Provided for non-commercial research and educational use. Not for reproduction, distribution or commercial use.

# Serdica Mathematical Journal Сердика

# Математическо списание

The attached copy is furnished for non-commercial research and education use only. Authors are permitted to post this version of the article to their personal websites or institutional repositories and to share with other researchers in the form of electronic reprints. Other uses, including reproduction and distribution, or selling or licensing copies, or posting to third party websites are prohibited.

For further information on
Serdica Mathematical Journal
which is the new series of
Serdica Bulgaricae Mathematicae Publicationes
visit the website of the journal http://www.math.bas.bg/~serdica
or contact: Editorial Office
Serdica Mathematical Journal
Institute of Mathematics and Informatics
Bulgarian Academy of Sciences
Telephone: (+359-2)9792818, FAX:(+359-2)971-36-49
e-mail: serdica@math.bas.bg

Serdica Mathematical Journal

Bulgarian Academy of Sciences Institute of Mathematics and Informatics

# EXTENDING THE CONVERGENCE REGION OF M-STEP ITERATIVE PROCEDURES

Ioannis K. Argyros, Santhosh George

Communicated by A. L. Dontchev and V. M. Veliov

ABSTRACT. The convergence region of iterative procedures is small in general, and it becomes smaller as m increases. This problem limits the choice of starting points, and consequently the applicability of these methods. The novelty of this work lies in the fact that, we extend the convergence region by using specializations of the Lipschitz constants used before. Further advantages include improved error estimations and uniqueness results. The results are tested favorably to us on examples.

**1. Introduction.** Let  $\mathcal{B}_1$  and  $\mathcal{B}_2$  stand for Banach spaces,  $\Omega \subset \mathcal{B}_1$  denote a convex and open set. Consider mapping  $G: \Omega \longrightarrow \mathcal{B}_2$ , to be nonlinear and Fréchet differentiable. One of the most challenging tasks is to find a solution  $x_*$  of

$$(1.1) G(x) = 0.$$

<sup>2020</sup> Mathematics Subject Classification: 65F08, 37F50, 65N12.

 $<sup>\</sup>it Key\ words:\ m\mbox{-step}$  iterative methods, Banach space, semi-local convergence, Newton's method, Lipschitz continuity.

Solving (1.1) is needed, since many problems from various disciplines can be made to look like equation (1.1) by resorting to Mathematical modeling. The solution  $x_*$  is rarely obtained in closed or analytical form. Hence, researchers develop iterative procedures that approximate  $x_*$  provided that the initial point  $x_0 \in \Omega$  is close enough to  $x_*$ . A great effort is given recently to develop high convergence order iterative procedures [1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 23, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22, 24, 25, 26]. Let m be a natural number.

In this article, we give the semi-local convergence of the m-step Traub or Newton-type method defined as

$$x_{n} = y_{n}^{(0)}$$

$$y_{n}^{(1)} = y_{n}^{(0)} - G'(y_{n}^{(0)})^{-1}G(y_{n}^{(0)})$$

$$(1.2) y_{n}^{(2)} = y_{n}^{(1)} - G'(y_{n}^{(0)})^{-1}G(y_{n}^{(1)})$$

$$\dots$$

$$x_{n+1} = y_{n}^{(m)} = y_{n}^{(m-1)} - G'(y_{n}^{(0)})^{-1}G(y_{n}^{(m-1)}).$$

Notice that if m = 1, we obtain Newton's method [1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 23, 13, 14, 15].

Method (1.2) has convergence order m+1 [1, 2, 20]. But it only uses the first derivative. This is in contrast to third order methods such as Euler, Chebyshev, Halley and other methods that utilize expensive higher order than one derivatives. That explains why many works have appeared dealing with the convergence and efficiency of method (1.2) [1, 2, 21, 26]. A major drawback of these works is the convergence region which is small in general and becomes even smaller as m increases. This problem limits the availability of initial points. Motivated by this concern, we use an extension of our technique introduced in [10] for Newton's method combined with our notion of the restricted convergence region in combination with the center-Lipschitz condition to find a strict subset of  $\Omega$  also containing the iterates. This techniques gives us at least as small constants as before leading to a larger convergence region as well as to the carrying out of less computations to obtain a predetermined error accuracy. The information on the uniqueness of  $x_*$  in a neighborhood of  $\Omega$  is also improved. Related work can be found in the excellent paper by Donchev et al. [17], where numerous Lipschitztype conditions are studied in the setting of fixed points. Then, our results can be written in those settings too in a suitable way. The novelty of this work lies in the observation that these developments involve not further conditions because

the new parameters constitute specializations of the old ones. Relevant work but for generalized equations has been given in [14].

