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On Submanifolds of Sasakian Manifolds

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Presented by P. Kenderov

Any k-dimensional, $k \ge 4$, totally-umbilical submanifold tangent to the contact vector of a Sasakian space-form is totally-geodesic. A complete simply-connected extrinsic sphere tangent to the contact vector of a Sasakian manifold and having a flat normal connection is isometric to a standard sphere. Any submanifold tangent to the contact vector of a Sasakian space-form and having a parallel second fundamental form is either invariant (and thus totally-geodesic) or anti-invariant.

1. Introduction

Totally-umbilical submanifolds of complex space-forms have been classified by B. Y. Chen & K. Ogiue, cf.Th. 1 in [6], p. 225. Their classification theorem is based on the earlier (cf. prop. 3.1. in [7], p. 260) observation that submanifolds (of a complex space-form) invariant under the curvature transformation are either holomorphic or totally-real. We extend these ideas to submanifolds of Sasakian space-forms and obtain the following

Theorem 1. Let M^{2m+1} be an odd dimensional totally-umbilical submanifold of a Sasakian space-form $M^{2n+1}(c)$, 1 < m < n. If M^{2m+1} is tangent to the contact vector ξ of $M^{2n+1}(c)$ then M^{2m+1} is a Sasakian space-form immersed in $M^{2n+1}(c)$ as a totally-geodesic submanifold.

In contrast with prop. 3.1. in [7], p. 260, an invariant (in the sense of K. Ogiue [13], p. 389) submanifold M^{2m+1} of a Sasakian space-form is always φ -invariant (in the sense of K. Yano & M. Kon [14], p. 48) provided that m>1 and M^{2m+1} is tangent to ξ . Consequently, case b) in Th. 1 of [6], p. 225, has no analogue in contact geometry. In particular, cf. our Th. 1, there do not exist extrinsic spheres M^{2m+1} , m>1, tangent to the structure vector ξ of a Sasakian space-form.

As to extrinsic spheres (i.e. totally-umbilical submanifolds whose non-zero mean curvature vector H is parallel in the normal bundle) we obtain the following

Theorem 2. Let M^{2m+1} be a complete simply-connected extrinsic sphere tangent to the contact vector ξ of a Sasakian manifold M^{2n+1} , $1 \le m < n$. If M^{2m+1}

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has a flat normal connection then M^{2m+1} is isometric to the standard sphere $S^{2m+1}(\frac{1}{c})$ of radius $\frac{1}{c}$, where $c=\|H\|$.

Cf. B. Y. Chen [3], p. 327, a Riemannian manifold M^k , $\dim(M^k) = k$, is sufficiently curved if for any $x \in M^k$ the maximal linear subspace V of the tangent space $T_x(M^k)$ with $\overline{R}_x(u, v) = 0$ for all $u, v \in V$, (here \overline{R} denotes the curvature of M^k), has real algebraic dimension less than k-2. We show that if a submanifold M^{2m+1} bearing the hypothesis of our Th. 2 is considered, then M^{2n+1} is a subject to

$$(1.1) \bar{R}(X, Y) = 0,$$

for all tangent vector fields X, Y on M^{2m+1} , i.e. if M^{2m+1} has codimension two (i.e. m=n-1) then the ambient space M^{2n+1} is not sufficiently curved. Note that Sasakian space-forms $M^{2n+1}(c)$ do not verify (1.1).

Theorem 3. Let M^m be a real m-dimensional submanifold of the Sasakian manifold M^{2n+1} . If M^m is tangent to the contact vector of M^{2n+1} and has a parallel second fundamental form then M^m is a contact Cauchy-Riemann submanifold.

In particular, any extrinsic sphere of M^{2n+1} is a contact C. R. submanifold. Also our th. 3 leads to the following

Corollary. Let M^m be a real m-dimensional submanifold of the Sasakian space-form $M^{2n+1}(c)$. Suppose M^m is tangent to ξ and $\nabla h = 0$. Then either M^m is invariant (and thus totally geodesic) or M^m is anti-invariant.

