

Parallel PCG solver for non-conforming FEM elasticity problems

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Outline of the talk:

- Linear Elasticity Problem
- Non-Conforming FEM
- Preconditioning Strategy
- Parallel Implementation

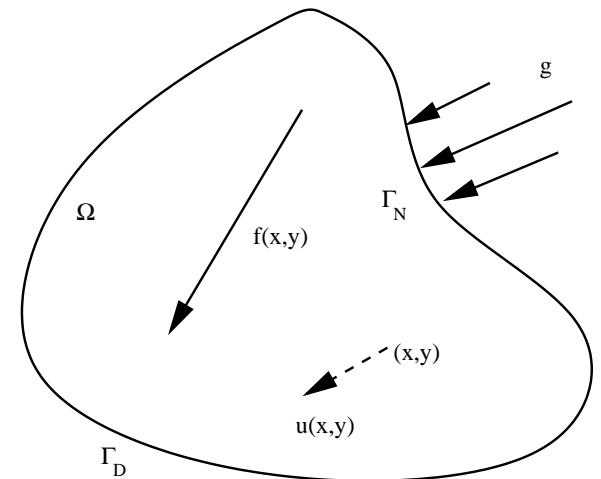
Linear Elasticity Problem

find the displacement $\underline{u} \in [H_E^1(\Omega)]^2 = \{\underline{v} \in [H^1(\Omega)]^2 : \underline{v}|_{\Gamma_D} = \underline{u}_b\}$ of an elastic material such that

$$\int_{\Omega} [2\mu\varepsilon(\underline{u}) : \varepsilon(\underline{v}) + \lambda \operatorname{div} \underline{u} \operatorname{div} \underline{v}] d\Omega = \int_{\Omega} \underline{f}^t \underline{v} d\Omega + \int_{\Gamma_N} \underline{g}_b^t \underline{v} d\Gamma,$$

$\forall \underline{v} \in [H_0^1(\Omega)]^2 = \{\underline{v} \in [H^1(\Omega)]^2 : \underline{v}|_{\Gamma_D} = 0\}$, where $\varepsilon(\underline{u}) := 0.5(\nabla \underline{u} + (\nabla \underline{u})^t)$

- Ω – initial configuration of the elastic body
- \underline{f} – distributed volume forces in Ω
- \underline{g} – boundary tractions (on Γ_N)
- λ, μ – positive constants of Lamé



Linear Elasticity Problem – Discretization

find $\underline{u}^h \in V_E^h$ such that

$$\sum_{e \in \Omega^h} \int_e \left[2\mu \varepsilon^*(\underline{u}^h) : \varepsilon^*(\underline{v}^h) + \lambda \operatorname{div} \underline{u}^h \operatorname{div} \underline{v}^h \right] de = \int_{\Omega} \underline{f}^t \underline{v}^h d\Omega + \int_{\Gamma_N} \underline{g}_b^t \underline{v}^h d\Gamma,$$

$\forall \underline{v}^h \in V_0^h$, where $\varepsilon^*(\underline{u}) := \nabla \underline{u} - 0.5 I_L^{Q^H} (\nabla \underline{u} - (\nabla \underline{u})^t)$

Ω^H – decomposition of Ω into convex quadrilaterals \mathcal{E}

Ω^h – refinement of the macroelements \mathcal{E} into 4 quadrilaterals e

Q^H – space of piecewise constant functions on Ω^H

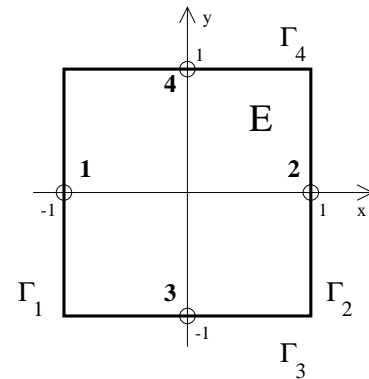
$\{\phi_i\}_{i=1}^4 = \{\varphi_i \circ \psi_e^{-1}\}_{i=1}^4$ define basis of V^h , where $\psi_e : E \rightarrow e$ for $e \in \Omega^h$

↓ non-conforming quadrilateral elements

$$\begin{pmatrix} K_{11} & K_{12} \\ K_{21} & K_{22} \end{pmatrix} \begin{pmatrix} u_1^h \\ u_2^h \end{pmatrix} = \begin{pmatrix} f_1^h \\ f_2^h \end{pmatrix}$$

