

ЮБИЛЕЙНА НАУЧНА СЕСИЯ

„100 ГОДИНИ ОТ РОЖДЕНИЕТО НА АКАДЕМИК ЛЮБОМИР НИКОЛОВ ЧАКАЛОВ“

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A NONLOCAL MAXIMUM PRINCIPLE FOR THE BIHARMONIC EQUATION, ALMANSI TYPE FORMULAE FOR OPERATORS WHICH ARE SQUARES OF ELLIPTIC OPERATORS OF SECOND ORDER AND APPROXIMATION BY THEIR SOLUTIONS

Ognyan I. Kounechev

A maximum principle of constructive type is proved using only the values of the biharmonic function. An analogue of the Almansi formula for some operators of a specific structure is proved. Some qualitative properties of the element of the best approximation by solutions of these equations are investigated.

A biharmonic function in Ω is a 4-differentiable solution of the equation $\Delta^2 u(x) = 0, u(x) \in C^4(\Omega)$, where $\Delta = \sum_{i=1}^n \partial^2/\partial x_i^2$ is the Laplace operator. We denote the set of all such functions by $H_2(\Omega), \Omega \subset \mathbb{R}^n$.

It was proved by Almansi [1] that under certain conditions on Ω (see [2]) a function $u(x) \in H_2(\Omega)$ can be represented by two functions $\varphi_j(x), j = \bar{0}, 1$ harmonic in Ω in the following way

$$(1) \quad u(x) = \varphi_0(x) + x_j \varphi_1(x), \quad x \in \bar{\Omega}.$$

In the case of a starlike domain Ω (see [3]) with respect to O there is a representation of the form

$$(2) \quad u(x) = \varphi_0(x) + |x|^2 \varphi_1(x), \quad x \in \bar{\Omega},$$

here $|x|^2 = \sum_{i=1}^n x_i^2$ and $\varphi_0(x), \varphi_1(x)$ are harmonic in Ω .

Further by $B(x_0; R)$ we denote the ball $\{x \in \mathbb{R}^n, |x - x_0| \leq R\}$ with centre x_0 and radius R ; if G is a set in \mathbb{R}^n then \bar{G} and G° denote respectively its closure and interior.

Theorem 1. Let $\varphi(x) \in H_2(\Omega)$ be a biharmonic function in the convex domain Ω in \mathbb{R}^n . If $B(x_0; R) \subset \Omega$ and $\bar{G} \subset \bar{B}(x_0; R)$ for some $x_0 \in \Omega$ and a regular domain G (44) then there exist two constants C_1, C_2 such that

$$(3) \quad \|\varphi\|_{\bar{G}} \leq C_1 \|\varphi\|_{\partial B} + C_2 \|\varphi\|_{\partial G}.$$

Here $\|\varphi\|_{\bar{G}} = \max_{x \in \bar{G}} |\varphi(x)|$ and similarly for the restrictions $\varphi|_{\partial B}$ and $\varphi|_{\partial G}$ of $\varphi(x)$, $\|\cdot\|_{\partial B}$ and $\|\cdot\|_{\partial G}$ denote the uniform norms.

Proof. Since Ω is starlike with respect to any point $x_0 \in \Omega$ using (2) we obtain the following representation

$$(4) \quad \varphi(x) = \varphi_0(x) + |x - x_0|^2 \varphi_1(x), \quad x \in \Omega$$

for an arbitrary function $\varphi(x) \in H_2(\Omega)$.

Let us denote by K the operator which maps the Dirichlet boundary

data on ∂B into the harmonic function having these data, i.e. if $f(x) \in C(\partial B)$ then $\Delta K[f](x) = 0$ and $K[f]|_{\partial B} = f(x)$ (see [4]). Similar operator for the domain G exists [4] and we shall denote it by L .

For $x \in \partial B$ we have $\varphi(x) = \varphi_0(x) + R^2 \varphi_1(x)$. Applying the operator K to (4) we obtain

$$(5) \quad \varphi|_{\partial G} = (K[\varphi|_{\partial B}] - \varphi|_{\partial G}) \cdot (R^2 - |x - x_0|^2)^{-1} \\ \varphi_0|_{\partial G} = \varphi|_{\partial G} - (K[\varphi|_{\partial B}] - \varphi|_{\partial G}) \cdot (R^2 - |x - x_0|^2)^{-1} \cdot |x - x_0|^2.$$

On the other hand, for $x \in G$ we have

$$\varphi(x) = L[\varphi_0|_{\partial G}] + |x - x_0|^2 L[\varphi_1|_{\partial G}],$$

and $|x - x_0| < R$ according to the inclusion $\bar{G} \in \bar{B}$.