2. Notations, conventions and basic formulae

Let M^{2n+1} be a real (2n+1)-dimensional differentiable manifold. An almost contact metrical (a. ct. m.) structure $(\varphi, \xi, \bar{\eta}, \bar{g})$ on M^{2n+1} consists of a (1,1)-tensor field φ , a tangent vector field ξ , a differential 1-form $\bar{\eta}$, and a Riemannian metric \bar{g} such that the following relations hold:

(2.1)
$$\varphi^{2} = -I + \bar{\eta} \otimes \bar{\xi}$$

$$\bar{\eta} \circ \varphi = 0, \ \varphi(\bar{\xi}) = 0$$

$$\bar{\eta}(\bar{\xi}) = 1, \ \bar{\xi} = \# \ \bar{\eta}$$

$$\bar{g}(\varphi X, \ \varphi Y) = \bar{g}(X, \ Y) - \bar{\eta}(X)\bar{\eta}(Y)$$

for any X, $Y \in \mathfrak{X}(M^{2n+1})$. We denote by $C^{\infty}(M^{2n+1})$ the ring of all IR-valued differentiable functions on M^{2n+1} and by $\mathfrak{X}(M^{2n+1})$ the $C^{\infty}(M^{2n+1})$ -module of all tangent vector fields on M^{2n+1} . Also # indicates raising of indices by \bar{g} . An a.ct. m. structure is normal if $N^{(1)} = 0$, where $N^{(1)} = [\varphi, \varphi] + 2(d\bar{\eta}) \otimes \xi$, while $[\varphi, \varphi]$ denotes the Nijenhuis torsion of φ . See D. E. Blair [1], p. 48. The fundamental 2-form $\bar{\varphi}$ of an a.ct. m. manifold M^{2n+1} is given by $\bar{\varphi}(X, Y) = \bar{g}(X, \varphi Y)$. A manifold M^{2n+1} carrying a normal a.ct. m. structure is termed

Sasakian if $\overline{Q} = d\overline{\eta}$. Let \overline{V} be the Riemannian connection of \overline{g} . If M^{2n+1} is a Sasakian manifold then

(2.2)
$$(\overline{\nabla}_{Y} \varphi) Y = -\overline{g}(X, Y) \overline{\xi} + \overline{\eta}(Y) X$$

for all X, $Y \in \mathfrak{X}(M^{2n+1})$. Cf. e. g. [14], p. 10. The curvature \overline{R} of a Sasakian space-form $M^{2n+1}(c)$, (cf. [1], p. 98, for definitions), is given by:

(2.3)
$$\bar{R}(X, Y)Z = \frac{1}{4}(c+3)(\bar{g}(Y, Z)X - \bar{g}(X, Z)Y)$$

$$-\frac{1}{4}(c-1)(\bar{\eta}(Y)\bar{\eta}(Z)X - \bar{\eta}(X)\bar{\eta}(Z)Y + \bar{g}(Y, Z)\bar{\eta}(X)\bar{\xi} - \bar{g}(X, Z)\bar{\eta}(Y)\bar{\xi}$$

$$-\bar{g}(\varphi Y, Z)\varphi X + \bar{g}(\varphi X, Z)\varphi Y + 2\bar{g}(\varphi X, \varphi Y)\varphi Z).$$

Let M^k be a submanifold of the Sasakian manifold M^{2n+1} . Let $g=i^*\bar{g}$ be the induced metric, where $i:M^k\to M^{2n+1}$ denotes the canonical inclusion. We recall the Gauss and Weingarten formulae:

(2.4)
$$\overline{\nabla}_X Y = \nabla_X Y + h(X, Y)$$

$$\overline{\nabla}_X N = -A_N X + \nabla_X^{\perp} N$$

for any X, $Y \in \mathfrak{X}(M^k)$, respectively any cross-section N in the normal bundle of i. Here ∇ , h, A_N and ∇^{\perp} denote respectively the induced connection, the second fundamental form, the Weingarten operator (associated

with the normal section N), and the normal connection. Let $H = \frac{1}{k} \operatorname{Trace}(h)$

be the mean curvature vector of M^k in M^{2n+1} . In §3 to §5 we are concerned with totally-umbilical (i.e. $h=g\bigotimes H$) submanifolds of Sasakian manifolds. A submanifold M^k of a Sasakian manifold is called φ -invariant if

$$\varphi_{\mathbf{x}}(T_{\mathbf{x}}(M^k)) \subseteq T_{\mathbf{x}}(M^k)$$

for any $x \in M^k$. Also M^k is said to be invariant (under the curvature transformation) if for any $x \in M^k$ and any u, $v \in T_x(M^k)$ the tangent space $T_x(M^k)$ is invariant under the transformation $\bar{R}_x(u, v) : T_x(M^{2n+1}) \to T_x(M^{2n+1})$, i.e.

$$\bar{R}_x(u, v)(T_x(M^k)) \subseteq T_x(M^k).$$

Cf. K. Ogiue [13]. A submanifold M^k is termed extrinsic sphere if $h=g\otimes H,\ H\neq 0,\ \nabla^\perp H=0$.

