\lambda$, satisfying the boundary condition $\Phi\left(L_{\lambda} f\right)=0$.

Proof First an explicit expression for $L_{\lambda}$ will be found. Let $\lambda$ be such that $E(\lambda) \neq 0$. Then

$$
\begin{equation*}
L_{\lambda} f(t)=\int_{1}^{t}\left(\frac{t}{\tau}\right)^{\lambda} f(\tau) \frac{\mathrm{d} \tau}{\tau}-\frac{t^{\lambda}}{E(\lambda)} \Phi_{\tau}\left\{\int_{1}^{\tau}\left(\frac{\tau}{\sigma}\right)^{\lambda} f(\sigma) \frac{\mathrm{d} \sigma}{\sigma}\right\} . \tag{25}
\end{equation*}
$$

Indeed, the general solution of the linear differential equation $t(\mathrm{~d} y / \mathrm{d} t)-\lambda y=f(t)$ is $y=t^{\lambda}\left(c+\int_{1}^{t} f(\tau) / \tau^{\lambda+1} \mathrm{~d} \tau\right)$ with an arbitrary constant $c$. Then, using the condition $\Phi\{y\}=$ 0 , one obtains the value

$$
c=-\frac{1}{E(\lambda)} \Phi_{\tau}\left\{\int_{1}^{\tau}\left(\frac{\tau}{\sigma}\right)^{\lambda} f(\sigma) \frac{\mathrm{d} \sigma}{\sigma}\right\} .
$$

Now suppose that $M L_{\lambda}=L_{\lambda} M$ in $C\left(\mathbb{R}_{+}\right)$and $f \in C_{\Phi}^{1}\left(\mathbb{R}_{+}\right)$. To prove that

$$
h=\left(M \delta_{\lambda}-\delta_{\lambda} M\right) f=0,
$$

consider

$$
\left.L_{\lambda} h=L_{\lambda} M \delta_{\lambda} f-L_{\lambda} \delta_{\lambda} M f=M\left(L_{\lambda} \delta_{\lambda}\right) f-\left(L_{\lambda} \delta_{\lambda}\right) M f\right)=M f-M f=0
$$

But $L_{\lambda} h=0$ implies $\delta_{\lambda} L_{\lambda} h=0$, i.e. $h=0$. Hence $M \delta_{\lambda} f=\delta_{\lambda} M f$.
Conversely, let $M \delta_{\lambda} f=\delta_{\lambda} M f$ for every $f \in C_{\Phi}^{1}\left(\mathbb{R}_{+}\right)$. If $g \in C\left(\mathbb{R}_{+}\right)$, then there is a function $f \in C_{\Phi}^{1}\left(\mathbb{R}_{+}\right)$, for which $f=L_{\lambda} g$. After the substitution $f=L_{\lambda} g$ in $\delta_{\lambda} M f=M \delta_{\lambda} f$, one gets

$$
\delta_{\lambda}\left(M L_{\lambda} g\right)=M \delta_{\lambda} L_{\lambda} g=M g
$$

Since $\Phi\left\{L_{\lambda} g\right\}=0$, then $\Phi\left\{M L_{\lambda} g\right\}=0$. But the solution of the equation $\delta_{\lambda} y=M g$ with the condition $\Phi\{y\}=0$ by definition is $y=L_{\lambda}(M g)$, which implies

$$
M L_{\lambda} g=L_{\lambda} M g
$$

in $C\left(\mathbb{R}_{+}\right)$, which completes the proof.
Lemma 4.2 The operator $L_{\lambda}$ given by (25) is a convolution operator of the form

$$
\begin{equation*}
L_{\lambda} f=\varphi_{\lambda} * f=\left\{\frac{t^{\lambda}}{E(\lambda)}\right\} * f \tag{26}
\end{equation*}
$$

Proof The equality (26) can be checked directly using (21) and the representation $\int_{\tau}^{t}=\int_{1}^{t}-\int_{1}^{\tau}$.

Theorem 4.3 The commutant of $\delta$ in the invariant hyperplane $C_{\Phi}$ coincides with the commutant of any of the operators $L_{\lambda}$ in $C\left(\mathbb{R}_{+}\right)$.