The rest of the work lays out: In Section 2, the convergence of method (1.2) is studied using majorizing sequences. Some examples are given in Section 3.

2. Semi-local analysis. We base the semi-local convergence analysis of method (1.2) on some scalar majorizing sequences.

**Lemma 2.1.** Let  $\ell_0$ ,  $\ell$  and  $r_0^{(1)}$  be given positive parameters. Denote by  $\gamma$  the unique solution in the interval (0,1) of the polynomial equation

$$(2.1) p(t) = 0,$$

where

(2.2) 
$$p(t) = \ell_0 t^{m+1} - \frac{\ell}{2} (2 - t^m - t^{m-1}).$$

Define the scalar sequence  $\{t_n\}$  for each  $n=0,1,2,\ldots,$  and  $i=1,2,\ldots,$  m-1 by

$$t_0 = 0, r_n^{(0)} = t_n,$$

$$(2.3) r_{n+1}^{(1)} = t_{n+1} + \frac{\bar{k}(t_{n+1} - t_n + r_n^{(m-1)} - t_n)(t_{n+1} - r_n^{(m-1)})}{2(1 - \ell_0(t_{n+1} - t_0))},$$

$$(2.4) r_n^{(m)} = t_{n+1}, r_n^{(i+1)} = r_n^{(i)} + \frac{\bar{k}(r_n^{(i)} - t_n + r_n^{(i-1)} - t_n)(r_n^{(i)} - r_n^{(i-1)})}{2(1 - \ell_0(t_n - t_0))},$$

where 
$$\bar{k} = \begin{cases} \ell_0, & n = 0 \\ \ell, & n = 1, 2, 3 \dots \end{cases}$$
. Suppose that

(2.5) 
$$\ell_0 t_2 < 1, \ 0 \le \frac{\ell(t_2 - t_1 + r_1^{(m-1)} - t_1)}{2(1 - \ell_0 t_2)} \le \gamma < 1 - \frac{\ell_0(r_2^{(2)} - r_0^{(1)})}{1 - \ell_0 r_0^{1}}.$$

Then, sequence  $\{t_n\}$  is bounded from above by  $t_{**} = r_0^{(1)} + \frac{r_0^{(2)} - r_0^{(1)}}{1 - \gamma}$ , non decreasingly convergent to its unique least upper bound denoted by  $t_*$  so that  $0 \le t_* \le t_{**}$ . Moreover, the following items hold

$$(2.6) r_n^{(i)} - r_n^{(i-1)} \le \gamma (r_n^{(i-1)} - r_n^{(i-2)} \le \dots \le \gamma^{mn+i-2} (r_0^{(2)} - r_0^{(1)})$$

$$(2.7) r_{n+1}^{(1)} - r_n^{(m)} \le \gamma^{m(n+1)-1} (r_0^{(2)} - r_0^{(1)}),$$

and

$$(2.8) t_n = r_n^{(0)} \le r_1^{(1)} \le r_n^{(2)} \le \dots \le r_n^{(m-1)} \le r_n^{(m)} = t_{n+1}.$$

The proof is a nontrivial extension of the one, we gave for Newton's method in [10] for m = 1.

Proof. The intermediate value theorem together with the estimations  $p(0) = -\ell < 0$  and  $p(1) = \ell_0$  assures that equation p(t) = 0 has at least one solution in the interval (0,1). By  $p'(t) = (m+1)\ell_0 t^k + \frac{\ell}{2}(tm+m-1) > 0$  for each  $t \in (0,1)$ , function p increases on (0,1), so it crosses the x- axis only one time between 0 and 1. We name the unique solution of equation p(t) = 0 in (0,1) by  $\gamma$ .

Clearly, if we show estimations (2.6)–(2.8) then sequence  $\{t_n\}$  shall be nondecreasing. Evidently, (2.6)–(2.8) by (2.3)–(2.4) hold true, if

(2.9) 
$$0 \le \frac{\ell(r_j^{(i)} - t_j + r_j^{(i-1)} - t_j)}{2(1 - \ell_0 t_j)} \le \gamma,$$

(2.10) 
$$0 \le \frac{\ell(r_j^{(m)} - t_j + r_j^{(m-1)} - t_j)}{2(1 - \ell_0 t_{j+1})} \le \gamma$$

and

$$(2.11) t_j = r_j^{(0)} \le r_j^{(1)} \le r_j^{(2)} \le \dots \le r_j^{(m-1)} \le r_j^{(m)} = t_{j+1}.$$