3. Classifying the totally-umbilical submanifolds in Sasakian space-forms

Let M^k be a totally-umbilical submanifold of the Sasakian space form $M^{2n+1}(c)$. Let $E \to M^k$ be the normal bundle of $i: M^k \to M^{2n+1}(c)$. We denote by \tan_x , nor, the natural projections associated with the direct sum decomposition:

$$T_x(M^{2n+1}(c)) = T_x(M^k) + E_x, x \in M^k.$$

Since $h = g \otimes H$, the covariant derivative of h is given by

$$(3.1) \qquad (\nabla_X h)(Y, Z) = g(Y, Z) \nabla_X^{\perp} H$$

such that the Codazzi equation, i.e. eq. (2.9) in [2], p. 46 becomes

(3.2)
$$\operatorname{nor}(\overline{R}(X, Y)Z) = g(Y, Z) \nabla_X^{\perp} H - g(X, Z) \nabla_X^{\perp} H$$

for any X, Y, $Z \in \mathfrak{X}(M^k)$. Let $X \in \mathfrak{X}(M^k)$ be arbitrary. Suppose from now on that $k \ge 3$. If this is the case, then we may choose $Y \in \mathfrak{X}(M^k)$ such that ||Y|| = 1, g(X, Y) = 0, $\bar{g}(\varphi X, Y) = 0$. Therefore, by our (3.2), it follows:

(3.3)
$$\operatorname{nor}(\bar{R}(X, Y)Y) = \nabla_X^{\perp} H.$$

Let us put $\xi = \tan(\xi)$, $\xi^{\perp} = \operatorname{nor}(\xi)$. Also we define a vector valued differential 1-form F on M^k by setting $FX = \operatorname{nor}(\varphi X)$, $X \in \mathfrak{X}(M^k)$. As a consequence of (2.3) one has

(3.4)
$$\operatorname{nor}(\bar{R}(X, Y)Z) = \frac{1}{4}(c-1)(2\eta(X)\eta(Y)FY - \eta(X)\xi^{\perp}),$$

where $\eta = i^* \bar{\eta}$. One obtains the following partial result:

Proposition 3.1. A totally-umbilical submanifold M^k tangent to the contact vector ξ of a Sasakian space-form is either totally-geodesic or an extrinsic sphere, provided that $k \ge 4$.

Proof. If $k \ge 4$ we may choose Y from the very beginning to be orthogonal on ξ . Moreover (3.3) – (3.4) and $\xi^{\perp} = 0$ lead to

$$\nabla_{\mathbf{x}}^{\perp} H = 0.$$

Now the two situations in our prop. 3.1. correspond to the cases H=0 and $H \neq 0$, respectively. Q. E. D.

To prove our Th. 1, we shall show that the second case in our Prop. 3.1. actually does not occur.

4. Proof of Theorem 1

Combining (3.2), (3.5) we obtain

(4.1)
$$\operatorname{nor}(\overline{R}(X, Y)Z) = 0$$

for any X, Y, $Z \in \mathfrak{X}(M^k)$, i.e. M^k follows to be invariant (under the curvature transformation). We need the following:

Proposition 4.1. Let M^k be an invariant submanifold, $k \ge 2$, of a Sasakian space-form $M^{2n+1}(c)$. Then M^k is φ -invariant.