Proof Let $M: C\left(\mathbb{R}_{+}\right) \rightarrow C\left(\mathbb{R}_{+}\right)$be a linear operator commuting with $L_{\lambda}$ for some $\lambda \in \mathbb{C}$, i.e. $M L_{\lambda}=L_{\lambda} M$. First, it will be proved that $C_{\Phi}$ is an invariant hyperplane for $M$. Indeed, let $g$ be a function from $C\left(\mathbb{R}_{+}\right)$and $f$ be the solution of the problem

$$
\begin{equation*}
\delta f-\lambda f=g, \quad \Phi\{f\}=0 \tag{27}
\end{equation*}
$$

Then

$$
\begin{equation*}
L_{\lambda} M g=M L_{\lambda} g=M f \tag{28}
\end{equation*}
$$

and hence

$$
M g=(\delta-\lambda) M f
$$

Using (27) this can be written as

$$
M(\delta-\lambda) f=(\delta-\lambda) M f
$$

or, equivalently,

$$
(M \delta) f=(\delta M) f
$$

It remains to show that $\Phi\{M f\}=0$. This follows using (28) and the representation (26) of $L_{\lambda}$ as a convolutional operator, along with the property $\Phi\{p * q\}=0$ for arbitrary $p, q \in C\left(\mathbb{R}_{+}\right)$ of the convolution (20).

Conversely, let $M: C\left(\mathbb{R}_{+}\right) \rightarrow C\left(\mathbb{R}_{+}\right)$have the hyperplane $C_{\Phi}$ as an invariant subspace and let $M \delta=\delta M$ in $C_{\Phi}^{1}$. One has to prove that $M L_{\lambda}=L_{\lambda} M$ for $\lambda \in \mathbb{C}$ with $E(\lambda) \neq 0$.

Let $f \in C\left(\mathbb{R}_{+}\right)$be arbitrary and denote $h=\left(M L_{\lambda}-L_{\lambda} M\right) f$. Then

$$
(\delta-\lambda) h=(\delta-\lambda) M L_{\lambda} f-M f=M(\delta-\lambda) L_{\lambda} f-M f=0
$$

and also

$$
\Phi\{h\}=\Phi\left\{M L_{\lambda} f\right\}-\Phi\left\{L_{\lambda} M f\right\}=0
$$

according to our assumptions. Since $\lambda$ is not an eigenvalue, i.e. $E(\lambda) \neq 0$, then $h=0$, or

$$
M L_{\lambda} f=L_{\lambda} M f
$$

The proof is completed.
DEFINITION 4.4 A linear operator $M: C\left(\mathbb{R}_{+}\right) \rightarrow C\left(\mathbb{R}_{+}\right)$is said to be a multiplier of the convolutional algebra $\left(C\left(\mathbb{R}_{+}\right), *\right)$ when for arbitrary $f, g \in C\left(\mathbb{R}_{+}\right)$it holds

$$
M(f * g)=(M f) * g .
$$

Theorem 4.5 A linear operator $M: C\left(\mathbb{R}_{+}\right) \rightarrow C\left(\mathbb{R}_{+}\right)$with $M: C^{1}\left(\mathbb{R}_{+}\right) \rightarrow C^{1}\left(\mathbb{R}_{+}\right)$is a multiplier of the convolution algebra $\left(C\left(\mathbb{R}_{+}\right), *\right)$ iff it has a representation of the form

$$
\begin{equation*}
M f(t)=\mu f(t)+(m * f)(t) \tag{29}
\end{equation*}
$$

where $\mu=\mathrm{const}$ and $m \in C\left(\mathbb{R}_{+}\right)$.
Proof The sufficiency is obvious. In order to prove the necessity, the notations from (18) and (19) will be used for convenience.