If  $r_0^{(i)} - r_0^{(i-1)} \ge 0$ , then it follows from  $r_0^{(i+1)} - r_0^{(i)} = \frac{\ell_0}{2} (r_0^{(i)} + r_0^{(i-1)}) (r_0^{(i)} - r_0^{(i-1)})$  that  $r_0^{(i+1)} - r_0^{(i)} \ge 0$ . But  $r_0^{(0)} = t_0^{(0)} = t_0 = 0$  and  $r_0^{(1)} > 0$ , so  $r_0^{(i+1)} - r_0^{(i)} \ge 0$ . Then (2.11) holds for j = 0. Then, by (2.5), estimations (2.9) and (2.10) hold for m = 1 by the left hand side inequality in (2.5). Next, assume (2.9)–(2.11) hold for  $m = 2, 3, \ldots, n$  Notice that

$$0 \leq \frac{\ell(r_{j-1}^{(i)} - t_{j-1} + r_{j-1}^{(i-1)} - t_{j-1})}{2(1 - \ell_0 t_{j-1})}$$
$$\leq \frac{\ell(r_j^{(i)} - t_j + r_j^{i-1} - t_j)}{2(1 - \ell_0 t_j)}$$

(2.12) 
$$\leq \frac{\ell(r_j^{(m)} - t_j + r_j^{(m-1)} - t_j)}{2(1 - \ell_0 t_{j+1})}.$$

Hence, it suffices to show only (2.10). We need to use the induction hypotheses to obtain an upper bound on  $r_n^{(i)}$ :

$$r_{n}^{(i)} \leq r_{n}^{(i-1)} + \gamma^{mn+i-2}(r_{0}^{(2)} - r_{0}^{(1)})$$

$$\leq r_{n}^{(i-2)} + \gamma^{mn+i-3}(r_{0}^{(2)} - r_{0}^{(1)}) + \gamma^{mn+i-2}(r_{0}^{(2)} - r_{0}^{(1)})$$

$$\vdots$$

$$\leq r_{n}^{(1)} + (\gamma^{mn} + \dots + \gamma^{mn+i-2})(r_{0}^{(2)} - r_{0}^{(1)})$$

$$\leq r_{n-1}^{(m)} + (\gamma^{mn-1} + \dots + \gamma^{mn+i-2})(r_{0}^{(2)} - r_{0}^{(1)})$$

$$\vdots$$

$$\leq r_{0}^{(2)} + \gamma(r_{0}^{(2)} - r_{0}^{(1)}) + \dots + \gamma^{mn+i-2}(r_{0}^{(2)} - r_{0}^{(1)})$$

$$= r_{0}^{(2)} - (r_{0}^{(2)} - r_{0}^{(1)}) + (r_{0}^{(2)} - r_{0}^{(1)})$$

$$+ \gamma(r_{0}^{(2)} - r_{0}^{(1)}) + \dots + \gamma^{mn+i-2}(r_{0}^{(2)} - r_{0}^{(1)})$$

$$= r_{0}^{(1)} + (1 + \gamma + \dots + \gamma^{mn+i-2})(r_{0}^{(2)} - r_{0}^{(1)})$$

$$= r_{0}^{(1)} + \frac{1 - \gamma^{mn+i-1}}{1 - \gamma}(r_{0}^{(2)} - r_{0}^{(1)})$$

$$\leq r_{0}^{(1)} + \frac{r_{0}^{(2)} - r_{0}^{(1)}}{1 - \gamma} = t_{**}.$$

Evidently (2.10) holds, if

$$(2.14) \frac{\ell(r_0^{(2)} - r_0^{(1)})[(\gamma^{mj-1} + \dots + \gamma^{mj+m-2}) + (\gamma^{mj-1} + \dots + \gamma^{mj+m-3})]}{2(1 - \ell_0(r_0^{(1)} + \frac{1 - \gamma^{mj+m-1}}{1 - \gamma}(r_0^{(2)} - r_0^{(1)}))]} \le \gamma$$

or 
$$(2.15) \frac{\ell(r_0^{(2)} - r_0^{(1)}) \left[\frac{1 - \gamma^{mj+m-1}}{1 - \gamma} - \frac{1 - \gamma^{m(j-1)+m-1}}{1 - \gamma} + \frac{1 - \gamma^{mj+m-2}}{1 - \gamma} - \frac{1 - \gamma^{m(j-1)+m-1}}{1 - \gamma}\right]}{2(1 - \ell_0(r_0^{(1)} + \frac{1 - \gamma^{mj+m-1}}{1 - \gamma}(r_0^{(2)} - r_0^{(1)}))} \le \gamma$$

or

(2.16) 
$$\frac{\ell(r_0^{(2)} - r_0^{(1)})\gamma^{mj-2}(2 - \gamma^m - \gamma^{m-1})\frac{1}{1-\gamma}}{2(1 - \ell_0(r_0^{(1)} + \frac{1 - \gamma^{mj+m-1}}{1-\gamma}(r_0^{(2)} - r_0^{(1)}))]} \le 1$$

or

(2.17) 
$$\frac{\ell(r_0^{(2)} - r_0^{(1)})\gamma^{mj-2}(2 - \gamma^m - \gamma^{m-1})}{2[(1 - \ell_0 r_0^{(1)})(1 - \gamma) - \ell_0(1 - \gamma^{mj+m-1})(r_0^{(2)} - r_0^{(1)})]} \le 1.$$