GOAL: Scalable Parallel Preconditioner

Nodal Basis Functions $\varphi_i(x, y)$, $\varphi_i \in S_p$



Reference element E

$$S_p = \text{span}\{1, x, y, x^2 - y^2\}$$

Two variants of interpolation operators:

I. MP - mid-point

$$\varphi_i(j) = \delta_{ij}, \quad i, j = 1, \dots, 4$$

$$\varphi_1(x, y) = \frac{1}{4}(1 - 2x + x^2 - y^2)$$

$$\varphi_2(x, y) = \frac{1}{4}(1 + 2x + x^2 - y^2)$$

$$\varphi_3(x, y) = \frac{1}{4}(1 - 2y + y^2 - x^2)$$

$$\varphi_4(x, y) = \frac{1}{4}(1 + 2y + y^2 - x^2)$$

II. MV - integral mid-value

$$\frac{1}{|\Gamma_j|} \int_{\Gamma_j} \varphi_i = \delta_{ij}, \quad i, j = 1, \dots, 4$$

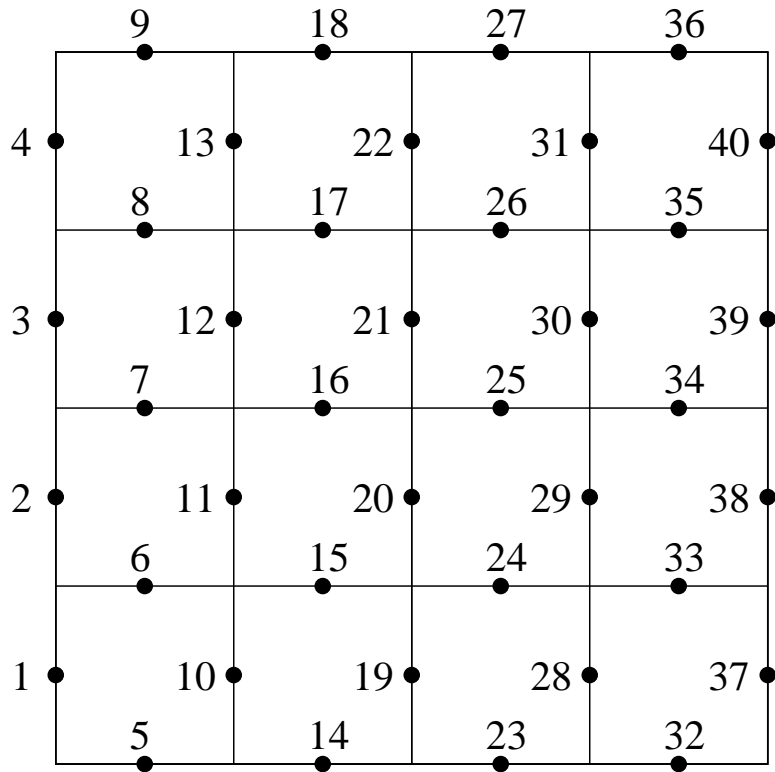
$$\varphi_1(x, y) = \frac{1}{8} - \frac{1}{4}x + \frac{3}{16}(x^2 - y^2)$$