Let $M: C\left(\mathbb{R}_{+}\right) \rightarrow C\left(\mathbb{R}_{+}\right)$be an arbitrary multiplier of $\left(C\left(\mathbb{R}_{+}\right), *\right)$. Applying (26), one has

$$
\begin{equation*}
M L_{\lambda} f=M\left(\varphi_{\lambda} * f\right)=\left(M \varphi_{\lambda}\right) * f=\varphi_{\lambda} * M f=L_{\lambda} M f \tag{30}
\end{equation*}
$$

i.e. $M L_{\lambda} f=L_{\lambda} M f$. Also, denoting $e_{\lambda}=M \varphi_{\lambda}$, one has $e_{\lambda} \in C^{1}\left(\mathbb{R}_{+}\right)$, and (30) gives

$$
L_{\lambda} M f=e_{\lambda} * f
$$

It remains to apply the operator $\delta_{\lambda}=\delta-\lambda$ and the definition of $L_{\lambda}$ as the right inverse operator of $\delta_{\lambda}$ to obtain

$$
M f=\delta_{\lambda}\left(e_{\lambda} * f\right)
$$

The right hand side can be represented in a different way using the identity

$$
\begin{equation*}
\delta_{\lambda}(u * v)=\left(\delta_{\lambda} u\right) * v+\Phi(u) v \tag{31}
\end{equation*}
$$

which can be checked directly. Then

$$
(M f)(t)=\left[\left(\delta_{\lambda} e_{\lambda}\right) * f\right](t)+\Phi\left(e_{\lambda}\right) f(t),
$$

which is the representation (29) with $\mu=\Phi\left(e_{\lambda}\right)=\Phi\left\{M \varphi_{\lambda}\right\}$ and $m(t)=\left(\delta_{\lambda} e_{\lambda}\right)(t)$ $=\left[\delta_{\lambda} M \varphi_{\lambda}\right](t)$. Thus, the necessity is proved.

Theorem 4.6 The function $\varphi_{\lambda}(t)=t^{\lambda} / E(\lambda)$ is a cyclic element of the operator $L_{\lambda}$.
Proof Let $f \in C\left(\mathbb{R}_{+}\right)$be arbitrarily chosen. It is needed to prove that there is a sequence of functions of the form

$$
f_{n}(t)=\sum_{k=0}^{n} c_{n k} L_{\lambda}^{k} \varphi_{\lambda}(t), \quad n=1,2, \ldots
$$

converging to $f(t)$ uniformly on any segment $[a, b]$ of $\mathbb{R}_{+}$.
First, it is easy to show by induction that

$$
\begin{equation*}
L_{\lambda}^{k} \varphi_{\lambda}(t)=t^{\lambda} p_{k}(\ln t) \tag{32}
\end{equation*}
$$

where $p_{k}$ is a polynomial of degree $k$, i.e. $p_{k}(\ln t)=\sum_{s=0}^{k} a_{k s}(\ln t)^{s}$.
Indeed, if $k=1$, then by (26) and (20)

$$
\begin{aligned}
L_{\lambda} \varphi_{\lambda}(t) & =\left\{\frac{t^{\lambda}}{E(\lambda)}\right\} *\left\{\frac{t^{\lambda}}{E(\lambda)}\right\}=\frac{1}{E^{2}(\lambda)} \Phi_{\tau}\left\{\int_{\tau}^{t}\left(\frac{t \tau}{\sigma}\right)^{\lambda} \sigma^{\lambda} \frac{\mathrm{d} \sigma}{\sigma}\right\} \\
& =\frac{1}{E^{2}(\lambda)} t^{\lambda} \Phi_{\tau}\left\{\tau^{\lambda} \int_{\tau}^{t} \frac{\mathrm{~d} \sigma}{\sigma}\right\}=t^{\lambda}\left[\frac{\Phi_{\tau}\left\{\tau^{\lambda}\right\}}{E^{2}(\lambda)} \ln t-\frac{\Phi_{\tau}\left\{\tau^{\lambda} \ln \tau\right\}}{E^{2}(\lambda)}\right]
\end{aligned}
$$

Next, the inductive step will be made. Suppose that

$$
L_{\lambda}^{k-1} \varphi_{\lambda}(t)=t^{\lambda} p_{k-1}(\ln t)
$$

Then

$$
\begin{aligned}
L_{\lambda}^{k} \varphi_{\lambda}(t) & =L_{\lambda}\left(L_{\lambda}^{k-1} \varphi_{\lambda}(t)\right)=\left\{\frac{t^{\lambda}}{E(\lambda)}\right\} * L_{\lambda}^{k-1} \varphi_{\lambda}(t) \\
& =\frac{1}{E(\lambda)} \Phi_{\tau}\left\{\int_{\tau}^{t}\left(\frac{t \tau}{\sigma}\right)^{\lambda} \sigma^{\lambda} p_{k-1}(\ln \sigma) \frac{\mathrm{d} \sigma}{\sigma}\right\} \\
& =\frac{1}{E(\lambda)} t^{\lambda} \Phi_{\tau}\left\{\tau^{\lambda} \int_{\tau}^{t} p_{k-1}(\ln \sigma) \mathrm{d} \ln \sigma\right\}
\end{aligned}
$$

