

AN APPLICATION OF THE SKEW-SYMMETRIC
STANILOV CURVATURE OPERATOR IN THE CLASSICAL
EGOLOGY*

Vesselin Videv, Marija Stoeva, Yordan Stajkov

The main result in this paper is that locally sprays of the Hamilton systems are distincts from the ecologically point of view if and only if a population space (M, g) is SB population space.

1. Introduction. Let (M, g) be an n -dimensional Riemannian manifold. Fixing a point $p \in M$, we can always consider the tangent space M_p to the manifold M , at this point p . If M is a Riemannian manifold and if ∇ is the Levi-Civita connection on M , then we can consider the curvature tensor R in M_p , which is a four-linear mapping satisfying the following properties:

$$(1) \quad \begin{aligned} R(x, y, z, u) &= -R(y, x, z, u), \quad R(x, y, z, u) = -R(x, y, u, z), \\ R(x, y, z, u) + R(y, z, x, u) + R(z, x, y, u) &= 0, \end{aligned}$$

Using these properties of R , we can define some curvature operators in the vector space M_p for example Jacobi operator, Stanilov operators and e.t.c.[1]. In the present note we will use one of the Stanilov curvature operators namely a skew-symmetric linear operator in the tangent space M_p , at a point $p \in M$, defined by $S(E^2)(u) = R(X, Y, u)$, where X, Y is an orthonormal basis in the plane $E^2 \subseteq M_p$ [2]. It is easy to see that this operator is invariant under all orthogonal transformations in E^2 . The theory of this operator started by Stanilov and Ivanova which investigated four-dimensional Riemannian manifolds with a pointwise constants eigenvalues of the curvature operator $S(E^2)$, for arbitrary plane $E^2 \subseteq M_p$, at any point $p \in M$ [2]. The classes of such manifolds are called Stanilov(S) manifolds as afterwards Gilkey, Leahy, and Sadofsky proved that *any n -dimensional Riemannian S -manifold is a space with a structure of almost product P , and with a curvature tensor R of the form* [1], [3]

$$(2) \quad R(x, y, z) = g(Py, x)Pz - g(Px, z)Py.$$

We provided in Lorentzian setting analogous investigations when $\dim M = 4$, supposing that in any cases the plane E^2 is not isotropic plane. We proved

*Partially supported under contract MM 809, NFSI(Bulgaria).

Keywords. Population space, spray-curvature tensor, Voltera-Hamilton system, Stanilov curvature operator, pointwise conditions SB spaces.

MSC. 92940, 53B

Theorem 1 [4]. *Let (M, g) be a four-dimensional Lorentzian manifold with pointwise constant eigenvalues of the Stanilov curvature operator $S(E^2)$, for arbitrary non-isotropic plane E^2 , at arbitrary point $p \in M$. Then (M, g) is a Lorentzian space of a constant sectional curvature, or (M, g) is a Lorentzian space of maximal mobility with metric (in a special coordinate system) of the form*

$$(3) \quad ds^2 = -sh^2 x_4 dx_2^2 - \sin^2 x_4 dx_3^2 + 2dx_1 dx_4.$$

2. Population spaces and Stanilov curvature operator. Let (M, g) be a population space considered as a Riemannian manifold, and let (x_i, N^i) denote the natural coordinates in a linear chart of the tangent bundle TM^n . We consider the Voltera-Hamilton systems of differential equations:

$$(4) \quad \begin{aligned} \frac{dx^i}{dt} &= k_{(i)} N^i \quad (\text{not summed}), \\ \frac{dN^i}{dt} &= -G_{jk}^i N^j N^k + r_j^i N^j + e^i, \end{aligned}$$

with all coefficients possibly depend on x^i, N^i, t , the quantities G_{ij}^k being n^3 functions homogenous of degree zero in N^i , and with a smooth initial conditions x_0^i, N_0^i, t_0 . The coordinates x^i are Voltera production's variables whose constant per capita rate of increase is $k(i)$, while the second system of equations is a description of how different species population, $N^i \geq 0$, growth r_i^j , interact G_{ij}^k and react e^i to the external environment (and may be noisy). For almost two decades these systems (of 2nd order) has played the major role in the modelling ecology and evolution of colonial organisms, which may involve chemical warfare when G_{ij}^k depend explicitly on x^i , and social interactions, when G_{ij}^k depend on ratio of population densities N^i/N_j [5]. Our natural geometrical approach starts from the second order system of differential equations, obtained from (4) by $e^i = 0$ and $r_i \lambda \delta_i^j$, where λ is a constant. Then we have the local spray