$$\varphi_2(x, y) = \frac{1}{8} + \frac{1}{4}x + \frac{3}{16}(x^2 - y^2)$$

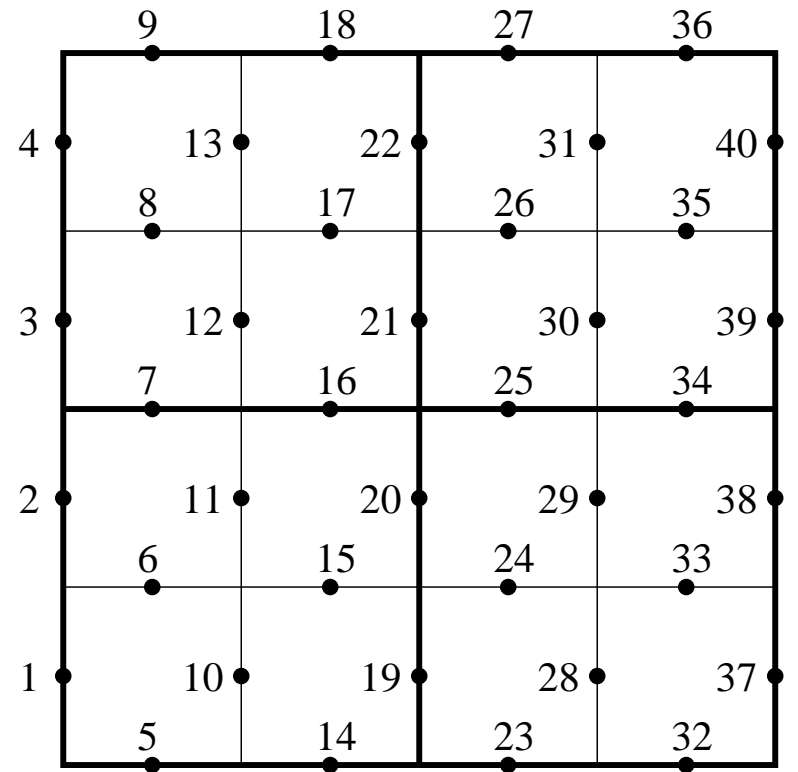
$$\varphi_3(x, y) = \frac{1}{8} - \frac{1}{4}y + \frac{3}{16}(y^2 - x^2)$$