The integration of $p_{k-1}$ gives a polynomial $q_{k}$ of $\ln t$ of degree $k$ and the above chain of equalities can be continued as

$$
\begin{aligned}
L_{\lambda}^{k} \varphi_{\lambda}(t) & =\frac{1}{E(\lambda)} t^{\lambda} \Phi_{\tau}\left\{\tau^{\lambda}\left[q_{k}(\ln t)-q_{k}(\ln \tau)\right]\right\} \\
& =t^{\lambda}\left[\frac{\Phi_{\tau}\left\{\tau^{\lambda}\right\}}{E(\lambda)} q_{k}(\ln t)-\frac{\Phi_{\tau}\left\{\tau^{\lambda} q_{k}(\ln \tau)\right\}}{E(\lambda)}\right],
\end{aligned}
$$

where the expression in the square brackets is obviously a polynomial $p_{k}$ of $\ln t$ of degree $k$, as desired.

Now let $f \in C\left(\mathbb{R}_{+}\right)$be arbitrarily chosen. Consider the function $\tilde{f}(t)=f(t) / t^{\lambda}$, which is again in $C\left(\mathbb{R}_{+}\right)$. Making the substitution $t=\mathrm{e}^{x}, x=\ln t$, the new function $g(x)=\tilde{f}(t)$ is in $C(-\infty, \infty)$. By Weierstrass' theorem, $g$ can be approximated almost uniformly on $(-\infty, \infty)$ by a sequence of polynomials $\left\{r_{n}(x)\right\}_{n=1}^{\infty}, r_{n}(x)=\sum_{k=0}^{n} b_{n k} x^{k}$, i.e. . the convergence is uniform on any segment $[a, b] \subset\left(\mathbb{R}_{+}\right)$. Returning to the old variable, $\widetilde{f}(t)$ can be approximated by the sequence of polynomials $\left\{r_{n}(\ln t)=\sum_{k=0}^{n} b_{n k}(\ln t)^{k}\right\}_{n=1}^{\infty}$. Finally, multiplying by $t^{\lambda}$ and using (32), the desired approximation of $f(t)$ on $\left(\mathbb{R}_{+}\right)$follows from the representation

$$
f_{n}(t)=t^{\lambda} r_{n}(\ln t)=\sum_{k=0}^{n} b_{n k} t^{\lambda}(\ln t)^{k}=\sum_{k=0}^{n} c_{n k} t^{\lambda} p_{k}(\ln t)=\sum_{k=0}^{n} c_{n k} L_{\lambda}^{k} \varphi_{\lambda}(t) .
$$

The new coefficients $c_{n k}$ can be calculated from the old ones $b_{n k}$. Thus, $\varphi_{\lambda}$ is a cyclic element of $L_{\lambda}$ in $C\left(\mathbb{R}_{+}\right)$.

Theorem 4.7 A linear operator $M: C\left(\mathbb{R}_{+}\right) \rightarrow C\left(\mathbb{R}_{+}\right)$, such that $M: C^{1}\left(\mathbb{R}_{+}\right) \rightarrow C^{1}\left(\mathbb{R}_{+}\right)$, and with an invariant hyperplane $C_{\Phi}=\left\{f \in C\left(\mathbb{R}_{+}\right): \Phi\{f\}=0\right\}$ commutes with $\delta$ in $C_{\Phi}^{1}$ if and only if it has a representation of the form

$$
\begin{equation*}
(M f)(t)=\mu f(t)+(m * f)(t) \tag{33}
\end{equation*}
$$

with a constant $\mu \in \mathbb{C}$ and $m \in C\left(\mathbb{R}_{+}\right)$.
Proof Since $\Phi\{f * g\}=0$ for $f, g \in C\left(\mathbb{R}_{+}\right)$(see (10)), then each operator of the form (33) has $C_{\Phi}$ as an invariant subspace. It commutes with $\delta$ in $C_{\Phi}^{1}$. Indeed, if $f \in C_{\Phi}^{1}$, then (31) gives

$$
\delta(m * f)=m * \delta f+\Phi\{f\} m
$$

and, using (33),

$$
\delta M f=\mu \delta f+m *(\delta f)+\Phi\{f\} m=\mu \delta f+m *(\delta f)=M \delta f
$$