Proof. Using (2.3) and (4.1), (i.e. the invariance assumption) one shows that $\overline{R}(X, Y)X \in \mathfrak{X}(M^k)$, i.e. $(2\overline{g}(\varphi X, \varphi Y) - \mathcal{O}(X, Y))\varphi X$ is tangent to M^k . Here

one obtains $\|\varphi_{x_0}u_0\|=0$, i.e. $\varphi_{x_0}u_0=0$, a contradiction. Q. E. D. Therefore, by prop. 3.1. and prop. 4.1., a totally-umbilical submanifold M^k , $k \ge 4$, tangent to the structure vector ξ of a Sasakian space-form is φ -invariant, (and k must be odd, i.e. k=2m+1, m>1). Now, if M^{2m+1} is φ -invariant and $\xi^{\perp}=0$ then M^{2m+1} must be minimal. Indeed, by the Gauss formula (cf. our (2.4)) and by (2.2) one has

$$(4.2) h(X, \varphi Y) = \varphi h(X, Y)$$

for any $X, Y \in \mathfrak{X}(M^{2m+1})$. Then by choosing an orthonormal tangential frame of the form $(\xi, X_i, \varphi X_i)_{1 \le i \le m}$ and using (4.2) one shows that $(2m+1)H = h(\xi, \xi) = 0$. Our Th. 1 is completely proved.

5. Extrinsic spheres

Let M^{2m+1} be an extrinsic sphere of the Sasakian manifold M^{2n+1} . Let R^{\perp} be the curvature of the normal connection. Since M^{2m+1} is taken to be simply-connected, the assumption $R^{\perp}=0$ is equivalent to the existence of a frame (in the normal bundle) consisting of mutually orthogonal parallel (in the normal bundle) unit vector fields. Let $c=\|H\|$. Then c=const. >0. Let $N=\frac{1}{c}H$. Then N is a parallel unit normal vector field. We may choose an orthonormal frame $(N_a)_1 \leq a \leq 2n-2m$ in the normal bundle such that $N_1=N$, and

$$\nabla^{\perp}N_a=0, \ a\geq 1.$$

Let us construct the functions $f_a \in C^{\infty}(M^{2m+1})$ by setting $f_a = \bar{g}(\varphi N, N_a)$, $2 \le a \le 2n - 2m$. At this point we may prove our Th. 2. This is done in several steps, following the ideas in [3].

Step 1. The following relation holds

$$(5.1) X(f_a) = c \ \overline{Q}(X, N_a), \ a > 1$$

for any $X \in \mathfrak{X}(M^{2m+1})$.

Proof. As $A_N = \bar{g}(N_a, H)X = 0$, we have $X(f_a) = X(\bar{g}(\varphi N, N_a)) = \bar{g}(\bar{\nabla}_X \varphi N, N_a) + \bar{g}(\varphi N, \bar{\nabla}_X N_a) = \bar{g}(\varphi \bar{\nabla}_X N, N_a) + \bar{\eta}(N)\bar{g}(X, N_a) - \bar{g}(\varphi N, A_{N_a}X) = -\bar{g}(\varphi A_N X, N_a)$, as a consequence of (2.2). Q. E. D.

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Step 2. The functions f_a are subject to:

(5.2)
$$(\nabla_X df_a) Y = c \left(\bar{\eta}(N_a) - cf_a \right) g(X, Y)$$

for any X, $Y \in \mathfrak{X}(M^{2m+1})$.

Proof. Indeed, by (5.1) one has $X(Y(f_a)) = cX(\overline{\phi}(Y, N_a)) = c\overline{g}(\overline{\nabla}_X Y, \varphi N_a) + c\overline{g}(Y, \overline{\nabla}_X \varphi N_a) = c\overline{g}(h(X, Y), \varphi N_a) + c\overline{g}(\nabla_X Y, \varphi N_a) + c\overline{g}(Y, \varphi \overline{\nabla}_X N_a) + c\overline{g}(Y, X)$ $\overline{\eta}(N_a) = -c^2g(X, Y)f_a + (\nabla_X Y)(f_a) + cg(X, Y)\overline{\eta}(N_a)$ and Step 2 is completely proved.

Step 3. If $\xi^{\perp} = 0$ then there exists $2 \le a \le 2n - 2m$ such that f_a is non-constant.