It is helpful to define recurrent polynomials defined on (0,1) by

$$h_{j}(t) = \frac{\ell}{2} (r_{0}^{(2)} - r_{0}^{(1)}) t^{mj-2} (2 - t^{m} - t^{m-1})$$

$$\ell_{0}(1 - t^{mj+m-1}) (r_{0}^{(2)} - r_{0}^{(1)}) - (1 - \ell_{0} r_{0}^{(1)}) (1 - t).$$

Then, instead of (2.17), we can prove

$$(2.19) h_j(\gamma) \le 0.$$

To achieve this we need a computation relating two consecutive polynomials:

$$h_{j+1}(t) = \frac{\ell}{2} (r_0^{(2)} - r_0^{(1)}) t^{m(j+1)-2} (2 - t^m - t^{m-1})$$

$$- (1 - \ell_0 r_0^{(1)}) (1 - t) + \ell_0 (1 - t^{m(j+1)+m-1}) - h_j(t) + h_j(t)$$

$$= \frac{\ell}{2} (r_0^{(2)} - r_0^{(1)}) t^{mj-2} (2 - t^m - t^{m-1})$$

$$- \frac{\ell}{2} (r_0^{(2)} - r_0^{(1)}) t^{mj-2} (2 - t^m - t^{m-1})$$

$$+ \ell_0 (1 - t^{m(j+1)+m-1}) (r_0^{(2)} - r_0^{(1)})$$

$$- \ell_0 (1 - t^{mj+j-1}) (r_0^{(2)} - r_0^{(1)}) + h_j(t)$$

$$(2.20) = h_j(t) + p(t) (1 - t^m) t^{mj-2} (r_0^{(2)} - r_0^{(1)}).$$

Notice that by  $p(\gamma) = 0$ , and (2.18)

$$h_{j+1}(\gamma) = h_j(\gamma) = h_{\infty}(\gamma) := \lim_{j \to \infty} h_j(\gamma)$$

$$= \ell_0(r_0^{(2)} - r_0^{(1)}) - (1 - \ell_0 r_0^{(1)})(1 - \gamma).$$

Then, (2.19) holds, if

$$(2.22) h_j(\gamma) \le 0,$$

which is true by the left hand side inequality in condition (2.5). The induction for (2.9)–(2.11) is completed.  $\square$ 

Define  $\mathcal{L}(\mathcal{B}_1, \mathcal{B}_2) =: \{T : \mathcal{B}_1 \longrightarrow \mathcal{B}_2 \text{ is a bounded linear operator}\}$ , and  $S(x, \rho) := \{y \in \mathcal{B}_1 : ||x - y|| < \rho, \rho > 0\}$ , and  $\bar{S}(x, \rho) = \{y \in \mathcal{B}_1 : ||x - y|| \le \rho\}$ .

Let us consider conditions (B) to be used together with the previous notations in the analysis of method (1.2).

(b1)  $G: \Omega \subseteq \mathcal{B}_1 \longrightarrow \mathcal{B}_2$  is differentiable in the Fréchet sense. There exist  $x_0 \in \Omega, r_0^{(1)} > 0$  such that  $G'(x_0)^{-1} \in \mathcal{L}(\mathcal{B}_2, \mathcal{B}_1)$ , and

$$||G'(x_0)^{-1}G(x_0)|| \le r_0^{(1)}.$$

(b2) For all  $x \in \Omega$ , and some  $\ell_0 > 0$ 

$$||G'(x_0)^{-1}(G'(x_0) - G'(x))|| < \ell_0 ||x_0 - x||.$$

Let 
$$S_0 = \Omega \cap S(x_0, \frac{1}{\ell_0})$$
.

(b3) For all  $x, y \in S_0$ , and some  $\ell > 0$ 

$$||G'(x_0)^{-1}(G'(y) - G'(x))|| \le \ell ||y - x||.$$

- (b4) Hypotheses of Lemma 2.1 hold.
- (b5)  $\bar{S}(x_0, t_*) \subseteq \Omega$ , where  $t_*$  is given in Lemma 2.1.
- (b6) There exists  $u \geq t_*$  such that  $\ell_0(t_* + u) < 2$ . Let  $S_1 = \Omega \cap \bar{S}(x_0, u)$ .