The sufficiency is proved.
In order to prove the necessity of (33), according to Lemma 4.1, $M L_{\lambda}=L_{\lambda} M$ for $\lambda \in \mathbb{C}$ with $E(\lambda) \neq 0$. As it is shown in [13] (Theorem 1.3.11, p.33), the commutant of $L_{\lambda}$ coincides with the ring of the multipliers of the convolution algebra $\left(C\left(\mathbb{R}_{+}\right), *\right)$ since $L_{\lambda}$ has a cyclic element. By Theorem 4.6 such a cyclic element is the function $\varphi_{\lambda}(t)=t^{\lambda} / E(\lambda)$ for which $L_{\lambda} f=\varphi_{\lambda} * f$. The proof is completed.

Remark The constant $\mu$ and the function $m \in C\left(\mathbb{R}_{+}\right)$in (29) are uniquely determined. Indeed, assume that $\mu f+m * f=\mu_{1} f+m_{1} * f$. Take $f$ such that $\Phi(f) \neq 0$. Then, (23) implies $\mu \Phi(f)=\mu_{1} \Phi(f)$, and hence $\mu=\mu_{1}$. From $m * f=m_{1} * f$ for arbitrary $f \in C\left(\mathbb{R}_{+}\right)$it follows that $\left(m-m_{1}\right) * f=0$, and hence $m=m_{1}$.

## 5. Mean-periodic functions for the Euler operator

Definition 5.1 A function $f \in C\left(\mathbb{R}_{+}\right)$is said to be mean-periodic for the Euler operator with respect to the linear functional $\Phi$ if

$$
\Phi_{\tau}\{f(t \tau)\}=0
$$

identically in $\mathbb{R}_{+}$.
It is clear that the mean-periodic functions with respect to $\Phi$ form the kernel space of the operator

$$
M f(t)=\Phi_{\tau}\{f(t \tau)\}
$$

commuting with the Euler operator $\delta$ in $C\left(\mathbb{R}_{+}\right)$.
Now a connection between the mean-periodic functions and the convolutional algebra $\left(C\left(\mathbb{R}_{+}\right), *\right)$ will be shown.

Theorem 5.2 The mean-periodic functions for the Euler operator $\delta$ with respect to any non-zero functional $\Phi: C\left(\mathbb{R}_{+}\right) \rightarrow \mathbb{C}$ form an ideal in the convolutional algebra $\left(C\left(\mathbb{R}_{+}\right), *\right)$.

Proof One need prove only that the convolutional product $(f * g)(t)$ of a mean-periodic function $f$ and an arbitrary function $g \in C\left(\mathbb{R}_{+}\right)$is a mean-periodic function, too, i.e. it is given that $\Phi_{\tau}\{f(t \tau)\}=0$ and then $\Phi_{\tau}\{(f * g)(t \tau)\}=0$ is to be shown. By (20)

$$
(f * g)(t \tau)=\Phi_{\sigma}\left\{\int_{\sigma}^{t \tau} f\left(\frac{t \tau \sigma}{\eta}\right) g(\eta) \frac{\mathrm{d} \eta}{\eta}\right\}
$$

and

$$
\begin{align*}
\Phi_{\tau}\{(f * g)(t \tau)\}= & \Phi_{\tau} \Phi_{\sigma}\left\{\int_{\sigma}^{t \tau} f\left(\frac{t \tau \sigma}{\eta}\right) g(\eta) \frac{\mathrm{d} \eta}{\eta}\right\} \\
= & \Phi_{\tau} \Phi_{\sigma}\left\{\int_{\sigma}^{\tau} f\left(\frac{t \tau \sigma}{\eta}\right) g(\eta) \frac{\mathrm{d} \eta}{\eta}\right\} \\
& +\Phi_{\tau} \Phi_{\sigma}\left\{\int_{\tau}^{t \tau} f\left(\frac{t \tau \sigma}{\eta}\right) g(\eta) \frac{\mathrm{d} \eta}{\eta}\right\} . \tag{34}
\end{align*}
$$