$$(5) \quad \frac{d^2 x^i}{ds^2} + G_{jk}^i \frac{dx^j}{ds} \frac{dx^k}{ds} = 0,$$

where $ds = e^{\lambda t} dt$ and make use of the local spray connection

$$(6) \quad G_j^i = \nabla_j G^i,$$

and the linear connection

$$(7) \quad G_{jk}^i = \nabla_k G_j^i.$$

If all interaction coefficients G_{jk}^i are zero, then we say that the spray has straight line form. The spray curvature tensor(operator) B of type (1,3), defined from Berwald [5], was defined as

$$(8) \quad B_{hjk}^i = \nabla_k G_{hj}^i + G_{hj}^r G_{rk}^i + G_j^r D_{rhk}^i - (\nabla_j G_{hk}^i + G_{hk}^r G_{rj}^i + G_k^r D_{rhj}^i),$$

where D is the sectional curvature, of the corresponding to B tensor of type (0,4). Following some result in [5] we can formulate

Theorem 2. *The spray curvature operator B can be transformed into straight-line form via smooth coordinate changes if and only if the eigenvalues of this operator are equal to zero.*

Using the spray curvature tensor B we can define a skew-symmetric linear *spray*

curvature operator $SB(E^2)u = B(x, y, u)$, where x, y is an orthonormal basis in the tangent space M_p , at the point p , of the population space M . We define the corresponding to B Ricci tensor ρ , by $\rho(x, y) = \text{trace}(u \rightarrow B(u, x, y))$, $x, y, u \in M_p, p \in M$.

Definition 1. We say that population space (M, g) is spray-Einstein population space if $\rho(x, y) = kg(x, y)$, where k is a constant, $x, y \in M_p$, and $p \in M$ is an arbitrary point. We say that (M, g) is SB Stanilov-Berwald) population space if the eigenvalues of the curvature operator $SB(E^2)$ don't depend on the plane $E^2 \subset M_p$, at any point $p \in M$.

3. An ecological problem and characterization of the four-dimensional Lorentzian SB population spaces. A Riemannian manifold (M, g) is called Lorentzian manifold if at any point $p \in M$, the tangent space M_p is equipped with inner product g of a signature $(-, +, \dots, +)$ or $(+, +, \dots, +, -)$. A tangent vector X is called spacelike or timelike if $g(X, X) = 1$ or $g(X, X) = -1$. The set of all timelike tangent vectors in M_p we denote by ^-S_pM , respectively the set of all spacelike tangent vector in M_p we denote by ^+S_pM . As in the Riemannian setting, we define second exterior product $\wedge^2(M_p)$, which is a 6-dimensional vector space, such that

$$(9) \quad P_1 = e_1 \wedge e_2, P_2 = e_1 \wedge e_3, P_3 = e_1 \wedge e_4, P_4 = e_2 \wedge e_3, P_5 = e_2 \wedge e_4, P_6 = e_3 \wedge e_4,$$

formed an orthonormal basis in $\wedge^2(M_p)$, for any orthonormal Lorentzian basis e_1, e_2, e_3, e_4 ($e_4 \in ^-S_pM$) in $M_p, p \in m$. It was proved

Theorem 3 [6]. Let (M, g) be a four-dimensional Einstein Lorentzian manifold. Then at any point $p \in M$, there exists a Lorentzian basis e_1, e_2, e_3, e_4 ($e_4 \in ^-S_pM$) in M_p , such that the matrix of the curvature operator \mathcal{R} in $\wedge^2(M_p)$, with respect to the orthonormal basis (9), has the form $\begin{pmatrix} M & N \\ -N & M \end{pmatrix}$, where the matrix M and N must be of one of the following types:

$$\begin{aligned} \text{I.} \quad & M = \begin{pmatrix} \alpha_1 & 0 & 0 \\ 0 & \alpha_2 & 0 \\ 0 & 0 & \alpha_3 \end{pmatrix}, N = \begin{pmatrix} \beta_1 & 0 & 0 \\ 0 & \beta_2 & 0 \\ 0 & 0 & \beta_3 \end{pmatrix}, \\ & \alpha_1 + \alpha_2 + \alpha_3 = \lambda, \quad \beta_1 + \beta_2 + \beta_3 = 0; \\ \text{II.} \quad & M = \begin{pmatrix} \alpha_1 & 0 & 0 \\ 0 & \alpha_2 + 1 & 0 \\ 0 & 0 & \alpha_2 - 1 \end{pmatrix}, N = \begin{pmatrix} \beta_1 & 0 & 0 \\ 0 & \beta_2 & 0 \\ 0 & 1 & \beta_2 \end{pmatrix}, \\ & \alpha_1 + 2\alpha_2 = \lambda, \quad \beta_1 + 2\beta_2 = 0, \\ \text{III.} \quad & M = \begin{pmatrix} \alpha & 1 & 0 \\ 1 & \alpha & 0 \\ 0 & 0 & \alpha \end{pmatrix}, N = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & -1 & 0 \end{pmatrix}, \quad 3\alpha = \lambda. \end{aligned}$$

Using (1) and (9) we can prove

Theorem 4. Let (M, g) be a four-dimensional spray-Einstein Lorentzian population space. Then at any point $p \in M$ there exists a Lorentzian basis e_1, e_2, e_3, e_4 ($e_4 \in ^-S_pM$) in M_p , with respect to which all components of the spray curvature tensor B can be expressed by only one of the following formulas:

$$(10) \quad B_{1212} = -B_{3434} = \alpha_1, \quad B_{1313} = -B_{2424} = \alpha_2, \quad B_{2323} = -B_{1414} = \alpha_3;$$

$$(11) \quad \begin{aligned} B_{1212} = -B_{3434} = \alpha_1, \quad B_{1313} = -B_{2424} = \alpha_2 + 1, \\ B_{2323} = -B_{1414} = \alpha_2 - 1, \quad B_{3114} = -B_{3224} = 1; \end{aligned}$$

$$(12) \quad \begin{aligned} B_{1212} = -B_{3434} = B_{1313} = -B_{2424} = B_{2323} = -B_{1414} = \alpha, \\ B_{3114} = -B_{3224} = 1, \quad B_{2443} = -B_{2113} = 1. \end{aligned}$$

Using this result we check that the characteristic equation of the curvature operator $SB(E^2)$, with respect to the Lorentzian basis $e_1, e_2, e_3, e_4 (e_4 \in^- S_p M)$, in the tangent space M_p , can be written in the form

$$\mu^4 - I_2(p; X, Y) \cdot \mu^2 - I_4(p; X, Y) = 0,$$

where

$$\begin{aligned} I_2(p; X, Y) &= B_{XY12}^2 + B_{XY13}^2 + B_{XY23}^2 - B_{XY14}^2 - B_{XY24}^2 - B_{XY34}^2, \\ I_4(p; X, Y) &= -(B_{XY12}B_{XY34} - B_{XY13}B_{XY24} + B_{XY23}B_{XY14})^2. \end{aligned}$$

Now following the methods in [4], we can obtain that if for B holds (10), then

$$(10.a) \quad \begin{aligned} I_2(p; e_1, e_2) = -I_2(p; e_3, e_4) = \alpha_1^2 - \beta_1^2, \quad I_2(p; e_1, e_3) = -I_2(p; e_2, e_4) = \alpha_2^2 - \beta_2^2, \\ I_2(p; e_2, e_3) = -I_2(p; e_1, e_4) = \alpha_3^2 - \beta_3^2; \quad I_4(p; e_1, e_2) = -I_4(p; e_3, e_4) = -\alpha_1^2\beta_1^2, \\ I_4(p; e_1, e_3) = -I_4(p; e_2, e_4) = -\alpha_2^2\beta_2^2, \quad I_4(p; e_2, e_3) = -I_4(p; e_1, e_4) = -\alpha_3^2\beta_3^2. \end{aligned}$$

From our hypothesis (M, g) to be SB population space, we have

$$(10.b) \quad \begin{aligned} I_k(p; e_1, e_2) = I_k(p; e_1, e_3) = I_k(p; e_2, e_3); \\ I_k(p; e_1, e_4) = I_k(p; e_2, e_4) = I_k(p; e_3, e_4), \quad k = (2, 4). \end{aligned}$$

Now from (10.a) and (10.b) we get $\alpha_1 = \beta_1 = \alpha_2 = \beta_2 = \alpha_3 = \beta_3$, which means that (M, g) is a space of constant sectional curvature.