**Theorem 2.2.** Assume conditions (B) hold. Then, the following hold  $\{x_n\} \subset \bar{S}(x_0, t_*), \lim_{n \to \infty} x_n = x_* \in \bar{S}(x_0, t_*),$ 

$$||x_* - x_n|| \le t_* - t_n,$$

and  $x_*$  is the only solution of equation F(x) = 0, in the set  $S_1$ .

The proof is an extension of the corresponding one given by us in [10] for Newton's method (m = 1).

Proof. Mathematical induction is used to show items

(Q1) 
$$||y_n^{(1)} - x_n|| \le r_n^{(1)} - t_n$$
,

(Qi) 
$$||y_n^{(i)} - y_n^{(i-1)}|| \le r_n^{(i)} - r_n^{(i-1)}$$
 for all  $i = 2, 3, \dots, m-1$ .

(Qk) 
$$||x_{n+1} - y_n^{(i-1)}|| \le t_{n+1} - r_n^{(m-1)}$$
.

If n = 0, by (b1)  $||y_0^{(1)} - x_0|| = ||G'(x_0)^{-1}G(x_0)|| \le r_0^{(1)} \le t_*$ , so  $y_0^{(1)} \in \bar{S}(x_0, t_*)$ , and (Q1) holds for n = 0. By the  $i^{th}$  step of method (1.2),  $i = 2, 3, \ldots, m-1$ , (b2), we have in turn that

$$||y_1^{(1)} - x_1|| = ||(G'(x_1)^{-1}G'(x_0)(G'(x_0)^{-1}G(x_1))||$$

$$\leq \frac{||G'(x_0)^{-1}(G(x_1) - G(y_0^{(m-1)})) - G'(x_0)(x_1 - y_0^{(m-1)})||}{1 - \ell_0||x_1 - x_0||}$$

$$\leq \frac{\ell_0(||x_1 - x_0|| + ||y_0^{(m-1)} - x_0||)||x_1 - y_0^{(m-1)}||}{2(1 - \ell_0||x_1 - x_0||)}$$

$$\leq \frac{\ell_0(t_1 - t_0 + r_0^{(m-1)} - t_0)(t_1 - r_0^{(m-1)})}{2(1 - \ell_0(t_1 - t_0))}$$

$$= r_1^{(1)} - t_1,$$

and

$$||y_1^{(1)} - x_0|| \le ||y_1^{(1)} - x_1|| + ||x_1 - x_0|| \le r_1^{(1)} - t_1 + t_1 - t_0 = r_1^{(1)} \le t_*,$$

so  $y_0^{(1)} \in \bar{S}(x_0, t_*)$ , and (Q1) holds. Next, using (b3), we obtain by method (1.2)

$$||y_1^{(i)} - y_1^{(i-1)}|| = ||(G'(x_1)^{-1}G'(x_0)(G'(x_0)^{-1}G(y_1^{(i-1)}))||$$

$$\leq \frac{||G'(x_0)^{-1}(G(y_1^{(i-1)}) - G(y_1^{(i-2)})) - G'(x_1)(y_1^{(i-1)} - y_0^{(i-2)})||}{2(1 - \ell_0||x_1 - x_0||)}$$

$$\leq \frac{\ell(r_1^{(i-1)} - t_1 + r_1^{(i-2)} - t_1)(r_1^{(i-1)} - r_1^{(i-2)})}{2(1 - \ell_0(t_1 - t_0))}$$

$$= r_1^{(i)} - r_1^{(i-1)},$$

and

$$||y_0^{(i)} - y_0^{(i-1)}|| = ||G'(x_0)^{-1}(G(y_0^{(i-1)}) - G(y_0^{(i-2)}) + G(y_0^{(i-2)})||$$

$$= ||G'(x_0)^{-1}[G(y_0^{(i-2)} - G(y_0^{(i-2)}) - G'(x_0)(y_0^{(i-1)} - y_0^{(i-2)})]||$$

$$\leq \int_0^1 ||G'(x_0)^{-1}(G'(y_0^{(i-2)} + \tau(y_0^{(i-1)} - y_0^{(i-2)})) - G'(x_0)(y_0^{(i-1)} - y_0^{(i-2)})||$$

$$-G'(x_0)(y_0^{(i-1)} - y_0^{(i-2)})||d\tau||$$

$$\leq \frac{\ell_0}{2}(||y_0^{(i-1)} - x_0|| + ||y_0^{(i-2)} - x_0||)||y_0^{(i-1)} - y_0^{(i-2)}||$$