Interchanging $\tau$ and $\sigma$ in the first term of (34) and using the Fubini commutational property of the functionals yields

$$
\begin{aligned}
\Phi_{\tau} \Phi_{\sigma}\left\{\int_{\sigma}^{\tau} f\left(\frac{t \tau \sigma}{\eta}\right) g(\eta) \frac{\mathrm{d} \eta}{\eta}\right\} & =\Phi_{\sigma} \Phi_{\tau}\left\{\int_{\tau}^{\sigma} f\left(\frac{t \tau \sigma}{\eta}\right) g(\eta) \frac{\mathrm{d} \eta}{\eta}\right\} \\
& =\Phi_{\sigma} \Phi_{\tau}\left\{-\int_{\sigma}^{\tau} f\left(\frac{t \tau \sigma}{\eta}\right) g(\eta) \frac{\mathrm{d} \eta}{\eta}\right\} \\
& =-\Phi_{\tau} \Phi_{\sigma}\left\{\int_{\sigma}^{\tau} f\left(\frac{t \tau \sigma}{\eta}\right) g(\eta) \frac{\mathrm{d} \eta}{\eta}\right\},
\end{aligned}
$$

thus obtaining

$$
\begin{equation*}
\Phi_{\tau} \Phi_{\sigma}\left\{\int_{\sigma}^{\tau} f\left(\frac{t \tau \sigma}{\eta}\right) g(\eta) \frac{\mathrm{d} \eta}{\eta}\right\}=0 . \tag{35}
\end{equation*}
$$

The second term in (34) also vanishes

$$
\begin{equation*}
\Phi_{\tau} \Phi_{\sigma}\left\{\int_{\tau}^{t \tau} f\left(\frac{t \tau \sigma}{\eta}\right) g(\eta) \frac{\mathrm{d} \eta}{\eta}\right\}=\Phi_{\tau}\left\{\int_{\tau}^{t \tau} \Phi_{\sigma}\left\{f\left(\frac{t \tau \sigma}{\eta}\right)\right\} g(\eta) \frac{\mathrm{d} \eta}{\eta}\right\}=0 \tag{36}
\end{equation*}
$$

since $f$ is mean-periodic and hence

$$
\Phi_{\sigma}\left\{f\left(\frac{t \tau \sigma}{\eta}\right)\right\}=0
$$

Finally, equations (34)-(36) give the desired result $\Phi_{\tau}\{(f * g)(t \tau)\}=0$.

## 6. Application to the Euler differential equation

Now Theorem 5.2 will be applied to find necessary and sufficient conditions in order the Euler differential equation

$$
\begin{equation*}
P(\delta) y(t)=f(t), \quad 0<t<\infty, \tag{37}
\end{equation*}
$$

to have a unique mean-periodic solution with respect to a non-zero linear functional $\Phi$ in $C\left(\mathbb{R}_{+}\right)$.Here, $\delta=t(\mathrm{~d} / \mathrm{d} t)$ is the Euler operator and $P(\mu)=a\left(\mu-\mu_{1}\right)\left(\mu-\mu_{2}\right) \cdots\left(\mu-\mu_{k}\right)$ is a polynomial.

Theorem 6.1 In order for the Euler differential equation (37) to have a unique mean-periodic solution with respect to a non-zero linear functional $\Phi$ in $C\left(\mathbb{R}_{+}\right)$, it is necessary and sufficient no roots of the equation $P(\lambda)=0$ to be roots of the Euler indicatrix $E(\lambda)=\Phi_{\tau}\left(\tau^{\lambda}\right)$.