Proof. The proof is by contradiction. Suppose that all f_a are constant. Then $0 = X(f_a) = c\bar{g}(X, \varphi N_a)$, by Step 1. Thus φN_a , $2 \le a \le 2n - 2m$, are still normal. Let W_x be the linear subspace (of the normal space E_x) spanned by $N_{a,x}$, $\varphi_x N_{a,x}$, $2 \le a \le 2n - 2m$, for $x \in M^{2m+1}$ fixed. Since M^{2m+1} is tangent to ξ , the contact 1-form vanishes on normal vectors. Thus, by (2.1), φ_x is a complex structure on W_x and consequently

$$\dim_{\mathrm{IR}} W_x > 2n - 2m - 1.$$

Therefore $W_x = E_x$ such that E_x follows to be φ_x -invariant. Consequently, M^{2m+1} is a φ -invariant submanifold (tangent to ξ) and thus M^{2m+1} is minimal, a contradiction.

Step 4.
$$(M^{2m+1}, g) \approx S^{2m+1} \left(\frac{1}{c}\right)$$
 (an isometry).

Proof. By Step 2 and Step 3, the differential equation $\nabla_X \operatorname{grad}(f) = -c^2 f X$, where $\operatorname{grad}(f) = \# (df)$, (raising of indices is understood with respect to g), $f \in C^{\infty}(M^{2m+1})$, admits some non-constant solution f_a , provided that $\xi^{\perp} = 0$. Since (M^{2m+1}, g) was assumed to be complete, we may apply Th. A of M. O b at a, [12], p. 334, such as to conclude that (M^{2m+1}, g) and the standard sphere of radius $\frac{1}{c}$ in IR^{2m+2} are isometric, Q. E. D.

Let M^{2n+1} be a Sasakian manifold and suppose that there exists an extrinsic sphere M^{2m+1} in M^{2n+1} bearing the hypothesis of our Th. 2. The proof that (1.1) holds is similar to the one in [3], p. 329. Indeed, since M^{2m+1} has a flat normal connection, one has $\tan(\bar{R}(X, Y)Z) = 0$ as a consequence of the Gauss equation (i. e. eq. (2.6) of [2], p. 45), of umbilicity and of $g(R(X, Y)Z, W) = c^2(g(X, W)g(Y, Z) - g(X, Z)g(Y, W))$, $X, Y, Z, W \in \mathfrak{X}(M^{2m+1})$, by our Th. 2. Also nor $(\bar{R}(X, Y)Z) = 0$ (by $\nabla^{\perp}H = 0$, $h = g \otimes H$ and the Codazzi equation. On the other hand, as A_N is proportional (for each normal section N) to the identity, the Weingarten operators commute. Thus nor $(\bar{R}(X, Y)N) = 0$, by the Ricci equation, i. e. eq. (2.11) in [2], p. 46. Finally, as nor $(\bar{R}(X, Y)Z) = 0$ and as the Riemann-Christoffel tensor is skew-symmetric in the last two indices, one has $\tan(\bar{R}(X, Y)N) = 0$. Q. E. D.

6. Submanifolds with parallel second fundamental form

Let M^{2n+1} be a Sasakian manifold and M^m a submanifold of M^{2n+1} . Then M^m is a contact Cauchy-Riemann (C. R.) submanifold if it carries a pair of distributions D, D^{\perp} such that i) D^{\perp} is the g-orthogonal complement of D, ii) D is φ -invariant, i.e. $\varphi_x D_x \subseteq D_x$, for any $x \in M^m$, iii) D^{\perp} is φ -anti-invariant, i.e. $\varphi_x D_x^{\perp} \subseteq E_x$, for any $x \in M^m$. See [14]. Let $PX = \tan(\varphi X)$, $X \in \mathfrak{X}(M^m)$. Suppose from now on that M^m is tangent to the contact vector of M^{2n+1} . Besides (2.2) let us recall (cf. [14], p. 10) the following formula:

$$(6.1) \overline{\nabla}_{\mathbf{x}} \, \xi = \varphi X$$

for any $X \in \mathfrak{X}(M^{2n+1})$. At this point, the Gauss and Weingarten formulae (2.4) furnish

$$(6.2) \qquad \nabla_X \, \xi = PX$$

$$h(X, \xi) = FX$$

for any $X \in \mathfrak{X}(M^m)$, as a consequence of (6.1). Analogously (2.2) leads to