$$\leq \frac{\ell_0}{2}(r_0^{(i-1)} - t_0 + r_0^{(i-2)} - t_0)(r_0^{(i-1)} - r_0^{(i-2)})$$

$$= r_0^{(i)} - r_0^{(i-1)},$$

$$(2.24)$$

where, we also used the estimate

(2.25) 
$$G'(x_n)(y_n^{(i)} - y_n^{(i-1)}) = -G(y_n^{(i-1)}).$$

Then, we get

$$||y_0^{(i)} - x_0|| \leq ||y_0^{(i)} - y_0^{(i-1)}|| + ||y_0^{(i-1)} - y_0^{(i-2)}|| + \dots + ||y_0^{(1)} - x_0|| \leq r_0^{(i)} - r_0^{(i-1)} + r_0^{(i-1)} - r_0^{(i-2)} + \dots + r_0^{(1)} - r_0^{(0)} = r_0^{(i)} \leq t_*,$$

$$(2.26)$$

so  $y_0^{(i)} \in \bar{S}(x_0, t_*)$ . Letting i = m in (2.24 and (2.26) we have that

and

$$||x_1 - x_0|| \le t_1 \le t_*,$$

respectively, so  $x_1 \in \bar{S}(x_0, t_*)$  and  $Q_k$  holds for k = 0. Next, we show  $Q_i$  for i = 1, 2, ..., m when, n = 1 by induction on i. Let  $v \in S_0$ . Then, by (b2), we get that

$$(2.28) ||G'(x_0)^{-1}(G'(v) - G'(x_0))|| \le \ell_0 ||v - x_0|| < \ell_0 \frac{1}{\ell_0} = 1,$$

so  $G'(v)^{-1} \in \mathcal{L}(\mathcal{B}_2, \mathcal{B}_1)$  and

(2.29) 
$$||G'(v)^{-1}G'(x_0)|| \le \frac{1}{1 - \ell_0 ||v - x_0||},$$

by the Banach lemma for invertible mappings [5, 8, 23, 13, 21]. In particular, (2.29) holds for  $v = x_1$ . Then, by (b2), (2.3) and method (1.2) (first step of the  $k^{th}$  step), we obtain in turn that

$$||y_1^{(i)} - x_0|| \le ||y_1^{(i)} - y_1^{(i-1)}|| + ||y_1^{(i-1)} - x_0||$$
  
$$\le r_1^{(i)} - r_1^{(i-1)} + r_1^{(i-1)} - t_0 = r_1^{(i)} \le t_*,$$

so  $Q_1^{(i)} \in \bar{S}(x_0, t_*)$ , and  $(Q_i)$  holds. By using  $x_n, y_n^{(1)}, y_n^{(2)}, \dots, y_n^{(m)}$  instead of  $x_1, y_1^{(1)}, y_1^{(2)}, \dots, y_1^{(m)}$ , respectively items (Qi),  $i = 1, 2, \dots, m$  hold. In view of

$$||x_{n+1} - x_n|| = ||y_n^{(m)} - y_n^{(0)}||$$

$$\leq \sum_{q=0}^{m-1} ||y_n^{(m-q)} - y_n^{(m-q-1)}||$$

$$\leq \sum_{q=0}^{m-1} (r_n^{(m-q)} - r_n^{(m-q-1)})$$

$$= r_n^{(m)} - r_n^{(0)}.$$

That is  $\{x_n\}$  is a complete sequence in a Banach space  $\mathcal{B}_1$ . Hence, there exists  $x_* \in \bar{S}(x_0, t_*)$  such that  $\lim_{n \to \infty} x_n = x_*$ . Then, we have by the estimation  $\|G'(x_0)^{-1}G(y_n^{(i)})\| \le \ell(\|x_n^{(i)} - x_n\| + \|y_n^{(i-1)} - x_n\|)\|y_n^{(i)} - y_n^{(i-1)}\| \longrightarrow 0$  as  $n \to \infty$ , that  $G(x_*) = 0$ . The uniqueness proof is given in [10].  $\square$ 

## Remark 2.3.

- (a) The point  $t_{**}$  can be used in Theorem 2.2 instead of  $t_*$ , if one wants a closed form point.
- (b) As already noted in [10], we use initial data until the computation of  $t_2$ . This way, we relate the semi-local convergence condition (2.5) to  $r_0^{(2)} r_0^{(1)}$  (which is smaller) instead of  $r_0^{(1)} r_0^{(0)}$  which is traditionally done. It turns

out that smaller Lipschitz constants can replace the ones in conditions (B). Indeed, define set  $\Omega_2 = \Omega \cap S(x_1, \frac{1}{\ell_0} - r_0^{(1)})$  provided that  $\ell_0 r_0^{(1)} < 1$ . Clearly

$$(2.31) \Omega_2 \subseteq \Omega_1,$$

and can replace it in Theorem 2.2. But then, by (2.31) the new Lipschitz constant corresponding to  $\ell$  denoted by  $\lambda$  will be such that

$$(2.32) \lambda \le \ell.$$

Then,  $\lambda$  can also replace  $\ell$  in all estimations, and the resulting analysis will be even finer (see also the numerical example).