Since $\varphi_0|_{\partial G}$ and $\varphi_1|_{\partial G}$ are given by formulae (5) and the operators K and L satisfy the usual maximum principle [4]:

$$\|Kf\|_{\bar{B}} \leq \|f\|_{\partial B}, \quad \|Lf\|_{\bar{G}} \leq \|f\|_{\partial G} \quad \text{we easily obtain the estimate} \\ (3) \text{ with } C_1 = 2M\delta^{-1} \text{ and } C_2 = 1 + 2M\delta^{-1}; \text{ here } M = \max_{x \in G} |x - x_0|, \\ \delta = \min_{x \in G} (R^2 - |x - x_0|^2) \text{ Q.E.D.}$$

Let us note that (3) implies uniqueness of the solution of the nonlocal problem

$$(6) \quad \varphi|_{\partial B} = f_1(x), \quad x \in \partial B; \quad \varphi|_{\partial G} = f_2(x), \quad x \in \partial G.$$

Using formulae (1), an estimate similar to (3) can be proved when B is replaced by a half space.

It is very probable that estimates of type (3) could be proved when B is replaced by more general domains for which problem (6) has a unique solution.

We saw that the Almansi formulae are useful for obtaining qualitative information concerning the biharmonic functions. Similar formulae for operators of the form $Q(D_x) = \sum_{i,j=1}^n a_{ij} \partial^2/\partial x_i \partial x_j$ is a second order elliptic operator with constant coefficients are established in the following:

Theorem 2. Let $\varphi(x) \in C^4(\mathbb{R}^n)$ be a solution of the equation

$$Q^2(D_x) \varphi(x) = 0 \text{ satisfying the condition } U(x) = O(|x|) \text{ for large } |x| \text{ (see [5]).} \\ \text{Then } \varphi(x) \text{ can be represented in the following way:}$$

$$(7) \quad \varphi(x) = \varphi_0(x) + x_j \varphi_1(x), \quad x \in \mathbb{R}^n,$$

where $\varphi_0(x), \varphi_1(x)$ are solutions of the equation $Q\varphi_0(x) = Q\varphi_1(x) = 0, x \in \mathbb{R}^n = \{x \in \mathbb{R}^n, x_j \geq 0\}$.

Proof. To prove this we shall use the Poisson kernels in the half-space [5], denoting x_j by t and working in \mathbb{R}^{n+1} where we shall prove formula (7).

Let $\varphi_0(x)$ be the solution of the following boundary value problem

$$(8) \quad Q\varphi_0(x, t) = 0, (x, t) \in \mathbb{R}_+^{n+1} (t \geq 0); \quad \varphi_0(x, t) = f(x), \quad t = 0.$$

It is given by formula (2.3) in [5].

According to [5] for the operator $Q^2(D_x)$ we have:

$$m = 2, \quad L = (Q(\xi, \tau))^2, \quad Q = (\tau - \tau^+ (\xi)) (\tau - \tau^-(\xi));$$

$$M^+ = (\tau - \tau^+(\xi))^2 = \tau^2 - 2\tau\tau^+ + (\tau^+)^2;$$

$$B_1 = 1, m_1 = 0; B_2 = \tau, m_2 = 1, \theta_{ij} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$M_1^+ = \tau - 2\tau^+, M_0^+ = 1,$$

and which gives $N_1 = \tau - 2\tau^+, N_2 = 1$.

Solution of the boundary value problem

$$Q^2(Dx, Dt)\varphi(x, t) = 0, (x, t) \in R^{n+1}$$

$$(9) \quad \varphi(x, 0) = 0, \varphi(x, 0) = f(x), x \in R^n$$

is given by formula (2.3) in [5]:

$$(10) \quad \varphi(x, t) = \int K_2(x-y, t) f(y) dy,$$

where simple calculations show that

$$K_2(x, t) = G_1 \int_{|\xi|=1} \frac{d\omega_\xi}{\rho^2} \left(\int_{|\xi|=1} \frac{d\tau}{\rho^2} \frac{d\omega_\xi}{\rho^2} \right)$$

Here $d\omega_\xi$ denotes the surface element of the unit sphere and ρ is a Jordan curve in the half-plane $Im\tau > 0$ which contains all zeros of the polynomial $M^+(\xi, \tau)$ for $\xi \in R^n$ with $|\xi|=1$