$$\varphi_4(x, y) = \frac{1}{8} + \frac{1}{4}y + \frac{3}{16}(y^2 - x^2)$$

Standard Mesh and Ordering

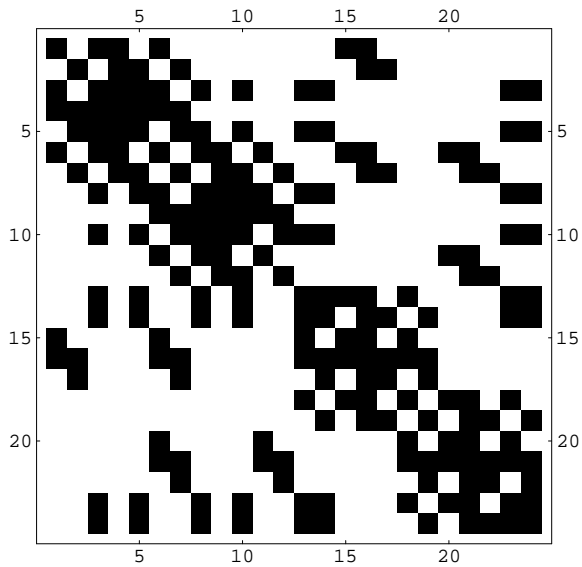


Ω^h

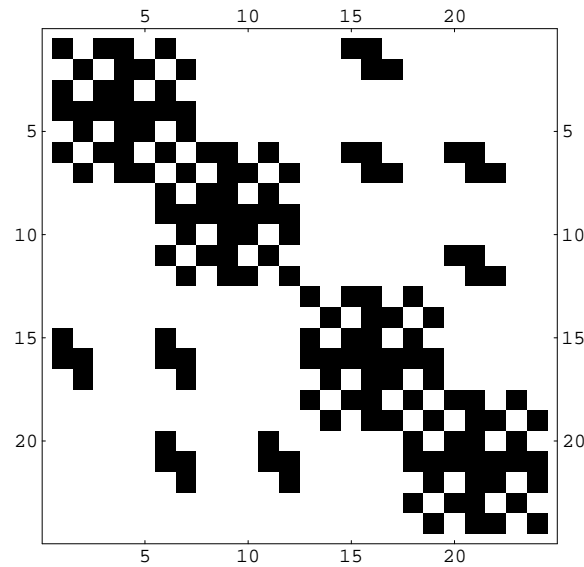


Ω^H

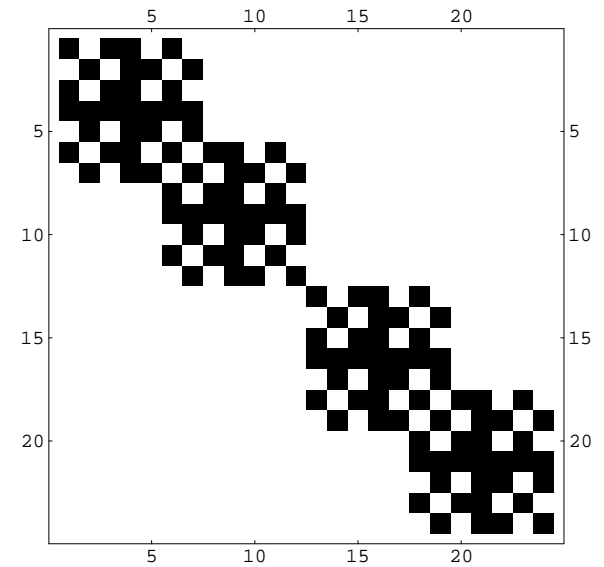
Macroelement Stiffness Matrix



$K_{\mathcal{E}}$



$K_{\mathcal{E}} - I_{\mathcal{E}}^Q$



$A_{\mathcal{E}}$

Preconditioning Strategy

1) Isotropic displacement decomposition $\begin{pmatrix} K_{11} & K_{12} \\ K_{21} & K_{22} \end{pmatrix} \rightarrow \begin{pmatrix} A & \\ & A \end{pmatrix}$,
where A corresponds to the bilinear form

$$a(u^h, v^h) = \sum_{e \in \Omega^h} \int_e E \left(\sum_{i=1}^2 \frac{\partial u^h}{\partial x_i} \frac{\partial v^h}{\partial x_i} \right) de$$

2) Locally modified approximation B of A :

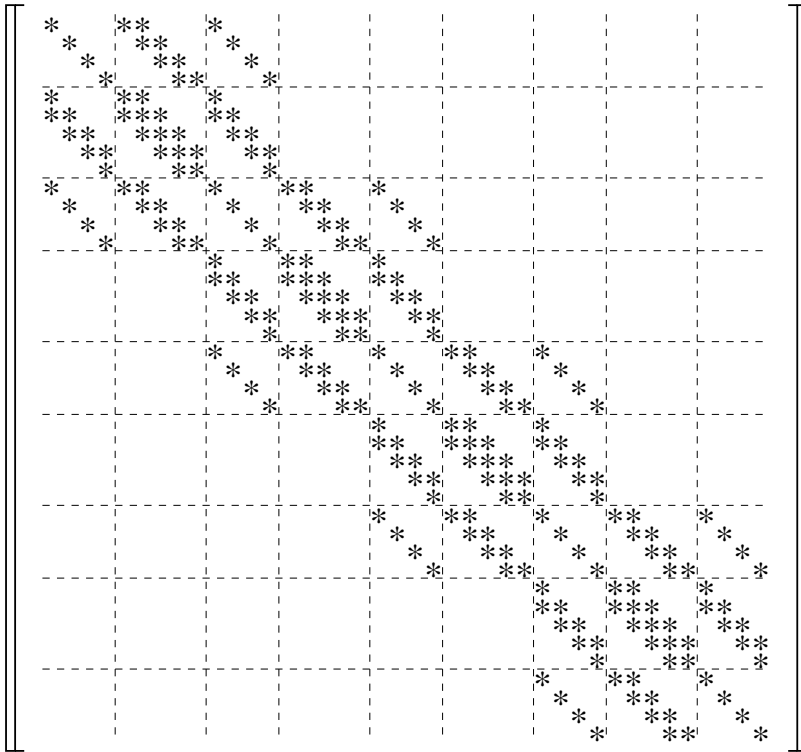
- a) a stable MIC(0) factorization;
- b) scalable parallel implementation;