(c) The condition in [26] using  $r_0^{(1)} - r_0^{(0)}$  in (2.5) instead of  $r_0^{(2)} - r_0^{(1)}$  is given by

(2.33) 
$$0 \le \frac{\bar{\ell}(t_1 + r_0^{(m-1)})}{2(1 - \ell_0 t_1)} \le \gamma < 1 - \ell_0 r_0^{(1)},$$

where  $\bar{\ell}$  is the Lipschitz constant on  $\Omega$  not on  $S_0$  (see (b3)).

- (d) The ratio of convergence is  $\gamma$  given in (2.2). According to the proof of Theorem 2.2 it can also be replaced by the upper bound  $\bar{\gamma}$  which is computable in advance and given by  $\bar{\gamma} = \frac{\gamma t_{**}}{1 \ell_0 t_{**}}$ .
  - 3. Numerical examples

**Example 3.1.** Let 
$$\mathcal{X} = \mathcal{Y} = \mathbb{R}$$
,  $\Omega = \bar{U}(x_0, 1 - \xi)$ ,  $x_0 = 1$  and  $\xi \in \left[0, \frac{1}{2}\right)$ .

Define function  $\mathcal{H}$  on  $\Omega$  by

$$\mathcal{H}(x) = x^3 - \xi.$$

Then, we get by (2.1)-(2.5) and (2.33) that for

(i) m = 1,  $r_0^{(1)} = \frac{1}{3}(1 - \xi)$ ,  $\ell_0 = 3 - \xi$ ,  $\ell = 2\left(1 + \frac{1}{\ell_0}\right)$ ,  $\bar{\ell} = 2(2 - \xi)$ . Then conditions of Lemma 2.1 are satisfied for  $I_1 = [0.42289, 0.5)$ ,  $I_2 = [0.43289, 0.5)$ . (ii) For m = 2, the conditions of Lemma 2.1 are satisfied for  $\xi \in I_3 = [0.496599, 0.5)$ 

but the earlier conditions [1, 2, 21, 26] are satisfied for  $\xi \in I_4 = [0.49669, 0.5)$ , and  $I_4 \subset I_3$ . Hence, in both cases m = 1, 2 we find infinite many values of  $\xi$  for which convergence is not guaranteed under the old condition (2.33). That is the usage of method (1.2) is extended.

4. Conclusion. Our idea of the convergence region in connection to the center Lipschitz condition were utilized to provide a local as well as a semilocal convergence analysis of method (1.2). Due to the fact that we locate a region at least as small as in earlier works [1, 2, 21, 26] containing the iterates, the new Lipschitz parameters are also at least as small. This technique leads to a finer convergence analysis (see Remark 2.3 and the numerical example). The novelty of the paper not only lies in the introduction of the new idea but also obtained using special cases of Lipschitz parameters appearing in [1, 2, 21, 26]. Hence, no additional work to [1, 2, 21, 26] is needed to arrive at these developments. This idea can be used to extend the applicability of other iterative methods appearing [1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 23, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22, 24, 25, 26] along the same lines.

### REFERENCES

- [1] S. AMAT, I. K. ARGYROS, S. BUSQUIER, M. A. HERNÁNDEZ-VERÓN. On two high-order families of frozen Newton-type methods. *Numer. Linear Algebra Appl.* **25**, 1 (2018), e2126, 13 pp.
- [2] S. AMAT, C. BERMUDEZ, M. A. HERNANDEZ-VERON, E. MARTINEZ. On an efficient k-step iterative method for nonlinear equations. J. Comput. Appl. Math. 302 (2016), 258–271.
- [3] S. Amat, S. Busquier, C. Bermudez, S. Plaza. On two families of high-order newton type methods. *Appl. Math. Lett.* **25**, *12* (2012), 2209–2217.
- [4] S. AMAT, S. BUSQUIER, S. PLAZA. Review of some iterative root-finding methods from a dynamical point of view. *Sci. Ser. A Math. Sci.* (N.S.) **10** (2004), 3–35.
- [5] I. K. Argyros. Computational theory of iterative methods. Studies in Computational Mathematics, vol. 15 (eds C. K. Chui, L. Wuytack), Amsterdam, Elsevier B. V., 2007.
- [6] I. K. Argyros. On the semilocal convergence of a fast two-step Newton method. Rev. Colombiana Mat. 42, 1 (2008), 15–24.
- [7] I. K. ARGYROS, S. REGMI. Contemporary Algorithms for Solving Problems in Economics and Other Disciplines. New York, Nova Science Publishes, 2020, DOI: 10.52305/KRNK4655