(6.4)
$$(\nabla_{Y} P)Y = A_{FY} X + t h(X, Y) - g(X, Y)\xi + \eta(Y)X$$

(6.5)
$$(\nabla_{Y} F)Y = -h(X, PY) + fh(X, Y).$$

Here $tN = \tan(\varphi N)$, $fN = \operatorname{nor}(\varphi N)$, for any normal section N on M^m . Suppose from now on that M^m has a parallel second fundamental form, i. e. $\nabla h = 0$. Using (6.3) and (6.2) we may perform the following computation:

$$0 = (\nabla_X h)(Y, \xi) = \nabla_X^{\perp} h(Y, \xi) - h(\nabla_X Y, \xi) - h(Y, \nabla_X \xi)$$

= $\nabla_X^{\perp} FY - F\nabla_X Y - h(Y, PX) = (\nabla_X F)Y - h(Y, PX).$

At this point we may substitute from (6.5) such as to yield

(6.6)
$$h(X, PY) + h(Y, PX) = fh(X, Y).$$

By (2.1), $\phi \xi = 0$. Thus $P\xi = 0$, $F\xi = 0$. Let us set $Y = \xi$ in (6.6). Then, using again the identity (6.3), we obtain

$$(6.7) FP = fF.$$

On the other hand, applying once more φ to the identity $\varphi X = PX + FX$ and using (2.1) and the uniqueness of the direct sum decomposition we obtain

$$(6.8) P^2 + tF = -I + \eta \otimes \xi$$

$$(6.9) FP + fF = 0.$$

See also [14], p. 44. Finally (6.7), (6.9) lead to

(6.10)
$$FP = 0$$
.

This ends the proof of our Th. 3; indeed, by a result of K. Yano&M. Kon, (see

Th. 2.1. of [14], p. 55) a submanifold M^m tangent to the structure vector ξ of a Sasakian manifold M^{2n+1} is a contact C. R. submanifold if and only if (6.10) holds.

To prove the corollary, let M^m be a contact C.R. submanifold of the Sasakian space form $M^{2n+1}(c)$. By (2.3) the Codazzi equation of M^m in M^{2n+1} reads

$$(6.11) (\nabla_X h) (Y, Z) - (\nabla_Y h) (Y, Z) = \frac{c-1}{4} (g(PY, Z) FX - g(PX, Z) FY + 2g(X, PY) FZ).$$

As h is assumed to be parallel, (6.11) turns into

(6.12)
$$g(PY, Z)FX - g(PX, Z)FY + 2g(X, PY)FZ = 0$$

for any X, Y, $Z \in \mathfrak{X}(M^m)$. Let D be the φ -invariant distribution of M^m , as a contact C. R. submanifold. Clearly the normal bundle valued l-form F on M^m vanishes on D. Let us use (6.12) for X, $Y \in D$, and Z arbitrary. We obtain

$$(6.13) g(X, PY)FZ = 0.$$

Cf. [14], p. 53, $j = -P^2 + \eta \otimes \xi$ and $j^{\perp} = I - j$ are the projectors of the (complementary) distributions D and D^{\perp} of M^m . Note that $j\xi = \xi$, i. e. $\xi \in D$ and thus $D \neq (0)$. We distinguish two possibilities: either $D^{\perp} = (0)$ and then M^m is φ -invariant (and in this case we may apply prop. 1.4. of [14], p. 49, such as to conclude that M^m is totally-geodesic), or $D^{\perp} \neq (0)$. If this situation occurs, we shall end the proof of the Corollary by establishing the following

Lemma. The invariant distribution is spanned by the contact vector.

Indeed, it would follow that M^m is φ -anti-invariant (and by (6.3) the submanifold cannot be totally-geodesic).

To prove the lemma, let $x \in M^m$ and consider $u \in D_x$, $u \neq 0$. Consequently $F_x u \neq 0$. Therefore our (6.13) furnishes

$$\langle v, P_x w \rangle = 0$$

for any v, $w \in D_x$. The rest of the proof is by contradiction. Suppose that $\dim_{\mathbb{R}} D_x \ge 2$; we may consider then $v \in D_x$ such that $v \ne 0$ and $\langle v, \xi_x \rangle = 0$. Let $w = P_x v$. Clearly $w \ne 0$, and $w \in D_x$ (as P is D-valued). Finally we may use (6.14) and (6.8) to perform the following computation:

$$0 = \langle v, P_x^2 v \rangle = -\|v\|^2 + \eta(v)^2 = -\|v\|^2$$

a contradiction.

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