3) MIC(0) factorization of B : $C_{MIC(0)}(B) = (X - L)X^{-1}(X - L)^t$

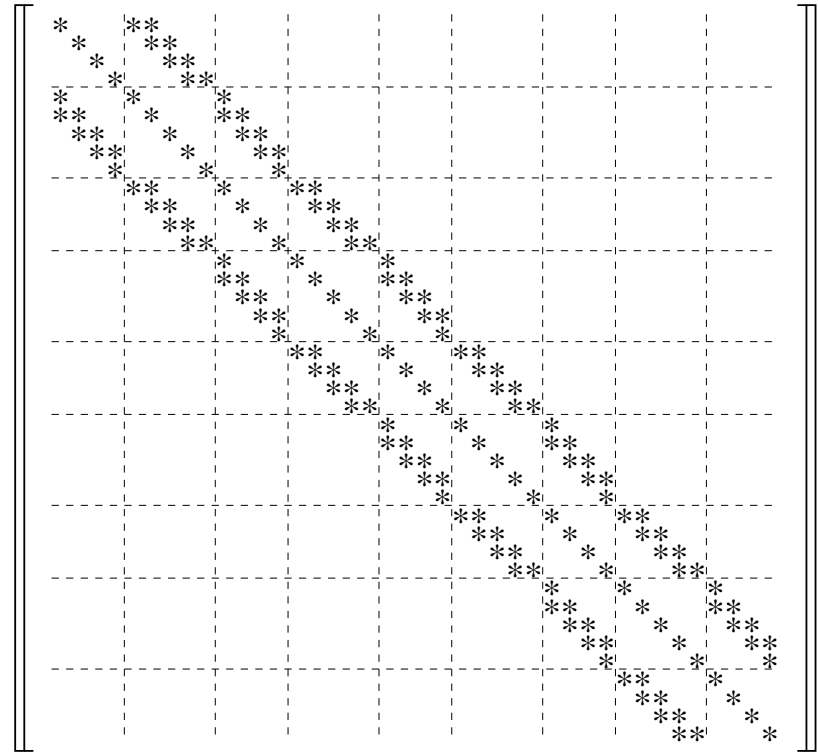
↓

PCG for K with preconditioner $\mathcal{C} = \begin{pmatrix} C_{MIC(0)}(B) & \\ & C_{MIC(0)}(B) \end{pmatrix}$