- [8] I. K. Argyros, S. George. Mathematical modeling for the solution of equations and systems of equations with applications, Volume IV. New York, Nova Science Publishes, 2021, DOI: 10.52305/EQOT3361.
- [9] I. K. Argyros, A. Cordero, Á. A. Magreñán, J. R. Torregrosa. Third-degree anomalies of Traubs method. J. Comput. Appl. Math. 309 (2017), 511–521.
- [10] I. K. Argyros, S. Hilout. Weaker conditions for the convergence of Newtons method. J. Complexity 28, 3 (2012), 364–387.
- [11] I. K. Argyros, S. Hilout. Computational Methods in Nonlinear Analysis: Efficient Algorithms, Fixed Point Theory and Applications. World Scientific, 2013, https://doi.org/10.1142/8475.
- [12] I. K. ARGYROS, Á. A. MAGREÑÁN, L. ORCOS, J. A. SICILIA. Local convergence of a relaxed two-step Newton like method with applications. J. Math. Chem. 55, 7 (2017), 1427–1442.
- [13] I. K. Argyros, Á. A. Magréñan. Iterative methods and their dynamics with applications, A contemporary study. Boca Raton, FL, CRC Press, 2017.
- [14] R. CIBULKA, A. L. DONTCHEV, J. PREININGER, T. ROUBAL, V. VELIOV. Kantorovich-type theorems for generalized equations. J. Convex Anal. 25, 2 (2018), 459–486
- [15] A. CORDERO, J. R. TORREGROSA. Low-complexity root-finding iteration functions with no derivatives of any order of convergence. J Comput. Appl. Math. 275 2015, 502–515.
- [16] A. CORDERO, J. R. TORREGROSA, P. VINDEL. Study of the dynamics of third-order iterative methods on quadratic polynomials. *Int. J. Comput. Math.* 89, 13–14 (2012), 1826–1836.
- [17] T. DONCHEV, E. FARKI, S. REICH. Fixed set iterations for relaxed Lipschitz multimaps. *Nonlinear Anal.* 53, 7–8 (2003), 997–1015.
- [18] J. A. EZQUERRO, M. A. HERŃANDEZ-VEŔON. How to improve the domain of starting points for steffensen's method. Stud. Appl. Math. 132, 4 (2014), 354–380.

- [19] J. A. EZQUERRO, M. GRAU-ŚANCHEZ, M. A. HERŃANDEZ-VEŔON, M. A. NOGUERA. A family of iterative methods that uses divided differences of first and second orders. *Numer. Algorithms* 70, 3 (2015), 571–589.
- [20] M. A. HERŃANDEZ-VEŔON, E. MARTÍNEZ, C. TERUEL. Semilocal convergence of a k-step iterative process and its application for solving a special kind of conservative problems. Numer. Algorithms 76, 2 (2017), 309–331.
- [21] L. V. KANTOROVICH, G. P. AKILOV. Functional Analysis. Translated from the Russian by Howard L. Silcock, 2nd edition. Oxford-Elmsford, N.Y., Pergamon Press, 1982.
- [22] Á. A. MAGREÑÁN, I. K. ARGYROS. Improved convergence analysis for Newton-like methods. Numer. Algorithms 71, 4 (2016), 811–826.
- [23] Á. A. MAGRÉÑAN, I. K. ARGYROS. A contemporary study of iterative methods, Convergence, dynamics and applications. London, Elsevier (Academic Press), 2018.
- [24] Á. A. MAGREÑÁN, A. CORDERO, J. M. GUTIÉRREZ, J. R. TORREGROSA. Real qualitative behavior of a fourth-order family of iterative methods by using the convergence plane. *Math. Comput. Simulation* **105** (2014), 49–61.
- [25] Á. A. MAGREÑÁN, I. K. ARGYROS. Two-step Newton methods. J. Complexity 30, 4 (2014), 533–553.
- [26] F. A. Potra, V. Pták. Nondiscrete induction and iterative processes. Research Notes in Mathematics, vol. 103. Boston, MA, Pitman, 1984.

Ioannis K. Argyros
Department of Mathematical Sciences
Cameron University
Lawton, OK 73505, USA
e-mail: iargyros@cameron.edu

Santhosh George

Department of Mathematical and Computational Sciences National Institute of Technology Karnataka India-575 025

e-mail: sgeorge@nitk.edu.in Received February 21, 2019