Calculation of the integral over ρ gives

$$K_2(x, t) = G_2 \int_{|\xi|=1} \frac{d\omega_\xi}{(\tau - \tau^+(\xi))^2}$$

In the same way we find the Poisson kernel for Q :

$$m=1, L = Q(\xi, \tau) = (\tau - \tau^+(\xi))(\tau - \tau^-(\xi)),$$

$$M^+ = \tau - \tau^+(\xi), B_1 = 1, m_1 = 0, (\theta_{ij}) = 1$$

$$M_0^+ = 1, N_1 = 1,$$

which gives (for Q) the kernel:

$$K_1(x, t) = G_3 \int_{|\xi|=1} \frac{d\omega_\xi}{(\tau - \tau^+(\xi))(\tau - \tau^-(\xi))} = G_3' \int_{|\xi|=1} \frac{d\omega_\xi}{(x\xi + t\xi^2)^n}$$

Evidently $K_2 = G.t.K_1$.

The representation (7) follows through formula (2.3) in [5] since (10) becomes

$$\varphi(x, t) = G.t. \int K_1(x-y, t) f(y) dy,$$

where the integral solves a boundary value problem of the form (8), Q.E.D.

Here we restricted ourselves to the case of a half-space so that we could freely use the formulae of [5] but similar formulae of the Almansi type can be proved for a wider class of domains [2]. For the solutions of the equation in (9) it is possible to prove a nonlocal maximum principle like theorem 1 for the half-space applying formula (7).

Next we apply some arguments used in the proof of Theorem 1 to demonstrate a partial case of the criterion for the element of the best uniform approximation by polyharmonic functions ([6]).

Consider the following approximation problem

$$(11) \quad \|\varphi - f\| = \sup_{x \in \Omega} | \varphi(x) - f(x) | \rightarrow \inf_{\varphi \in N} (\epsilon = \delta),$$

where the set of biharmonic functions N is such that the problem has a solution (see e.g. 7) $f(x) \in C(\bar{\Omega})$.

Denote by T the set of "critical points":

$$T = T(\varphi) = \{x \in \bar{\Omega}; \|\varphi - f\| = |\varphi(x) - f(x)|\}$$

Theorem 3. Let the set $T(\varphi)$ contain the sphere $\partial B(x_0; R)$, the boundary $\partial\bar{G}$ of a regular domain $\bar{G} \subset \bar{B}(x_0; R)$ and also $x_0 \in T$, so that the following "alternance" relations hold:

$$(12) \quad \varphi(x) - f(x) = \epsilon\delta, x \in \partial B(x_0; R);$$

$$(13) \quad \varphi(x) - f(x) = -\epsilon\delta, x \in \partial\bar{G};$$

$$(14) \quad \varphi(x_0) - f(x_0) = \epsilon\delta', \text{ where } \epsilon = \pm 1.$$

Then $\varphi(x)$ is the element of best approximation in problem (11).

Proof. Let us suppose, for the sake of simplicity, that $x_0 = 0, R=1$ and $\epsilon = +1$.

If the function $\varphi(x) \in N$ is such that $\|\varphi - f\| < \|\varphi - f\|$ then for the function $\psi(x) = \varphi(x) - \varphi(x)$ relations (12-14) imply:

$$(15) \quad \psi(x) > 0, x \in \partial B(0; 1);$$

$$(16) \quad \psi(x) < 0, x \in \partial\bar{G};$$

$$(17) \quad \psi(0) > 0.$$

For $\psi(x)$ we have the Almansi representation in $B(0; 1)$ $\psi = \psi_0(x) + |x|^2 \psi_1(x)$ with harmonic functions $\psi_0(x), \psi_1(x)$.

Applying the positive operator K to (15), (16) gives the inequality $\psi_0(x) + |x|^2 \psi_1(x) < 0 < \psi_0(x) + \psi_1(x), x \in \partial\bar{G}$. Since $|x| < 1, x \in \partial\bar{G}$, this implies

$$(18) \quad \psi_1(x) > 0, x \in \partial\bar{G},$$

and (16) implies:

$$(19) \quad \psi_0(x) < 0, x \in \partial\bar{G}.$$

Since the operator L is positive, (19) gives $\psi_0(0) < 0$ which contradicts (17).

This contradiction proves that $\varphi(x)$ is the best uniform approximation of $f(x)$, Q.E.D.

Similar theorem can be proved for operators of the type \mathcal{L}^m considered in Theorem 2. In that case the set T contains $m-1$ concentric spheres, $\partial\bar{G}$ and the centre of the spheres x_0 .