Structure of the Matrices A and B



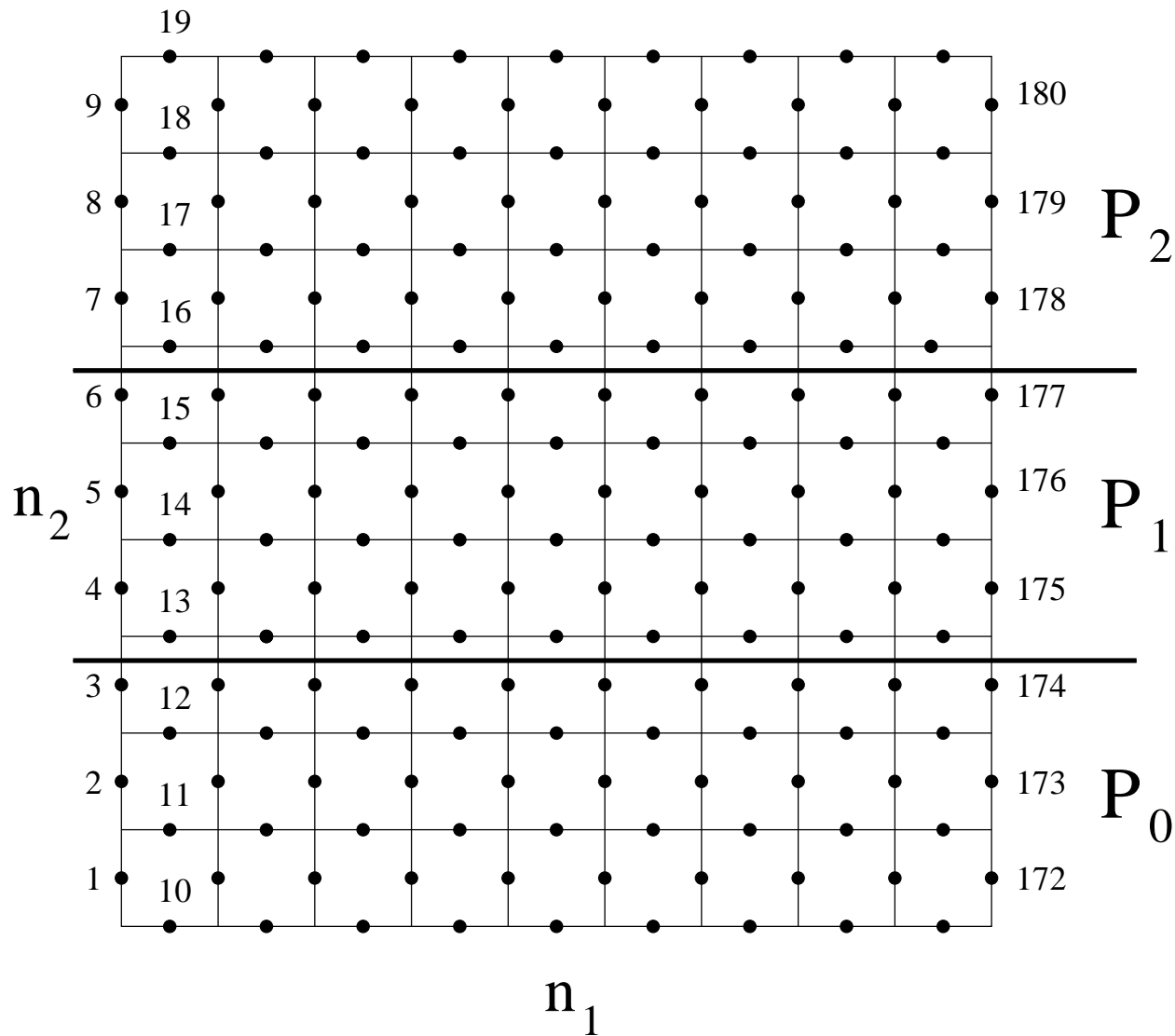
A



B

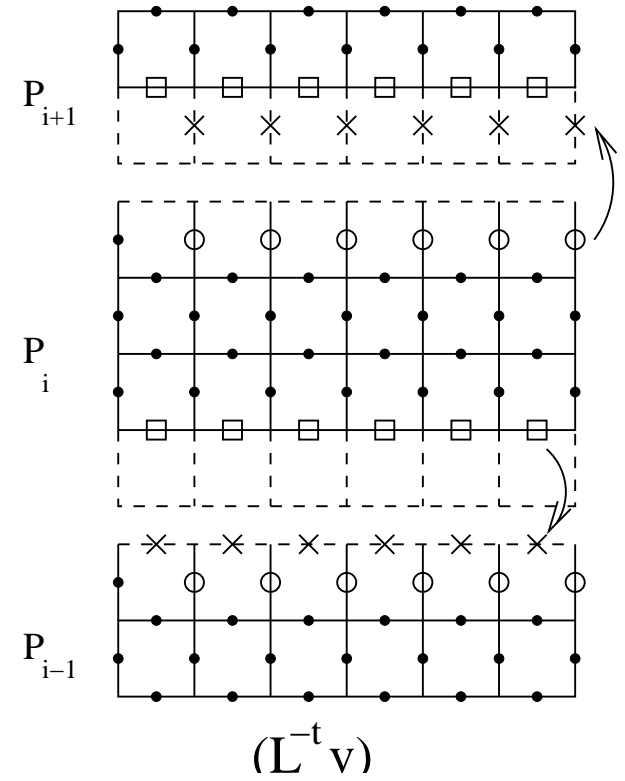
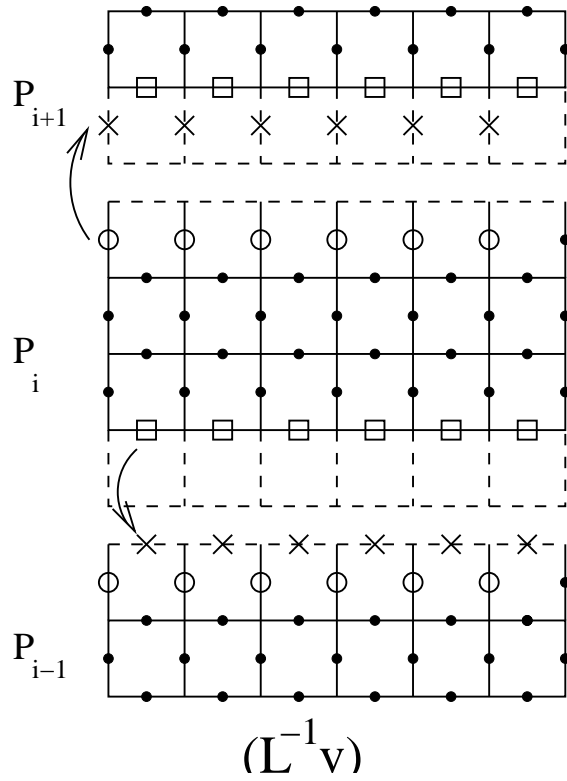
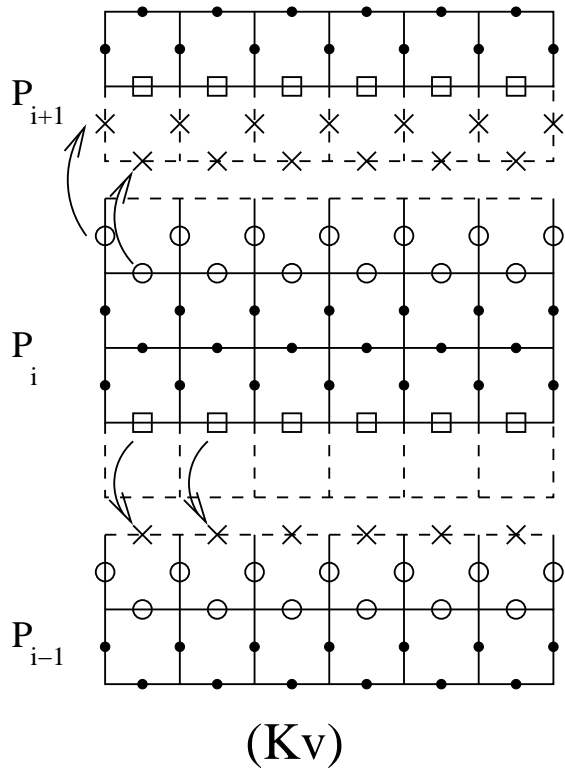
Parallel Implementation