Suppose for the components of the spray curvature tensor B holds (11). Then

$$(11.a) \quad \begin{aligned} I_2(p; e_1, e_2) = -I_2(p; e_3, e_4) = \alpha_1^2 - \beta_1^2, \\ I_2(p; e_1, e_3) = -I_2(p; e_2, e_4) = (\alpha_2 + 1)^2 - \beta_2^2 - 1, \\ I_2(p; e_2, e_3) = -I_2(p; e_1, e_4) = (\alpha_2 - 1)^2 - \beta_2^2 - 1; \\ I_4(p; e_1, e_2) = -I_4(p; e_3, e_4) = -\alpha_1^2\beta_1^2, \\ I_4(p; e_1, e_3) = -I_4(p; e_2, e_4) = -\beta_2^2(\alpha_2 + 1)^2, \\ I_4(p; e_2, e_3) = -I_4(p; e_1, e_4) = -\beta_2^2(\alpha_2 - 1)^2. \end{aligned}$$

From here and (10.b), we get that if (M, g) is SB population space, then $\alpha_1 = \beta_1 = \alpha_2 = \beta_2 = \alpha_3 = \beta_3 = 0$, which is necessary and sufficient condition (M, g) to be a Lorentzian space of maximal mobility with metric of the form (3)[6].

Finally we remark that if for B holds (12), then $\alpha = 0$, which is impossible [6].

Thus we can formulate

Theorem 5. *Let (M, g) be a four-dimensional spray-Einstien Lorentzian population space. Then (M, g) is SB -population space if and only if (M, g) is a space of constant sectional curvature or (M, g) is a space of maximal mobility with metric of the form (3).*

From this theorem and the main results in [5] we get our main result

Theorem 6. *Let (M, g) be a four-dimensional spray-Einstein Lorentzian population space which is not with a constant sectional curvature. Then the Voltera-Hamilton systems and their local sprays have straight line forms and are distinct from the ecologically point of view, if and only if (M, g) is Stanilov-Berwald population space.*

Finally we denote that some similarly results was provided in marine ecology [7].

REFERENCES

- [1] P. GILKEY. Geometric properties of the curvature operator. Proceedings of Beijing Conference II, Differential geometry and applications (Eds Kolar, Kowalski, Krupka, Slovak) Publ. Masaryk University Brno, Czech Republic ISBN 80-210-2097-0, (1999), 73–87.
- [2] R. IVANOVA, G. STANILOV. A skew symmetric curvature operator in Riemannian geometry. Symposia Gaussiana, Conf. A, (Eds Behara, Fritch, Lintz), 1995, 391–395.
- [3] P. GILKEY, J. LEAHY, H. SADOFSKY. Riemannian manifolds whose skew-symmetric curvature operator has constant eigenvalues. *Indiana Journal*, **48** (1999), 615–634.
- [4] V. VIDEV. A characterization of a four-dimensional Einstein Lorentzian manifolds using a skew-symmetric curvature operator. *Mathematica Balkanica, New series*, **15**, 2001, Fasc. 1–2.
- [5] P. ANTONELLY. The constant sprays of classical ecology and their noisy perturbations. Finslerian geometry (Edmonton, AB, 1998), 67–77, Fund. Theories Phys., 109, Kluwer Acad. Publ. Dodrecht, 2000.
- [6] A. Z. PETROV. Einstein Spaces. Pergamon Press, Hungary, Oxford and New York, 1969.
- [7] V. NONCHEVA, I. VELCHEVA. Heavy Metals Content in the Organs of Freshwater Fish. Statistical study. *Applications of Mathematics in Engineering and Economics*, (2001), 217–219.

Veselin T. Videv
Trakia University
Stara Zagora 6000, Bulgaria
e-mail: videv@uni-sz.bg

Marija V. Stoeva
Trakia University-Technical College
Jambol, Bulgaria
e-mail: maria_stoeva@abv.bg

Yordan Stajkov
Trakia University
Stara Zagora 6000, Bulgaria
e-mail: tula026@uni-sz.bg

ПРИЛОЖЕНИЕ НА АНТИСИМЕТРИЧНИЯ ОПЕРАТОР НА СТАНИЛОВ В КЛАСИЧЕСКАТА ЕКОЛОГИЯ

Веселин Видев, Мария Вълкова, Йордан Стайков

Главен резултат в статията е, че локалните вълни (следствия) от системата на Хамилтон са различни от екологична гледна точка тогава и само тогава, когато популационното пространство (M, g) е SB пространство.