Proof Consider the Euler differential equation (37). It is clear that in order for $y$ to be a mean-periodic solution, the right hand side, i.e. the function $f(t)$, should be mean-periodic, too. Formally, let $M f(t)=\Phi_{\tau}\{f(t \tau)\}$. Applying $M$ to (37) and using the commutativity of $\delta=t(\mathrm{~d} / \mathrm{d} t)$ and $M$ yields

$$
P(\delta) M y(t)=M f(t) .
$$

Then from $M y=0$ it follows that $M f=0$, i.e. the requirement $f$ to be mean-periodic is a necessary condition for existing of a mean-periodic solution $y$. It can be shown that it is also a sufficient condition, but in general the solution may not be unique. Indeed, if a root $\mu$ of the equation $P(\lambda)=0$ is a root of the Euler indicatrix $E(\lambda)$, then the function $t^{\mu}$ is a solution of the homogeneous equation $P(\delta) u=0$, and hence the uniqueness of the solution holds no more.

Now it will be shown that if neither of the roots $\mu_{1}, \mu_{2}, \ldots, \mu_{k}$ of the equation $P(\lambda)=0$ is a root of the Euler indicatrix $E(\lambda)=\Phi_{\tau}\left\{\tau^{\lambda}\right\}$, then there exists a unique mean-periodic solution of the Euler equation $P(\delta) y=f$, provided $f$ is a mean-periodic function with respect to $\Phi$.

Assuming that $y$ is a mean-periodic solution of (37), an explicit expression for $y$ will be obtained. Let $P$ be a polynomial of degree $k$

$$
P(\mu)=a\left(\mu-\mu_{1}\right)\left(\mu-\mu_{2}\right) \cdots\left(\mu-\mu_{k}\right)
$$

From the assumption that $y$ is a mean-periodic solution it follows that

$$
\begin{equation*}
\Phi\{y\}=\Phi\{\delta y\}=\cdots=\Phi\left\{\delta^{k-1} y\right\}=0 . \tag{38}
\end{equation*}
$$

Indeed, the mean-periodicity of $y$ means that

$$
\Phi_{\tau}\{y(t \tau)\}=0
$$

Applying the operator $\delta$ to this identity with respect to $t$, Theorem 2.1 gives

$$
\Phi_{\tau}\left\{\left(\delta^{n} y\right)(t \tau)\right\}=0, \quad n=1,2, \ldots, k-1
$$

It remains to put $t=1$ in order to obtain the boundary conditions (38).
Next, unique solution of (37) is

$$
\begin{equation*}
y=\frac{1}{a} L_{\mu_{k}} L_{\mu_{k-1}} \cdots L_{\mu_{1}} f(t) . \tag{39}
\end{equation*}
$$

Indeed, the equation (37) can be represented as

$$
\left(\delta-\mu_{1}\right)\left[\left(\delta-\mu_{2}\right) \cdots\left(\delta-\mu_{k}\right) y(t)\right]=\frac{1}{a} f(t)
$$

Denoting the square brackets by $u_{1}(t)$ yields

$$
\delta u_{1}-\mu_{1} u_{1}=\frac{1}{a} f
$$

for $u_{1}$ with $\Phi\left\{u_{1}\right\}=0$, as it follows from (38). This equation has the unique solution $u_{1}=(1 / a) L_{\mu_{1}} f$ with $L_{\mu_{1}}$ defined as in Lemma 4.1. Next solve

$$
\delta u_{2}-\mu_{2} u_{2}=u_{1}, \quad \Phi\left\{u_{2}\right\}=0
$$

for $u_{2}(t)=\left(\delta-\mu_{3}\right) \cdots\left(\delta-\mu_{k}\right) y(t)$ with the unique solution $u_{2}=L_{\mu_{2}} u_{1}$. Continuing in the same manner one gets the unique solution (39) of the initial equation (37). Now it is easy to verify that (39) is indeed a mean-periodic solution. It can be written in the form of convolutional product using Lemma 4.2:

$$
\begin{equation*}
y=\frac{1}{a} L_{\mu_{k}} L_{\mu_{k-1}} \cdots L_{\mu_{1}} f(t)=\left(\frac{1}{a} \varphi_{\mu_{k}} * \varphi_{\mu_{k-1}} * \cdots * \varphi_{\mu_{1}}\right) * f=\varphi * f \tag{40}
\end{equation*}
$$

with $\varphi:=(1 / a) \varphi_{\mu_{k}} * \varphi_{\mu_{k-1}} * \cdots * \varphi_{\mu_{1}}$. It remains to use Theorem 5.2 to assert that the mean-periodicity of $f$ implies the mean-periodicity of $y$.

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