Data Partitioning



$$N = 2(n_1(2n_2 + 1) + n_2), \quad NP = 3, \quad n_1 = 9, \quad n_2 = 9,$$

Communications



Parallel Complexity

Each PCG iteration:

- 1 solution of system with $C_{N \times N}$ ($\approx 11N/NP$ a. o.)
- 1 matrix vector multiplication with $K_{N \times N}$ ($\approx 37N/NP$ a. o.)
- 2 inner products ($4N/NP$ a. o.)
- 3 linked vector triads $\mathbf{v} := \alpha\mathbf{v} + \mathbf{u}$ ($6N/NP$ a. o.)

$$n_1 = n_2 = n, \quad N = 4n(n + 1)$$

$$T_a = M.t_a \text{ (no vectorization) }, \quad T_{com} = l(t_s + M.t_w),$$

$$T_a^{it} = 58 \frac{N}{NP}.t_a, \quad T_{com}(in.pr.) = T(bcast, 1) + T(gather, 1)$$

$$T_{com}(C^{-1}\mathbf{v}) = 8n(t_s + t_w), \quad T_{com}(K\mathbf{v}) = 2t_s + (6n + 1)t_w$$

$$T_{NP}^{it} = T_a^{it} + T_{com}^{it} \approx 58 \frac{4n(n+1)}{NP}.t_a + 8n.t_s + 14n.t_w$$

$$\text{Parallel PCG/MIC}(0), S_{NP} = \frac{T_1}{T_{NP}}, E_{NP} = \frac{S_{NP}}{NP}$$

Algorithm MP					Algorithm MV				
$\frac{n}{iter}$	NP	cpu	S_{NP}	E_{NP}	$\frac{n}{iter}$	NP	cpu	S_{NP}	E_{NP}
<u>128</u> 49	1	2.76			<u>128</u> 56	1	3.15		
	2	1.81	1.52	0.76		2	1.95	1.62	0.81
	4	3.09	0.89	0.22		4	3.52	0.89	0.22
	8	3.54	0.78	0.10		8	4.06	0.78	0.10
<u>256</u> 71	1	16.74			<u>256</u> 81	1	19.09		
	2	10.73	1.56	0.78		2	12.24	1.56	0.78
	4	11.71	1.43	0.36		4	13.32	1.43	0.36
	8	10.92	1.53	0.19		8	12.93	1.48	0.19
<u>512</u> 104	1	99.42			<u>512</u> 119	1	113.45		
	2	63.69	1.56	0.78		2	73.00	1.55	0.78
	4	50.22	1.98	0.50		4	57.66	1.97	0.49
	8	37.74	2.63	0.33		8	42.51	2.67	0.33
<u>1024</u> 148	1	577.00			<u>1024</u> 167	1	635.63		
	2	373.19	1.55	0.78		2	409.39	1.55	0.78
	4	233.55	2.47	0.62		4	264.88	2.40	0.60
	8	171.28	3.37	0.42		8	175.63	3.62	0.45