For the approximation by n -harmonic functions φ (i.e. $\Delta^n \varphi(x) = 0, x \in \bar{\Omega}$) in the problem (11) we have the following

Corollary. Let a continuous in the unit ball $B(0; 1)$ function $f(x)$ be rotationally symmetric, i.e. $f(x) = f(|x|)$. Then the n -harmonic function $\varphi(x)$ which is the element of best uniform approximation of $f(x)$ by n -harmonic functions (solving the problem (11)) has the form $\varphi(x) = P_{n-1}(|x|^2)$ where the polynomial $P_{n-1}(t)$ is the element of the best uniform approximation

of function $f(\sqrt{x})$ in the interval $[0, 1]$ by polynomials of degree less than or equal to $n-1$.

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НЕПОКАЛЕН ПРИНЦИП ЗА МАКСИМУМА ЗА БИХАРМОНИЧНИ ФУНКЦИИ,
 ФОРМУЛА НА АЛМАНЗИ ЗА ОПЕРАТОРИ, КОИТО СА КВАДРАТИ НА
 ЕЛИПТИЧНИ ОПЕРАТОРИ ОТ ВТОРИ РЕД И АПРОКСИМАЦИЯ С РЕШЕНИЯТА ИМ

Отгнн И. Кунчев

Обоснован е един критерий за елемента на най-доброто приближение с бихармонични функции в равномерно метрика. Технически това е свързано с формулата на Алманзи и с един непокален принцип за максимума за бихармонични функции. Резултатите се обобщават и в случая на диференциални оператори, които са степени на елиптични оператори от втори ред с постоянни коефициенти, в частност полихармонични.

СОФИЙСКИ ОКРЪТ НАРОДЕН СЪВЕТ • СЪЮЗ НА МАТЕМАТИЦИТЕ В БЪЛГАРИЯ
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ДОЛНА ГРАНИЦА ЗА РАЗМЕРА НА НОСИТЕЛЯ НА
 БАЛАНСИРАНИ НЕПЪЛНИ ОЛЮК-ДИЗАЙНИ

Иван Н. Данджев

В статията се дава подобрение на оценката на Фули и Хедаят за размера на носителя на балансиран непълен олюк-дизайн с повтарещи се олюкове.

1. Въведение. Комбинаторните понятия и означения, използвани в настоящата статия, са съгласувани с тези от книгата на Гончев [1]. Дефиницията на t -дизайн допуска появата на повтарещи се олюкове. Множеството от различните олюкове в даден дизайн \mathcal{D} ще означим с \mathcal{D}^* и ще наричаме носител на дизайна. Мощността на носителя ще означим с δ^* и ще наричаме размер на носителя. За $t = (v, k, \lambda)$ -дизайн с размер на носител δ^* ще използваме означението $t = (v, k, \lambda | \delta^*)$. Дизайн \mathcal{D} , за който $\delta^* < \delta$, ще наричаме дизайн с повтарещи се олюкове. Ако даден олюк се повтаря s пъти в \mathcal{D} , ще го наричаме s -олюк. За всеки олюк-дизайн, съдържащ s -олюк, е в сила неравенството на Ман [4]:

$$(1.1) \quad \delta \geq s \cdot v$$

По-нататък ще разглеждаме само олюк-дизайни. За произволни v, k и λ с δ_{min}^* ще означим най-малкото δ^* , за което съществува $2 = (v, k, \lambda | \delta^*)$ -дизайн. В [2] Фули и Хедаят дават следната оценка за δ_{min}^* :

$$(1.2) \quad \delta_{min}^* \geq \left\lceil \frac{v}{k} \left\lceil \frac{v-1}{k-1} \right\rceil \right\rceil,$$

където $\lceil a \rceil$ е горната цяла част на a .

Цел на настоящата статия е подобряването на този резултат. Нека с m_i^* означаваме максималното число, за което съществува $2 = (v, k, \lambda | \delta^*)$ -дизайн с $\delta^* = i$, съдържащ m_i^* различни λ -олюка. Ако за $\delta^* = i$ не съществува $2 = (v, k, \lambda | \delta^*)$ -дизайн, $m_i^* = 0$. Сета нека

$$m^* = \max_{1 \leq i < \delta} m_i^*.$$

В настоящата статия е показано, че

$$(1.3) \quad \delta_{min}^* \geq 2 \left(\frac{v}{k} \right) - m^*.$$

Дадена е горна оценка за m^* , която след заместване в (1.3) води до по-сил-